TRANSPORT AND THERMOMAGNETIC PROPERTIES OF METALLIC GLASSES

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DEPARTMENT OF PHYSICS

PLAN INSTITUTE OF TECHNOLOGY, KANPUR

MAY, 1984

TRANSPORT AND THERMOMAGNETIC PROPERTIES OF METALLIC GLASSES

A Thesis Submitted in Partial Fulfilment of the Requirements for the Degree of

DOCTOR OF PHILOSOPHY

BY
RATNAMALA ROY

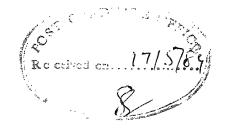
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CERTIFICATE

This is to certify that the work reported in this thesis entitled 'Transport and Thermomagnetic Properties of Metallic Glasses' has been carried out by Ratnamala Roy under our supervision. No part of this work has been submitted elsewhere for a degree.

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SYNOPSIS

TRANSPORT AND THERMOMAGNETIC PROPERTIES OF METALLIC GLASSES

A thesis submitted
In Partial Fulfilment of the Requirements
for the degree of
DOCTOR OF PHILOSOPHY

Ratnamala Roy
Department of Physics
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Since the historical prediction of ferromagnetism in glassy metals was made by Gubanov, the interest in the study of metallic glasses has increased rapidly. The survey of the literature of metallic glasses suggests that the properties of these glasses may vary considerably from one set of samples to the other. The scatter and the disagreement in the results are believed to arise mainly from the uncertainty of the preparation conditions as well as compositions. Hence, any correlation or comparison would be meaningful only if different measurements are made on the same set of samples. For this purpose we have chosen a very simple and fundamental binary glass series, namely, $Fe_{100-x}B_x$ (13 $\le x \le 26$) made by Allied Chemical Corporation, USA. The characterization of such a system is important towards the understanding of more complicated systems. Very few systematic studies of the galvanomagnetic properties on such a simple binary alloy series, with

metalloid variation, are available in the literature. In the present work we have studied electrical resistivity, magneto-resistance and Hall effect of Fe-B series over the available range of composition. Wherever possible, we have compared our results with those of liquid phase or crystalline state.

Chapter I of this thesis starts with an exact definition and a short discussion on the historical development of metallic glasses. Methods of preparation and structure of these glasses are also discussed. A brief review is given for the electrical and magnetic properties studied so far in these glasses. This chapter also establishes the subject and motivation of the present investigation.

There is no general theory available particularly for the disordered or amorphous state. In the absence of anything better, generally the results of the measurements are made to fit into different theories available for crystalline or liquid phase. Chapter II introduces those relevant theories which are needed to discuss the results of our measurements.

Chapter III deals with the experimental procedures. The fabrication and design of a cryostat and the electrical circuit used for all these measurements are described. Particular methodologies used for different measurements are also explained.

In Chapter IV the results of our measurements of :

- (i) Variation of electrical resistivity ρ with temperature T in two different series, (a) $\text{Fe}_{100-x}\text{B}_x$ (13 $\leq x \leq 26$), in the temperature range 77K $\leq T \leq 300\text{K}$ and (b) $\text{Fe}_{80}\text{B}_{20-x}\text{Si}_x$ (0 $\leq x \leq 12$), in the temperature range 4.2K $\leq T \leq 300\text{K}$,
- (ii) Variation of ρ with concentration x in $Fe_{100-x}B_x$ series at 300K,
- (iii) Variation of ferromagnetic anisotropy of resistivity (FAR) with x in $Fe_{100-x}B_x$ series at 77K and 300K, and,
 - (iv) Concentration (x) dependence of spontaneous Hall constant R_s in Fe $_{100-x}B_x$ series at 77K and 300K, are presented.

The results of all these measurements are discussed in Chapter V and can be summarized as follows,

⁽i) The temperature coefficient of resistivity, α , was found to be positive for the entire range of compositions in both the series, $Fe_{100-x}B_x$ and $Fe_{80}B_{20-x}Si_x$

- (iii) These quantities are also calculated for the first time in this Fe-B series, using the extended Ziman theory and they are in reasonable agreement with our data
- (iv) An attempt is made to correlate them in terms of structure factor and stability of this amorphous series
- (v) An estimation of the Debye temperature Θ_D for the $Fe_{100-X}B_X$ series is made. Its variation with x shows a minimum around x = 20 and this behaviour is explained in terms of the Invar anomaly.
- (vi) The values of Θ_D in Fe-B-Si series are much smaller compared to those of Fe-B. In this series the variation of Θ_D with x might indicate some structural changes, which could not be verified because of the non-availability of the structural data in this series
- (vii) It is shown from both theory and experiment that the absolute values of resistivity ρ increase with boron concentration x
- (viii) The limitation of the applicability of the extended Ziman theory to these glasses is also pointed out
 - (ix) Like many other properties of the Fe-B series, FAR versus x plot shows a smeared out peak at 300K and a sharper one at the lower temperature of 77K around x = 16. A physical explanation is provided for this observation.
 - (x) We have tried to find out ρ and FAR at 300K for amorphous Fe from our resistivity and magnetoresistance data.

- (xi) Forced magnetoresistivity ($\frac{1}{\rho} \frac{\partial \rho}{\partial H}$ at high fields), unexpectedly becomes less negative at lower boron concentration. This is again attributed to the Invar anomaly
- (xii) The angle Θ between the spontaneous magnetization and the ribbon axis is calculated for the whole series and is found to lie between $30^{\circ}-40^{\circ}$.
- (xiii) The R_s versus x curves also show a prominent peak around x=18 at 300 and 77K. This peak is also attributed to the Invar anomaly. From R_s vs x and ρ vs x plots it is concluded that R_s does not vary as ρ^2
 - (xiv) The correlation between Hall effect and magnetoresistance which was proposed earlier is shown to fail in these metallic glasses.

Chapter VI of the thesis deals with systematic thermomagnetic and galvanomagnetic studies of two metallic glasses, namely, 2605SC (Fe₈₁B_{13.5}Si_{3.5}C₂) and 2605 (Fe₈₀B₂₀). The final crystalline phases of these two amorphous alloys were found out by various methods like, M(T), Mossbauer, Differential thermal analysis and X-ray. It is concluded that 2605SC is more stable than 2605 as an amorphous ferromagnet. The thermomagnetic properties are seriously affected by the replacement of B by Si and C while the galvanomagnetic properties have changed only quantitatively.

At the end, it is to be emphasised again that because of the nonavailability of any general theory, most of the results are interpreted in terms of physical arguments and are correlated with other relevant properties. From an experimentalist's point of view, we believe that a systematic set of data of various electrical and magnetic properties taken on the same set of samples would be of considerable use in developing theories of galvanomagnetic properties in amorphous systems.

CHAPTER 1

INTRODUCTION

During the last twenty five years or so, the interest in metallic glasses has increased steadily. If the progress made during this time could be measured in some units, it is probable that the curve would be close to an exponential !. . The research in this field helps our understanding of noncrystalline material in general. The interpretation of the properties of metallic glasses promises a particular challenge because, there is no general theory available (as to understand crystallinity, a fascinating theory of translational invariance has been developed) for the disordered or amorphous state. Before dealing with the subject, we should be particularly clear about a few terms like, 'glass', 'amorphous', 'disorder' etc. In fact'disorder'is at the heart of 'amrophous' ferromagnets, but what we should understand is that 'amorphous' and 'disordered' do not mean the same thing. 'Amorphous' refers to the lack of crystallinity, which indirectly implies that amrophous materials are 'disordered'. But this is not viceversa true, i.e., all 'disordered' materials are not 'amorphous'. There exist disordered crystalline materials too, where different atoms irregularly occupy sites of a regular crystal lattice. 'Metallic glasses' are 'amorphous' whereas most

practical magnetic alloys like Permalloy are 'disordered', but not 'amorphous'. The distinction between amorphous materials and disordered crystalline alloys leads us to consider two different aspects of 'disorder'

- (i) structural disorder which refers to the lack of crystallinity, and
- (ii) chemical disorder which refers to the local environments;
 'Disordered crystalline alloys' have only chemical disorder,
 but 'amorphous materials' have both structural and chemical
 disorder.

After recognizing the difference between 'disordered' and 'amorphous materials', let us try to differentiate between the two terms 'amorphous' and 'glassy' metals. Amorphous metals can be prepared by a variety of methods: (i) Evaporation of metals in vacuum and their condensation on a cooled substrate. (ii) Sputtering by which the atoms are removed from the source under bombardment with energetic inert gas atoms. (iii) Chemical deposition, a method in which ions in aqueous solution are deposited onto substrates by chemical reactions. (iv) Electrodeposition, where the chemical reaction requires the presence of an external potential. (v) Rapid quenching from the liquid state. By definition, a glass is a solid which does not crystallize during cooling from the liquid state. Only the amorphous alloys prepared by the last method,

i.e., by liquid quenching, satisfy the definition and hence from now onwards we would use the term 'metallic glasses' or 'glassy metals' for these alloys only.

A BRIEF HISTORICAL SURVEY

Earlier, it was believed that because of the lack of atomic ordering ferromagnetism could not exist in amorphous solids. However, in 1960 Gubanov² predicted on the basis of theoretical analysis, that ferromagnetism could occur in amorphous solids, based on the argument that the electronic band structure of crystalline solids did not change in any fundamental way on transition to the liquid state. This implies that the band structure depends more on short-range, rather than longorder. Hence, ferromagnetism, which depends on shortorder, should not be destroyed in the corresponding amorphous solid. After this important prediction was made, interest in amorphous solids took a rather interesting turn. Since then a large number of different alloys have been produced as metallic glasses and the scientific and technological interest in these materials has been growing rapidly. The history of metallic glasses starts from the report of Cal. Tech. group led by P. Duwez on the preparation and properties of amorphous meta-The X-ray diffraction pattern of Au-Si alloy llic alloys. prepared by them indicated the absence of crystallinity. However, as stated by Duwezlhimself, at that time they were not

unquestionably convinced about the amorphosity of the alloys. Cohen and Turnbull⁴ pointed out that the favourable condition for glass formation is that, in a metal-metalloid alloy, the eutectic point of the alloy should be at a rather low temperature compared to the melting point of the constituent metals. The next report was on Pd-Si metallic glasses with Si concentration around 20 at. published by Duwez et al5. Shortly after this paper, there appeared two very important papers by Chen and Turnbull6,7 on the specific heat measurements of Au-Ge-Si and Pd-Si liquid quenched alloys. Their measurements established for the first time the presence of glass transition temperature in these alloys, which in turn proved that the liquid-quenched alloys were indeed glassy and the name metallic glasses' was completely justified for these alloys. The first strongly ferromagnetic metallic glass Fe75 P15 C10 was also prepared by Duwez et al⁸ in late 1960s. A compact view of the discovery and development of metallic glasses in historical perspective is given in Table 1.19.

PREPARATION

Let us discuss the methods of preparation of metallic glass in brief. The basic principle of obtaining these materials is that the liquid must be quenched very rapidly as a droplet or jet thrown on a cooled substrate of highly conductive metal (generally copper). The cooling rate, which is a crucial point in the preparation of metallic glass, should be high enough to

Table 1.1 Headlines in the discovery and development of metallic glasses

1960	Gubanov: Ferromagnetism does not require crystallinity
1960	Klement, Willens, Duwez: The first metallic glass ${^{\mathrm{Au}}}_{80}{^{\mathrm{Si}}}_{20}$
1961	Cohen and Turnbull: Composition requirements for metallic glass formation
1965	Duwez, Willens and Crewdson: Pd-Si metallic glasses
1967	Duwez and Lin : Fe rich liquid-quenched alloys, $H_c=3.0e$
1968 -7 1	USSR, USA, UK : Full perception - 'Amorphous' → no magnetic anisotropy ==> low H _c
1969 -7 0	Pond and Maddin, Chen and Miller: Production techniques, liquid quenched ribbons
1974	Allied Chemical Corpn: METGLAS , narrow ribbons commercially available
1975	$H_c \rightarrow 0.01$ Oe or lower (T_{80} M_{20})
Today	Intense activity: Development of wider ribbons, tailored properties, Possibility of replacing high permeability Ni-Fe alloys and for power applications of Si-Fe steels

bypass the crystallization. Generally, to get samples of \sim 20-40 μm thickness, by this melt spinning process, a cooling rate of about $(10^6-10^7) K/sec$ is needed 10 . At the eutectic composition, minimum cooling rate is required. There are two common techniques for liquid quenching.

(a) Splat Cooling:

In this method a droplet is squeezed between a rapidly moving piston and a fixed anvil (see Fig. 1.1). The obtained splat is between 15 and 30 mm in diameter and 20-80 μ m thick. These splat cooling devices give slower cooling rates than the melt spinning devices described next.

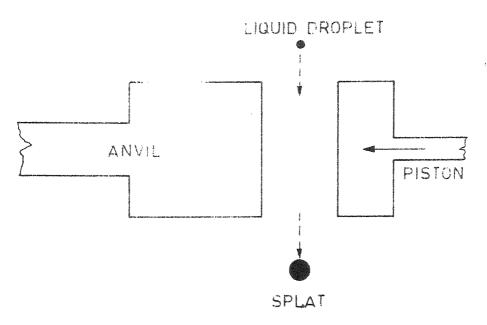
(b) Melt Spinning:

In this method a rapidly spinning cold copper or steel wheel is used to conduct the heat away from the molten jet of liquid and thus quenching it at a high cooling rate (see Fig. 1.2). The ribbons produced by this method have typical dimensions of 1-3 mm width and 20-60 μ m thickness.

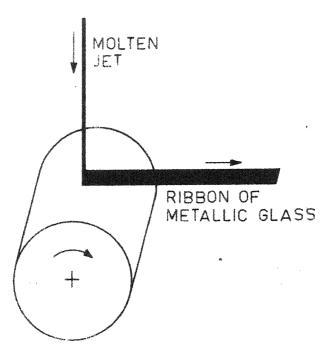
Some new techniques of obtaining metallic glasses are still developing. These are laser glazing 11 , electric field emission of ions from the melt 12 and electric arc furnace quenching 13 .

COMPOSITION OF METALLIC GLASSES

At present, all the metallic glasses reported in the literature can be classified in a few different families 14,15. They are tabulated with representative systems and particular composition range in Table 1.2.



SPLAT-COOLING TECHNIQUE FIG. 1.1



MELT-SPINNING TECHNIQUE FIG. 1.2

Table 1.2 Classification of glass forming alloy systems

Category		Representative Systems	Typical composition range, at. %	
i)	T or N-M	Fe-B, Pd-Si, Au-Si	15-25 M	
ii)	AM-BM	Mg-Zn, Ca-Mg, Mg-Ga	Variable	
iii)	T_E-T_L (or Cu)	Zr-Fe,Zr-Ni,Zr-Cu,Nb-Ni, Ti-Ni, Y-Cu, Ta-Ir	$30-65$ Cu or T_L , or smaller range	
iv)	T_E -AM	(Ti,Zr) Be	20 - 60 Be	
v)	U-T	U-Fe, U-Cr, U-V	20 - 40 T	
vi)	RE-M	La ₇₀ Al ₃₀		
vii)	RE-N	La ₈₀ Au ₂₀		
iii)	$RE-T_L$	Gd ₇₀ Co ₃₀ ,Gd ₇₀ Ni ₃₀		

Here T is transition metal, M is polyvalent metal, AM is Li, Mg group metals, BM is Cu,Zn,Al group metals, T_E is early transition metals, T_L is late transition metals, N is Noble metals. RE is rare earth metals and U denotes uranium. In each category of glasses there is a particular range of composition over which the glasses are formed. This range might be quite narrow, as in Pd-Si (~ 5 at.%) or wide as in Cu-Zr (~ 35 at.%). As stated earlier, in a few cases where the phase diagram is known, there is a low-melting eutectic at or near

the easy glass formation range. The existence of eutectic means that the liquid state is stable to relatively low temperatures, and suggests that the amorphous state and the crystalline state are not much different in energy. reason for the presence of glass forming tendency, only over a particular range is not clear 10,16, and this has been an interesting open question in this field. Different groups of scientists have suggested different reasons to explain 'why only over a particular range of composition stable glasses are formed. One suggestion 17, based on geometrical argument. is that these glasses exist essentially in a Bernal structure of densely-packed hard sphere metal atoms (a) and the smaller and softer metalloid atoms (b) (20 at.% in T-M type) can just get in and occupy the open spaces in the otherwise densely packed array and thus stabilize the random configuration. But the short coming of this model is that in some cases the . class forming composition predicted by the model falls well outside the observed range, and in many cases the softer 'b' atoms are even larger than the 'a' atoms - e.g. Pt-Sb and $(Au,Ag)_{25}$ Pb $_{75}^{18}$. The second model suggested by Chen is that the destabilization of the crystalline mixture, rather than the stabilization of the glassy phase near the eutectic composition, determines the stability and the ease of glass formation. Chemical affinity due either to electron transfer or to ionization among constituent atoms, stabilizes the stochiometric

a₃b, a₂b or ab crystalline phases and leads naturally to eutectic compositions near 20,25 or 35 at.% of 'b' atom. Duwez has proposed what he calls a 'confusion principle' to the effect that complex mixtures of constituents have greater glass forming tendency than binary mixtures and whatever the underlying rationale of this empirical observation may be, designers of commercial glasses have evidently accepted this principle as valid. Another important model suggested by Nagel and Tauc²⁰ is an electronic band-structure argument based on the reduction in the d-electron band energy by amorphous short-range order. This model will be discussed in some detail in Chapter II of this thesis. Also, the validity of this criterion for our amorphous alloys is discussed in Chapter V.

STRUCTURES

In 1975 Cargill²¹ concluded that no microcrystalline model was able to match the experimental radial distribution functions (RDF) of the majority of glasses and there remains no doubt that the kinds of samples we are discussing are truly amorphous. Conventional X-ray diffraction techniques, which give information about the metal atoms almost exclusively, are in fairly good agreement with results predicted for an assembly of dense-random packed spheres (DRPS). Many models were suggested based on DRPS. Finney, in 1970²² developed the mechanical model of dense random packing of hard spheres

(DRPHS) suggested by Bernal. Computer modelling was first used by Bennett²³. Starting from seed cluster, atoms are added one at a time, each atom is brought into hard sphere contact with one of the atoms already in the cluster. Both these models could not reproduce the second peak in the RDF. The most successful structural model of amorphous metals is the relaxed DRPS model of Cargill and Kirkpatrick 24. The algorithm used to generate this model is similar to the one of Bennett except that the atom being added to the cluster is allowed to move to the nearest position where it can make contact with three atoms in contact with each other to form a nearly perfect tetrahedron. This model is extremely successful in that it exhibits the second peak in the RDF. In the study of metallic glasses many new techniques other than X-ray diffraction are introduced. These are pulsed neutron scattering methods, small angle neutron scattering, Mössbauer offect, EXAFS (extended X-ray absorption fine structure) and EDXD (energy dispersive X-ray diffraction). Pulsed neutron scattering methods can provide a high resolution RDF in the high wave vector region, which show structural details of short-range order (SRO) not detected in previous diffraction studies. EXAFS has the unique capability of probing the near neighbour environment in multicomponent systems where EXAFS from each element can be studied. Study of Mössbauer effect provides another tool to probe the local environment. The main

application of EDXD technique lies in real time study of the kinetics of structural relaxation by annealing and in the study of compositional SRO of metallic glasses. Based on these models, the present understanding of the structure of amorphous metals is: the major features are nearly 12-fold coordinated dense random packing (DRP) structure (like fcc or hcp close-packed crystals) but beyond first nearest neighbours correlations are very weak. The metalloid atoms have a lower coordination number than the metals. In DRP structures there are a number of types of interstitial spaces that are not possible in close-packed crystals. These spaces, known as Bernal holes may play a role in amorphous structures in accommodating the metalloid atoms in T-M alloys. Surroundings of metalloid atoms are probably similar to those in crystalline compounds of the same composition.

A BRIEF REVIEW OF THE ELECTRICAL AND MAGNETIC PROPERTIES OF

Until recently the major efforts in solid state physics have been confined to the understanding of crystalline materials. Amorphous solids new represent a new state of matter. Some of their properties are entirely as predicted and some of them show anomalous behaviour. The most significant experimental results reported in the recent literature are the large absolute values of electrical resistivity, very small temperature coefficient of resistivity, very small values

of ferromagnetic anisotropy of resistivity and a nearly temperature independent anomalous Hall coefficient. Interest in metallic glasses was accelerated due to the ferromagnetism in them, hence the study of magnetic properties in these materials bears a special significance. The amorphous state influences mainly the electronic transport properties. Hence, the electrical resistivity, Hall resistivity, magnetoresis—tance are other important properties to be studied to understand the non-crystallinestructure. The subject of magnetic behaviour of metallic glasses is so extensive that it is very difficult to touch upon all the topics. We would discuss here only a few important ones.

(i) Saturation Magnetization:

This is a widely studied property of ferromagnetic amorphous alloys. The considerable scatter and disagreement in the results (e.g., the variation of saturation magnetic moment with boron concentration in $Fe_{100-x}B_x$ alloys studied by Hiroyoshi et al²⁵ show a broad maximum around x = 14, whereas the same study in the similar series, done by Hasagawa and Ray²⁶ show a continuous decrease with increasing x) can be attributed to various causes - (a) the inherent difficulty to measure magnetization on small samples, (b) the other major experimental uncertainty is because of the uncertain composition of the samples and (c) a further difficulty for some

alloys like Ni-Co series and the compositions near pure Ni, have fairly high susceptibilities at high fields, making the definition of saturation magnetization uncertain. However, one point is certain that magnetic moments of the amorphous glasses are smaller than those of pure crystalline forms of the transition metals which they contain. The direct influence of the structural disorder on the moments is very small. is shown by Kazama et al 27 that the moments are lower because of the change in local environment provided by the presence of metalloids. To explain the magnetic moment in amorphous alloys we then assume that metalloid with more sp electrons will contribute more electrons to the d-band of transition metals and thus shifting the peak of Slater-Pauling curve towards a lower transition metal electron concentration 28. Hence, the magnetization would decrease with increasing metalloid concentration (this is true for both amorphous and crystalline alloys). According to Luborsky 29, the magnetic moment of the transition metal, T atoms in amorphous alloy $T_{1-z-y}F_zG_y$ can be expressed as,

$$\mu = [m(1-z-y) - fz - gy]/(1-z-y)$$
 (1.1)

or for moment per atom of alloy as,

$$\mu = m(1-z-y) - fz - gy$$
 (1.2)

where F and G represent the metalloid or glass forming atomic

species, m is the original number of unpaired spins in the transition metal alloy, and f and g are number of electrons transferred from F and G atoms respectively. Since the number of nearest neighbours in an amorphous alloy is essentially the same as in the fcc crystalline phase, one can assume m to be the same. Thus m = 0.6, 1.6 and 2.6 for Ni, Co, Fe respectively. Using these values in eqn. (1.1) or (1.2) the theoretically calculated μ tallies well with the experimentally observed values.

Alben et al³⁰ have discussed the saturation magnetization in the light of chemical bonding. The first extensive measurements of saturation moment for a wide range of alloys, were given by Mizoguchi et al³¹. Durand and Yung³² too have performed a detailed investigation of the moment and Curie temperature of amorphous alloys, Fe-P-B over the entire range of amorphosity.

The study of the variation of magnetization with temperature M(T), in amorphous alloy systems is also quite important. This leads one to the understanding of amorphous to crystalline transition and helps to study the equilibrium phases present in any particular amorphous alloy by identifying $T_{\rm C}$ of different crystalline phases present in it. From magnetization measurements directly, or from Mössbauer measurements, assuming that the hyperfine field $H_{\rm eff}$ is proportional to M, the change in magnetization with temperature is given by (as in crystals),

$$(M_o - M_T)/M_o = \Delta M/M_o = BT^{3/2} + CT^{5/2} + ...$$
 (1.3)

where M_0 , M_T are magnetization at O and T and B and C are constants characteristic of the low temperature, long wavelength spin waves. From neutron scattering, assuming a dispersion relation of the form $E(k) = Dk^2$, the spin-wave dispersion coefficient D may be determined. The values of D and B are related by

$$B = \zeta (3/2) (g\mu/M) (K/4\pi D)^{3/2}$$
 (1.4)

where g is the g-factor (~ 2.1), μ is the Bohr magneton in emu (9.27x10⁻²¹ emu), M is the magnetization in emu/Å³, K is the Boltzmann constant (8.61x10⁻⁵ ev/K) with D in eV Å², to obtain B in K^{-3/2}. ζ is the zeta function = 2.612. Like crystalline ferromagnets, in these amorphous alloys too T^{3/2} term is dominant. Recent experiments²⁷ show that the increase in B is largely due to chemical effects rather than to structural disorder.

(ii) Curic temperature:

Inspite of their chemical and structural disorder amorphous ferromagnets have well defined magnetic ordering or Curie temperature T_c . For most glasses of practical interest T_c lies in the range 600-700K 15 . Most of the glasses show a sharp transition near T_c^{33-35} but some alloys with two or more transition metals show a spread out Curie transition 36 . Chemical

inhomogenety appears to be the reason behind such spreading of Curie transition. The Tr's of amorphous transition metal= metalloid alloys are found to be significantly lower than those of the pure crystalline samples. Chemical composition and chemical disorder is thought to be the reason for this reduction in T_c^{37} . The degree of dependence of T_c on metalloid content varies greatly between the alloys based on Co and on T_c apparently decreases nearly linearly with increasing metalloid content in former, whereas the latter have a much weaker dependence of T_c on metalloid content 37,38 . In some of the Fe based alloys (e.g. in $Fe_X(PB)_v$ alloys) T_c increases as x decreases, i.e., alloys of higher Fe content have lower T_c, but this is not true for all the alloys with Fe as the only transition metal. In fact, T is generally sensitive to Fe-Fe interatomic spacing, which in turn depends on both the metalloid species and their concentration. Hence, clearly the increase or decrease of T_c with metalloid content depends upon the particular metalloid the alloy contains and also on the percentage weight of metalloid present in the alloy. Chen et al 39 have shown that in binary (Fe) amorphous alloys T_c decreases in the order Fe-Si, Fe-B, Fe-C, Fe-P, where the values for $\text{Fe}_{80}\text{Si}_{20}$ and $\text{Fe}_{80}\text{C}_{20}$ are found by the extrapolation of their data on $Fe_{80}(BSi)_{20}$, $Fe_{80}(PSi)_{20}$ and $Fe_{80}(BC)_{20}$, $Fe_{80}(PC)_{20}$ respectively.

Many workers 31,40 have shown that the substitution of other transition metals, like, Cr, Mn, V, Mo etc. for Fe sharply brings down the Curie temperature.

However, generally in amorphous systems Curie temperature T_c is a smooth function of alloy composition over the eutectic range. As pointed out by Luborsky²⁹, though the theoretical treatment of spin ordering, and hence Curie temperature, in amorphous solids is a very difficult problem, in the molecular field approximation T_c could be given by,

$$T_{c} = [2S(S+1)/3K] \sum_{ij} J_{ij}$$
 (1.5)

where S is the spin number, K is Boltzmann's constant and J_{ij} is the exchange interaction between atoms at the position r_i and r_j and can be expressed in terms of radial distribution function.

(iii) Magnetic Anisotropy :

The absence of crystallinity in metallic glasses should give a corresponding absence of magnetocrystalline anisotropy. But, in actual practical cases, this is not found to be true. In fact, while quenching the metals, inhomogeneous stresses result from differential thermal contraction. This stress then interacts with the magnetostriction to cause local magnetic anisotropy K_{λ} . This type of anisotropy is called strain-magnetostriction anisotropy. An important case where this

particular anisotropy is present is in $T_{80}(P,B,Al...)_{20}$ type of metallic glasses. The non-uniform strain developed during the preparation of the ribbon results in a periodic fluctuation in the perpendicular component of anisotropy along the length of the ribbon. Thermal annealing removes the internal stresses and then the anisotropy disappears. Luborsky 29 has discussed many other types of anisotropies which can be present in the metallic glasses. These are structural and compositional enisotropy, directional order anisotropy or induced anisotropy and exchange anisotropy. On an atomic scale, magnetic anisotropy exists even in an ideally homogeneous amorphous alloy. Each magnetic ion experiences an anisotropic electric field or exchange field due to its neighbouring ion. These local anisotropies vary from place to place within the amorphous structures. Rhyne et al41 have shown that in metallic glasses containing mare-earth elements such local anisotropy is often very strong whereas in transition metal containing metallic glasses exchange interaction overrides local anisotropy and thus within a domain all the spins are essentially parallel. Borry and Pritchet 42 first observed that by annealing amorphous alloys in magnetic field one can get a non-random distribution of local environments and this in turn gives rise to the induced anisotropy (or magnethe annealing anisotropy) in these alloys. The anisotropy in emorphous alloys is largest when two transition metals are prosent in equal concentration. For metallic glasses all these anisotropies are uniaxial.

(iv) Magnetostriction:

When an amorphous alloy is subjected to an elastic stress, the neighbouring ion positions are slightly changed and results in a microscopic anisotropy. This in turn results in a macroscopic anisotropy with uniaxial symmetry. Also, within each uniformly magnetized domain, there will be a spontaneous strain to minimise the elastic strain energy and anisotropy energy. This spontaneous strain resulting from the strain dependence of the anisotropy energy is called Magnetostriction. the amorphous alloy is macroscopically isotropic, the magnetostriction is explained by a single constant, the saturation magnetostriction, λ_s . The magnetostrictive strain can then be expressed as $\lambda = \lambda_s \cos^2 \emptyset$, where \emptyset is the angle between the direction of measured strain and the direction of magnetization. Magnetostriction of glasses is an interesting property because it was assumed that a glass with $\lambda = 0$ would have virtually in-Finite permeability. Ohnuma and Masumoto 43 have examined in detail how the permeability of a range of glasses is affected by λ and heat-treatment. Values of λ_s reported by Brooks⁴⁴ for the series $(Fe_{1-x}Co_x)_{75}P_{16}B_6Al_3$, and Sherwood et al⁴⁵ for $(Fe-Ni-Co)_{75}P_{16}B_6Al_3$ showed that a zero magnetostrictive composition occurred at (Fe_{O.O4}Co_{O.96})₇₅P₁₆B₆Al₃. Another Cobased metallic glass Vitrovac E6010, Co58Ni 10Fe5 Si11B16 has $\lambda \leq 5 \text{x10}^{-7^{15}}$. Tsuya et al 46 studied λ of Fe $_{80}$ P $_{13}$ C $_7$ from -76°C to room temperature and got a: universal result that the

material did not appear to be isotropic. Narita et al 47 have shown that in Fe-B and Co-B glasses a nearly quadratic relation exists between magnetostriction and saturation magnetization. O'Handley⁴⁸ has reported a systematic study of λ_s on (Fe Ni) $_{80}$ B $_{20}$ and (Fe-Co) $_{80}$ B $_{20}$ series. In this report he has also discussed the possible origin of magnetostriction in amorphous alloys. A few measurements of the temperature dependence of λ_s have been reported with conflicting results 46,49,50,51. Jagielinski et al 51 measured the temperature dependence of λ_{ς} for a large number of alloys between 77 and 300K and found λ_c increasing in some cases and decreasing in others. There can also be a volume magnetostriction, ω , that appears as an anomaly in volume thermal expansion at Curie temperature and as a field dependent volume change at any temperature where the saturation magnetization is field dependent. Jagielinski et al⁵¹ have reported the volume magnetostriction for several alloys.

(v) Low Temperature Specific Heat:

Since the electronic, lattice and ferro-magnetic contributions to the specific heat defined as $C_p = \gamma T + \alpha T^3 + \sigma T^{3/2}$, can be well separated, specific heat measurement is an important tool for investigating the interdependence between the electronic and magnetic properties. Krause et al have measured the low temperature specific heat in Fe-B-P, Fe-B-Si and Fe-Ni-B alloys and discussed the effect of B and P

on the lattice and magnetic specific heat. Golding et al have measured C_p for $\mathrm{Pd}_{30}\mathrm{Si}_{20}$ metallic glass. Recently Matsuura et al have measured the low temperature specific heat of $\mathrm{Fe}_{100-x}\mathrm{B}_x$ glasses. They found that both electronic specific heat coefficient γ and the Debye temperature Θ_D decrease rapidly with increasing B content. For amorphous materials Θ_D is generally $\sim 10\text{--}20\%$ lower than Θ_D in crystaline transition metals whereas γ value is twice as large as that for pure bcc Fe. The value of Θ_D in this Fe-B series is very high even compared to the other metal-metalloid amorphous alloys. Also, the spin-wave stiffness constant D of these alloys were found to be small. All these findings led them to the conclusion that the Fe-B amorphous alloys showed the characteristic features of Invar alloys.

Specific heat measurement is also an important tool to find out the glass transition temperature T_g of these glassy metals. The sudden increase in the specific heat of glass upon heating, is the thermal manifestation of the glass transition and the point of inflection of rising C_p is defined as T_g . Chen and Turnbull observed this behaviour in AuGeSi alloys.

(vi) Electrical Resistivity:

Non-crystallinity of the materials directly affects the electronic transport properties. Hence, the study of

electrical resistivity in metallic glasses is very important. The variation of resistivity ρ with temperature T can be divided into three main categories:

- (i) Low temperature region, < 20K a logarithmic term of disputed origin is observed . .
- (ii) Intermediate temperature region, $20K \le T \le 100K$, where, generally a T^2 dependence is reported
- (iii) High temperature range, above 150K, a linear dependence is found.

The model which is generally used to interpret the intermediate and high temperature range is the extended Ziman's theory of resistivity. Since we are interested in the ρ values between 20K \leq T \leq 300K, Ziman's theory is discussed in detail in Chapter II of this thesis. But recently the applicability of this theory to metallic glasses is criticised by many workers. Theoreticians 56,57,58 have questioned the validity of this theory for systems with strong scattering potentials. In fact, the Boltzmann equation is the basis of this theory and is frequently questioned for strong scattering systems such as amorphous transition metal based alloys 59 . But one has to use this theory for metallic glasses (assuming these glasses to be similar to liquid metals) in the absence of anything better. The Ziman's theory could however, yield good agreement with experimental results 60,61 when the Fermi energy E_F , effective valence z

and a suitable muffin-tin potential for a liquid are reasonably adjusted. As argued by Yonczawa 56 for liquid metals (we can use the same argument for metallic glasses too), inspite of its quantitative successes, the extended Ziman formula is neither based upon theoretical first principles since little is known of the physical circumstances under which it might be valid, nor of the corrections that should be applied when these conditions are not well satisfied. It has been noted 58 that the theoretical calculation of ρ on the basis of this theory is very sensitive to the three parameters E_{r} , Z and the choice of a suitable muffin-tin potential as described above. This fact reflects the vulnerability of the extended Ziman theory. The multiple scattering effect which is important for strong scattering systems, is absent in the original Ziman's formula. Attempts have been made to remove this difficulty by including some of the multiple scattering terms and thus modifying the extended Ziman theory 62, but the extended Ziman's formula still remains parameter sensitive. ${\tt More}$ sophisticated approaches based on the Kubo formula 63 have been successfully applied to the transport in completely random liquids and crystalline alloys. Beginning with Kubo formula, Chen, Weisz and Sher (CWS)⁶⁴ made a number of simplifying assumptions, computed the Green's functions and then the conductivity. The important results of this approach is that it explains the negative temperature coefficient of resistivity α somewhat successfully.

CWS showed that as the strength of the effective scattering potential in a completely random alloy increases, an energy gap in the electron density of states begins to form and that, if the Fermi energy falls near this gap, one can get negative temperature coefficients of resistivity, α . Other workers 65,66,67 have also applied this CWS approach to their own models and have successfully explained the negative temperature coefficient of these high resistivity (\geq 100 $\mu\Omega$ cm) metallic glasses. However, to get negative α

- i) the effective scattering must be strong enough to initiate the energy gap formation in the density of states curve and ii) $E_{\rm F}$ has to be near the energy gap.
- These theoretical studies which completely ignore the structure of the disordered materials have their own shortcomings e.g., they cannot explain $\rho = a+bT^2$ behaviour in the intermediate temperature region. Despite these shortcomings attempts to explain the transport behaviour directly from Kubo formula, does not fail in strong scattering systems and seem promising. Yonezawa has tried to establish a systematic scheme of studying transport properties of materials with strong scattering potentials using the effective medium approximation (EMA) for conductivity. We also face another

controversial point in p-T plots of metallic glasses the dependence on T in the intermediate temperature range. Ziman's theory considers the electron-ion potential scattering and at low temperatures it evolves into a T2 dependence. Bergmann et al⁶⁸ and Richter et al⁶⁹ have worked out the effect of the electron-magnon scattering and get a $T^{3/2}$ dependence. Experimental evidence of this T3/2 dependence of p has been claimed by many workers 70,71 . Mogro-Campero et al 22 have argued in their report that though the best fit to the equation $P = a+bT^n$ is obtained with n = 1.5 in the intermediate temperature range, it cannot be claimed definitely that it is the electron-magnon scattering which governs the ρ -T dependence in the intermediate temperature They have suggested that it is possible that electronion potential scattering alone can explain the observations. It may be that the intermediate temperature regime is the transition region between the asymptotic T and T² behaviours and in the temperature interval 20K < T < 100K this transition can be well described by power law with exponent n . 1.5. (vii) Magnetoresistance:

The anisotropic magnetoresistance (ρ_{11} - ρ_{1}), being an inherent material property, does not depend on the initial magnetic domain structure and remains unchanged by heat treatment etc. Hence one can compare other magnetic properties in terms of this quantity 73,74,75 . The practical quantity

which is generally measured is the ratio of $(\rho_{11}-\rho_{1})$ and the specific resistivity ρ of the material. This quantity $(\rho_{l} - \rho_{l})/\rho$ or $\Delta \rho/\rho$ is known as the ferromagnetic anisotropy of resistivity (FAR). As stated earlier, in amorphous glasses, magnetostriction contributes greatly to the appearance of finite values of magnetic anisotropy. With regard to this significant behaviours of λ , another problem of interest is the magnetoresistance of these amorphous alloys 76. It appears that the anomalous magnetoresistance depends upon the magnetic domain structure associated with stress magnetostriction. The magnitude of the anisotropic magnetoresistance may depend upon the electronic mechanism associated with amorphous structure which is related to the characteristics of magnetostriction. However, the available data on the magnetoresistance of the amorphous alloys are not sufficient to discuss the above problem. Recently, the investigation of magnetoresistance in amorphous alloys has become a subject of several studies 77,78,79. Bhonke and Rosenberg 80 have studied the magnetoresistance of Fe-Ni-P-B metallic glasses at different temperatures. From the dependence of FAR on temperature they predicted that $\Delta F / F$ at OK increases with the amount of Fe, and that above Tc the magnetoresistivity becomes isotropic. Fukamichi et al⁷⁵ have studied FAR in Fe-B glasses and pointed out that the concentration and temperature dependences of the FAR for Fe-B alloys are very

similar to those of the saturation magnetization and the linear magnetostriction. In another report 81 , where they have studied FAR of Fe-P alloys, they have shown that $\lambda_s \propto M_s^2$ is not valid in this system but FAR and λ_s vary similarly at room temperature. Naka, Kern and Gonser 73 have studied FAR in Fe-B-P system. They have verified the correlation between FAR and saturation magnetic moment in this series $(\Delta P/P = A\mu^m)$. An important result of FAR is that the FAR of amorphous alloys are an order of magnitude smaller than those of their crystalline counterparts. Nigam and Majumdar 82 have shown that the field dependence of resistivity, and other corresponding features like magneteanisotropy of resistivity (FAR) etc. of amorphous ferromagnets behave in a manner which is similar to that of crystalline ferromagnets.

(viii) Hall Effect:

Hall effect is an important galvanomagnetic property which is widely studied \$3,84,85. One of the most important questions regarding amorphous materials concerns their stability against thermal cycling. For instance, some of the amorphous alloys are metastable at 300K, show irreversible effects on heating and eventually crystallize upon heating to temperatures 600-800K. They crystallize into different structures depending upon the temperature and the composition of the material. Hall resistivity is strongly influenced by thermal cycling \$6,87 and hence it could be an important tool

to understand the occurrence of new phases during any transformation process. A good review on Hall effect studies of amorphous glasses from an experimental point of view is presented by T.R. McGuire et al⁸⁸. An open question in this area is the understanding of the sign and magnitude (always larger than those of their crystalline counterparts) of the Hall coefficients of these amorphous alloys ^{14,56}. The Hall coefficient in these glasses does not obey the free electron formula and is often positive.

(ix) Invar Property:

Another property which would frequently enter our discussion in Chapter V is the Invar property. As reported by Wohlfarth 89 the Invar behaviour is almost always observed for weak itinerant ferromagnets and should thus arise for some of the amorphous alloys. $(Fe_xNi_{100-x})_{80}^P10^{-B}10$, $Fe_xMn_P_C$, Ni_P , Fe_x are the examples of weak itinerant ferromagnets. Invar problems are closely related to the origin of ferromagnetism in transition metals and alloys 90 and hence is an important research field in ferromagnetic materials. To find out whether a particular material has Invar characteristics or not one should check as follows. The expected observations are 89 - (1) low saturation magnetization (2) low T_c (3) large high field susceptibility (4) large volume magnetostriction (5) large negative linear thermal

expansion at low temperatures, (6) low thermal expansion at $300K^{91}$, (7) large negative pressure derivative of saturation magnetization, leading to a critical pressure for the disappearance of ferromagnetism, (8) large negative pressure derivative of T_c , (9) small spin-wave stiffness constant D, and (10) anomalies at the Curie temperature. According to Masumoto 92 high magnetic moment and a low Curie temperature are empirical principle of finding Invar alloys.

After this brief review of magnetic and electric properties we conclude that most of the properties of metallic glass are qualitatively similar to those of their nearest available crystalline counterparts. Whatever quantitative differences are there between amorphous and crystalline alloys arise from the chemical disorder, not from structural disorder. Some of the results concerning the thermal and transport properties are very specific for glasses. These are:

- i) Specific heat shows a term almost linear in T at very low temperatures
- $\pm i$) The T² dependence of resistivity ρ at low temperatures
- iii) Negative temperature coefficient of resistivity α , at high temperatures.

The appeal of these amorphous magnetic ribbons lies in the following factors: (1) the lack of magnetocrystalline anisotropy, with low domain wall energy, nearly reversible wall

motion and easy magnetization direction along the ribbon axis (2) moderately high resistivity (higher compared to the conventional metallic materials used for devices) which results in smaller eddy current contributions to the permeability and losses, which is specially important at higher frequencies, (3) the combination of high resistivity and thin gauge of the ribbons (0.003 to 0.005 cm), reduces the magnetic loss by a factor of 10 compared to polycrystalline 3% Si-Fe sheets in conventional thickness (Note: the achievement of very thin gauge in Si-Fe is very expensive) and (4) presumably, inexpensive to manufacture.

SUBJECT OF PRESENT STUDY

In the present investigation we have chosen a very simple transition metal-metalloid (T-M) metallic glass—series, namely, $Fe_{100-x}B_x$ (13 \leq x \leq 26). Characterization of such simple binary metallic glasses is important towards understanding the properties of more complicated amorphous systems. We have studied the absolute values of electrical resistivity as a function of composition, the temperature dependence of electrical resistivity in the temperature range $77K \leq T \leq 300K$, the ferromagnetic anisotropy of resistivity (FAR) and the Hall effect in the Fe-B series. All these experiments were done on the same set of $Fe_{100-x}B_x$ (13 \leq x \leq 26) samples manufactured by Allied Chemical Corporation, USA. Since the composition range is rather wide it is ideal for studying the composition

dependence of the above galvanomagnetic properties. Here, any correlation and comparison of physical properties are meaningful since various measurements are made on the same set of samples. This is especially desirable for metallic glasses.

An order of magnitude calculation for α and $\Delta\rho/\rho$ was reported by us 93 for the first time. Also, the variations of the absolute values of resistivity ρ , the spontaneous Hall constant R_s and the spontaneous Hall conductivity $^{\gamma}H_s$ with the boron concentration in Fe-B alloys are also presented for the first time in our work. The results of magnetoresistance measurements are included. The angle θ between the spontaneous magnetization M_s and the ribbon axis for the whole series is reported. We have tried to estimate the absolute resistivity and FAR for amorphous Fe from our magnetoresistance and resistivity data. An attempt is made to consistently explain our observations in terms of the structure, known physical properties and Invar anomaly of Fe-B series.

The variation of ρ with temperature, in the temperature range 4.2K \leq T \leq 300K, for another series of metallic glass, $\text{Fe}_{80} \text{B}_{20-x} \text{Si}_{x} \ (0 \leq x \leq 12) \text{ is also presented.}$ These samples are manufactured by General Electric Co., USA.

CHAPTER II

THEORY

2.1 ELECTRICAL RESISTIVITY

There is a striking similarity in the structure, magnitude of electrical resistivity ρ and the temperature coefficient α of resistivity of liquid metals and glassy metals. Keeping view, we believe that a model which explains the high temperature electrical transport behaviour of liquid metals can be used to explain glassy metals too. Hence, we may try to use Ziman's theory of liquid metals 4 to explain the behaviour of metallic glasses. The most common metallic glasses are the alloys of T-M type where T is a transition metal (Fe,Co,Ni,Pd, etc) and M is a polyvalent metal (B,Si,P,C etc.). Obviously, the electronic properties of such alloy are affected most by the d-states. These glasses consist of randomly distributed ions and the conduction electrons. The ions are positioned in a random close-packed distribution. The arrangement of the ions in the glassy (i.e., frozen liquid) state can be described in terms of a pair correlation functioning q(r). The function g(r) determines the probability of finding two ions separated by the distance r. This function has a typical shape: zero for small distances (where the atomic cores cannot overlap) and unity for large distances, with a

number of oscillatory peaks between these two limits. Fourier transform of the pair correlation function is the structure factor S(k) i.e., the interference function. intensity of beam scattered from the alloy depends on this function S(k). A typical example of the S(k) vs k graph is shown in Fig. 2.1. The main peak represents the nearest neighbour distance of the alloy in k space, denoted by k_{p} . The distribution functions S(k) and g(r) are deduced from X-ray and neutron scattering experiments, statistical mechanics calculations and computer experiments. conduction electrons are supposed to form a degenerate freeelectron gas with a spherical Fermi surface. The electrical resistivity can be explained only by interaction of the conduction electrons with the ions. The electrons represented as plane waves are scattered by the irregular arrangement of the metal ions.

According to Ziman the electrical resistivity of liquid metal can be given as,

$$\rho = \frac{3 \pi 0}{4e^2 h v_F^2 k_F^4} \int_0^{2k_F} S(k) |V(k)|^2 k^3 dk \qquad (2.1)$$

where Ω is the atomic volume, \mathbf{v}_F the Fermi velocity, \mathbf{k}_F the radius of the Fermi-sphere, $\mathbf{S}(\mathbf{k})$ the structure factor and $\mathbf{V}(\mathbf{k})$ is a suitably chosen electron-ion potential. For liquid transition metals, Evans et al⁹⁵ have extended the Ziman's formula,

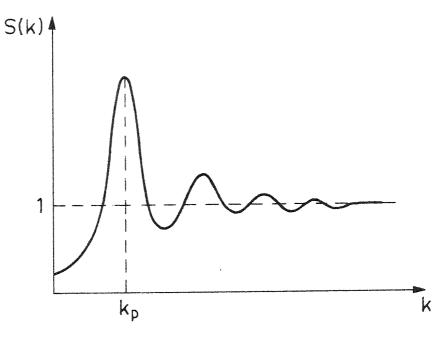
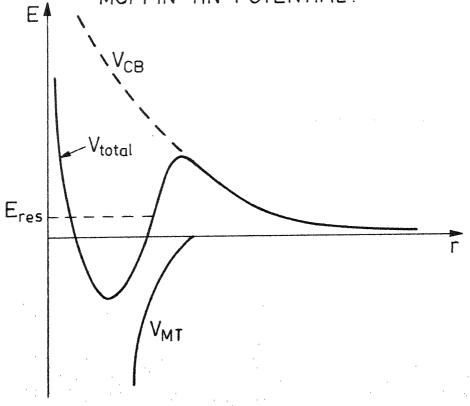


FIG. 2.1

TOTAL POTENTIAL OF ONE TRANSITION METAL ION. V_{CB} IS CENTRIFUGAL BARRIER, V_{MT} IS MUFFIN-TIN POTENTIAL.



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using mainly physical arguments, by bringing in the t-matrix of the muffin_tin potential for one ion. The total potential is a superposition of muffin-tin potential and the centrifugal barrier arising for d-electrons (Fig. 2.2). The d states act as resonance state. The conduction electrons scattered by this potential experiences a delay or resonance scattering. The strength of the scattering depends on the difference $(E_{\text{res}}-E_{\text{F}})$. Gyorffy, Szabo and Evans 96 have derived an exact expression of resistivity in terms of phase shifts and the ion positions. The extended Ziman's formula for resistivity is (following Busch and Guntherodt) 97

$$\rho = \frac{3\pi\Omega}{4e^{2}hv_{F}^{2}k_{F}^{4}} \int_{0}^{2k_{F}} S(k) |t(k)|^{2} k^{3} dk$$

where t(k) is the single-site t matrix which is defined in the partial wave representation as

$$t(k) = \frac{-2\pi\hbar^3}{m(2mE)^{1/2}} \frac{1}{\Omega} \sum_{i=1}^{\infty} (2i+1) \sin \eta_{i}(E) \exp i\eta_{i}(E) P_{i}(\cos\theta)$$

where m is the electron mass, E_f is the Fermi energy (measured relative to the muffin-tin zero) and the sum is over various partial waves contributing to the scattering. $P_1(\cos\theta)$ is the Legendre polynomial of order 1 and the η_1 are the partial wave phase shifts describing the scattering of the conduction electrons by the ion cores. If the d-phase shift η_2 is dominant at the Fermi energy in transition metals, we can write

$$\rho = \frac{30\pi^{3}h^{3}}{m e^{2}k_{F}^{2}E_{F}^{0}} \sin^{2} \eta_{2}(E_{F}) S(2k_{F})$$

$$\rho = \frac{30\pi^3 \, \text{K}^3}{\text{m e}^2 \, \text{k}_F^2 \, \text{E}_F} \, \Omega \qquad \text{S(2k}_F) \, \frac{1}{7^2 + 4 \left(\text{E}_{res} - \text{E}_F \right)^2}$$
 (2.2)

where $\widehat{\mathbf{f}}$ is the width and \mathbf{E}_{res} is the energy of the scattering resonance lying approximately at the centre of the 3d band (Fig. 2.3).

Thus the electrical resistivity $\boldsymbol{\rho}$ is governed by two major factors,

- (i) the structure factor or 'interference function' S(k), and
- (ii) the resonant scattering of conduction electrons from the 3d states lying in the conduction band by the ion cores.

As can be seen from Fig. 2.3, with the increase of the number of 3d electrons the Fermi energy E_F increases, the difference $E_{\text{res}}-E_F$ increases and hence from $e_{\text{qn}}\cdot(2.2)$ the resistivity value ρ should decrease. From Fig. 2.3, it can be predicted that amorphous F_e will have a larger resistivity value than the amorphous Ni. The large resistivity values of metallic glasses are due to this resonance scattering.

2.1.1 Temperature Dependence of Electrical Resistivity

In Ziman's theory of liquid metals the temperature dependence of electrical resistivity is included by taking into account the change in the structure factor S(k) as the

CONTRIBUTION OF RESONANCE SCATTERING IN TERMS OF PHASE SHIFT η_2 and $(\mathsf{E_{res}}^-\mathsf{E_F})$. ARROWS INDICATE THE FERMI ENERGIES OF TRANSITION METALS RELATIVE TO $\mathsf{E_{res}}$. THE LARGEST CONTRIBUTION ARISES IF $\eta_2(\mathsf{E_F})$ IS CLOSE TO THE VALUE OF $\pi/_2$ OR IF THE DIFFERENCE $(\mathsf{E_{res}}^-\mathsf{E_F})$ IS SMALL.

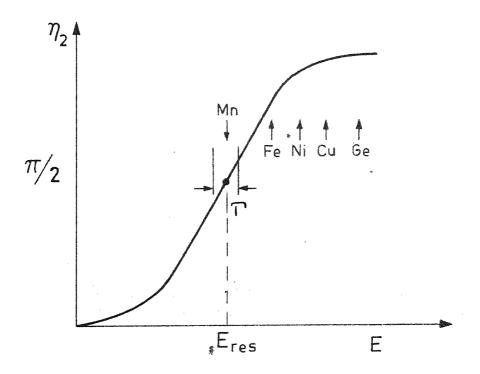


FIG. 2.3

temperature T is varied. However, in the solid the change in S(k) should be calculated as due to the vibration of ions around their equilibrium positions. An expression for this change is derived by including the Debye-Waller factor. The first peak height of S(k) versus k graph decreases with increasing temperature, giving rise to a negative α , whereas the number of phonons increase with increasing temperature resulting in a positive α . In case of metallic glasses these two mechanisms are competitive. The final sign of α is determined by the dominant one.

Following Nagel 98 the electrical resistivity ρ of metallic glass is given by.

$$\rho = \frac{30\pi^{3}h^{3}}{\text{m e}^{2}k_{F}^{2}E_{F}\Omega} \sin^{2}\eta_{2}(E_{F}) S(2k_{F})$$
 (2.3)

where $\eta_2(E_F)$ is the 1 = 2 partial wave phase shift at the Fermienergy E_F .

In this equation, the temperature-dependence of ρ will be determined by the temperature dependence of $S(2k_F)$. In calculating the temperature dependence of $S(2k_F)$, i.e., $S_T(2k_F)$, care must be taken to include not only the decrease in the intensity of the structure factor but to include phonon terms as well. The resulting expression for $S_T(k)$ is given by

$$S_{T}(k) \simeq 1 + [S(2k_{F}) - 1]e^{-2W(T)}$$
 (2.4)

Now the resistivity as a function of temperature can be expressed as

$$\rho(T) = \frac{30\pi^{3}h^{3}}{m e^{2}k_{F}^{2}E_{F}^{2}\Omega} \sin^{2}[\eta_{2}(E_{F})] \times \{1+[S_{0}(2k_{F})-1]e^{-2[W(T)-W(0)]}\}$$
(2.5)

where k_F is the Fermi wave vector, Q is the atomic volume, W(T) is the Debye-Waller factor at a temperature T, $S_T(2k_F)$ is the structure factor corresponding to $k=2k_F$, and h, and h have their usual meaning.

Also,
$$\alpha = \frac{1}{\rho_{RT}} \frac{\partial \rho_{T}}{\partial T} \simeq 2 \left[\frac{1 - S_{T}(2k_{F})}{S_{T}(2k_{F})} \right] \frac{\partial W(T)}{\partial T}$$
(2.6)

Since $\partial W(T)/\partial T>0$, α is negative only if $S_T(2k_F)>1$, i.e., if $2k_F$ is near k_P , the position of the first peak in the S(k) versus k graph. Coming back to eqn. (2.6), the asymptotic temperature dependence of W(T) in the Debye approximation is given by,

$$W(T) = \begin{cases} W(\circ) + 4W(\circ) \frac{1}{6} \pi^{2} (T/\Theta_{D})^{2} & \text{for } T << \Theta_{D}, (2.7) \\ W(\circ) + 4W(\circ) (T/\Theta_{D}) & \text{for } T \ge \Theta_{D}, (2.8) \end{cases}$$

where

$$W(o) = \frac{3h^2k^2}{8M K \Theta_D}$$
 (2.9)

here M is the atomic weight and K is Boltzmann constant.

Thus an estimate of α could be made for individual alloys, from eqns. (2.6) and (2.8), if the structure factor S(k) at the corresponding $2k_F$ value (which depends on the number of conduction electrons per unit volume) and Θ_D are known. The percentage change of resistivity $\Delta P/P$ from 300 to 80K is given by .

$$\frac{\Delta \rho}{\rho} = \frac{\rho(300K) - \rho(80K)}{\rho(80K)}$$

$$= -C \frac{[S_T(2k_F) - 1]}{S_T(2k_F)}$$
(2.10)

This expression along with the constant C would be derived from eqns. (2.5), (2.7) and (2.8). Using the same equations, Θ_D is found to be,

$$\Theta_{\rm D} = \frac{\pi^2}{6} \frac{\alpha}{5} \tag{2.11}$$

where
$$S = \frac{\partial \rho_T}{\rho_{RT} \delta(T^2)}$$
 for $T \ll \Theta_D$ (2.12)

It is clear from eqns. (2.5), (2.7) and (2.8) that the resistivity ρ is expected to vary as T^2 at low temperatures (low with respect to the Debye temperature) and vary as T at high temperatures. The functional relationship predicted for electron—ion potential scattering is given by,

$$\rho = a + bT^{n} \tag{2.13}$$

where asymptotically n=1 or 2.

The non-magnetic term changes from T to T^2 as one moves to lower temperature, and the transition depends on the value of Debye temperature.

At very low temperatures, a minimum of the electrical resistivity is observed. There are two main mechanisms which are suggested for explaining this resistivity minimum (i) the Kondo effect 99 which is magnetic in origin and (ii) tunneling-state scattering, 100 which is completely nonmagnetic in origin and is believed to be a manifestation of the amorphous structure. We generally restrict our interest in the range above this minimum, i.e., in the temperature range 20K $\leq T \leq 300$ K.

2.1.2 Composition Dependence of Electrical Resistivity

As stated earlier, the main contribution to the large values of electrical resistivity of liquid transition metals comes from the resonant scattering of conduction electrons from the d-states. As discussed by Nagel and Tauc 20 when these transition metals are alloyed with polyvalent metals and quenched to solid state, the result is a frozen liquid structure, with the effective number of conduction electrons $Z_{\mbox{eff}}$ which increases in accordance with the relation

$$Z_{eff} = Z_1(1-x) + Z_2x$$
 (2.14)

where \mathbf{Z}_1 and \mathbf{Z}_2 are the number of conduction electrons of corresponding metals.

This, in turn, increases the value of $2k_F$ giving rise to a larger contribution to the resistivity via the structure factor. The assumption made in formulating this model is that the Group VIII transition metals (Fe,Co,Ni) as well as the noble metals can be treated as if they had one free-electron per atom in the liquid state. Faber and Ziman 101 predict that on such alloying the resistivity will reach a maximum when $2k_F$ passes through k_P . Also, when $2k_F$ $^{\circ}k_P$, negative temperature coefficients (NTC) occur.

In calculating the resistivity of metallic glasses as a function of composition, we assume that in eqn. (2.5), $\sin^2[\eta_2(E_F)] \text{ and } \Omega \text{ are approximately the same for the whole series. Using the relation } E_F\alpha k_F^2 \text{ we can write eqn. (2.5) as,}$

$$\rho = \frac{C!}{k_F^4} \{ 1 + [S_0(2k_F) - 1] \} e^{-2[W(T) - W(0)]},$$

where C' takes care of the constants.

Since we are calculating the room temperature resistivity in eqn. (2.14) we use W(T) - W(o) from eqn. (2.8).

Then eqn. (2.14) can be written as,

$$\rho = \frac{C!}{k_F^4} \{ S_0(2k_F) + 8W(0) \frac{T}{\Theta_D} [1 - S_0(2k_F)] \}$$
 (2.15)

The values of k_F , $S_o(2k_F)$, W(o) and Θ_D change with

changing metalloid concentration x and thus we can roughly estimate the nature of variation of resistivity ρ with composition x.

2.1.3 Electronic Stability Criterion

Nagel and Tauc 20 have suggested a model to understand the stability of the metallic glasses, i.e., to understand 'why the metallic glasses are structurally stable only over a limited range of composition '. The metallic glasses which are basically metals are treated as a nearly free-electron In a crystal the structure factor S(k) depends on both magnitude and direction of k, but in amorphous materials S(k) is spherically symmetric. Hence, in the case of metallic glasses the relationship between $2k_F$ and k_P is of crucial importance. For atoms with Z=1, $2k_F$ lies slightly below k_P and for Z=2, $2k_F$ lies slightly above k_P . The effect of alloying a monovalent metal with an element with higher valence is to shift the effective valence, $Z_{eff} = Z_1(1-x) + Z_2x eqn($ thus shifting $2k_F$ towards k_P . A system with $2k_F = k_P$ is believed to be more stable against crystallization than a system for which $2k_F \neq k_p$. They have suggested an arbitrary choice of $Z_{eff} = 1.7$, to give a reasonable estimate of the concentration (x), which is needed for the situation $2k_F = k_p$. Depending on the details of S(k) vs k graph, kp will coincide with $2k_F$ at different values of Z_{eff} .

2.2 MAGNETORESISTANCE

The electrical resistivity of a polycrystalline ferromagnet depends on the angle between the current density \vec{J} and the magnetization vector \vec{M} . The longitudinal magnetoresistance $(\vec{J} \mid \vec{M})$ is positive while the transverse one $(\vec{J} \mid \vec{M})$ is negative at low fields. At higher fields there is a slow decrease in resistivity, i.e., a negative magnetoresistance is observed in both orientations. Assuming a cubic structure for a ferromagnetic domain, the resistivity of a cubic single crystal can be written as 102

$$\rho(\alpha_{1},\beta_{1}) = a_{0} + a_{1}(\alpha_{1}\beta_{1} + \alpha_{2}\beta_{2} + \alpha_{3}\beta_{3})^{2} + 2(a_{2} - a_{1})(\alpha_{1}\alpha_{2}\beta_{1}\beta_{2} + \alpha_{2}\alpha_{3}\beta_{2}\beta_{3} + \alpha_{3}\alpha_{1}\beta_{3}\beta_{1}), \qquad (2.16)$$

where $\alpha_1, \alpha_2, \alpha_3$ are the direction cosines of spontaneous magnetization with respect to the crystal axes and the resistivity is measured in a direction characterized by the direction cosines $\beta_1, \beta_2, \beta_3$. Under the conditions \vec{J} / \vec{M} and $\vec{J} \cdot \vec{M}$, the saturation values of resistivity, expressed respectively as $\rho_{1|S}$ and $\rho_{1|S}$ can be found out by taking the averages of eqn. (2.16). One can write then,

$$\rho_{IIS} = a_0 + \frac{3}{5} a_1 + \frac{2}{5} a_2 , \qquad (2.17)$$

$$\rho_{1S} = a_0 + \frac{1}{5} a_1 - \frac{1}{5} a_2 . \qquad (2.18)$$

In ideal condition, when all the orientations with respect to the crystal axes are equally probable, and the crystallites are oriented at random, the resistivity ρ_0 in the demagnetized state, can be written as

$$\rho_0 = a_0 + \frac{1}{3} a_1 = \frac{1}{3} \rho_{11S} + \frac{2}{3} \rho_{1S}$$
 (2.19)

But, as stated in Chapter I, even in glassy ferromagnetic alloys, where the absence of magnetic anisotropy was expected, it was found out that these alloys had preferred magnetic directions which were induced during the cooling process etc. Thus, the ratio of $\Delta \rho_{11S}/\Delta \rho_{1S}$ depends completely on the orientation of this preferred axis. Here $\Delta \rho_{11S} = \rho_{11S} - \rho_{0}$ and $\Delta \rho_{1S} = \rho_{11S} - \rho_{0}$

2.2.1 Ferromagnetic Anisotropy of Resistivity (FAR)

Though the ratio $\Delta \rho_{\text{IS}}/\Delta \rho_{\text{IS}}$ depends on the initial processing and subsequent heat treatments etc, the quantity $(\Delta \rho_{\text{IS}} - \Delta \rho_{\text{IS}})$ does not depend on the initial magnetic domain structure and hence is a very important inherent property of the ferromagnet. This difference, which is practically always positive is called the anisotropic magnetoresistance. The experimentally measured quantity, the relative change in resistivity $\Delta \rho/\rho_{\text{O}}$ is called the ferromagnetic anisotropy of resistivity, FAR. Hence,

$$FAR = \frac{\Delta \rho}{\rho_0} = \frac{\rho_{11} S^{-\rho_{1S}}}{\rho_0}$$
, (2.20)

and the anisotropic magnetoresistance is given as,

$$\Delta \rho_{\text{IIS}} - \Delta \rho_{\text{IS}} = \rho_{\text{IIS}} - \rho_{\text{IS}}, \qquad (2.21)$$

where ρ_0 , the resistivity in the demagnetized state can be written from eqn. (2.19) as,

$$\rho_{o} = \rho + \frac{1}{3} \Delta \rho_{IIS} + \frac{2}{3} \Delta \rho_{IS} , \qquad (2.22)$$

 ρ being the resistivity for $H_{ext} = o$.

In a ferromagnet, because of the presence of spontaneous magnetization within each Weiss domain, the effective magnetic field is given by,

$$H_{eff} = H_{int} = H_{ext} - H_{demag}$$

$$= H_{ext} - \alpha M_{S} \quad (in MKS units) \qquad (2.23)$$

where α is the domagnetizing factor which depends on the dimensions of the sample and its orientation with respect to the magnetic field and M $_{\rm S}$ is the saturation magnetization at a particular temperature.

As stated earlier, to get $\rho_{_{\scriptsize O}}$, one has to do some kind of averaging over the all possible orientations of the spontaneous domain magnetization. In metallic glasses, since we have a uniaxial anisotropy and the domains are not at random, it is very difficult to do such averaging. However, fortunately enough, these materials have very small magnetoresistance and thus instead of calculating $\rho_{_{\scriptsize O}}$ we can use

$$\rho_{O} = \rho \tag{2.24}$$

Thus eqn. (2.20) can be written as,

$$FAR = \frac{\Delta \rho}{\rho} = \frac{\rho_{11S} - \rho_{1S}}{\rho}$$
 (2.25)

To get the anisotropic magnetoresistance ($\rho_{IIS} - \rho_{IS}$) in terms of the measured quantities one writes,

$$\rho_{11S} = \rho + \Delta \rho_{11S} = \rho (1 + \Delta \rho_{11S} / \rho)$$
 (2.26)

$$\rho_{LS} = \rho + \Delta \rho_{LS} = \rho (1 + \Delta \rho_{LS}/\rho) \qquad (2.27)$$

and thus,

$$\rho_{IIS} - \rho_{IS} = (\Delta \rho_{IIS}/\rho - \Delta \rho_{IS}/\rho)\rho \qquad (2.28)$$

where $\Delta \rho_{IIS}/\rho$ and $\Delta \rho_{IS}/\rho$ are obtained by extrapolating the $\Delta \rho/\rho$ versus $H_{\rm ext}$ plots to $H_{\rm ext}=H_{\rm demag}$, such that $H_{\rm int}=0$.

Hence, in terms of experimentally measured quantities, FAR [Eqn. (2.25)] can be written as.

$$FAR = \frac{\Delta \rho_{11S}}{\rho} - \frac{\Delta \rho_{1S}}{\rho}$$
 (2.29)

2.2.2 Dependence of ρ on H

This is an effect of purely ferromagnetic origin. As stated by $Smit^{10.3}$, if we compare the change in resistance with the magnetostriction, then the linear saturation magnetostriction corresponds to the Ferromagnetic anisotropy of resistivity both being tensor dependent on the orientation of the magnetization. However, the volume magnetorestriction corresponds to the small negative value of $\partial \rho/\partial H$ at strong fields, independent of the orientation. Clearly, volume effects are due to the effect of increasing intrinsic magnetization with increasing field. The direct influence of volume magnetostriction on resistance is very small 103 ($\frac{1}{\rho}$ $\frac{\partial \rho}{\partial H}$ values are very small) and hence the effects observed are due to a change of the specific resistance. Assuming that the resistivity depends only on magnetization M_S , one can write,

$$\frac{\partial \rho}{\partial H} = \frac{\partial M_S}{\partial M_S} \frac{\partial H}{\partial M_S} \tag{2.30}$$

Now again assuming that ρ does not vary appreciably with magnetization M_S for normal fields, the dependence of $\partial \rho/\partial H$ on H is determined by that of $\partial M_S/\partial H$, the high field susceptibility.

2.2.3 Formulation of Θ , the Angle between \vec{J} and \vec{M}

Since in metallic glasses, we have uniaxial anisotropy, i.e., the domains are preferentially oriented at some angle θ with the ribbon axis, the resistivity in the demagnetized state can be expressed as.

$$\rho_{o} = \rho_{\perp} \sin^{2}\theta + \rho_{\parallel} \cos^{2}\theta \qquad (2.31)$$

where Θ is the angle between the current and the magnetization vectors. Hence, the longitudinal magnetoresistance is

$$\Delta \rho_{11}/\rho_{0} = \frac{\rho_{11} - \rho_{0}}{\rho_{0}} = \frac{\rho_{11} - \rho_{1} \sin^{2}\theta - \rho_{11} \cos^{2}\theta}{\rho_{0}}$$
$$= \frac{(\rho_{11} - \rho_{1})\sin^{2}\theta}{\rho_{0}}$$

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$$\frac{\Delta \rho_{11}}{\rho_{0}} = FAR \sin^{2}\theta \qquad (2.32)$$

Similarly, the transverse magnetoresistance is

$$\frac{\Delta \rho_{\downarrow}}{\rho_{0}} = -FAR \cos^{2}\theta \qquad (2.33)$$

From eqns. (2.32) and (2.33) we get,

$$FAR = \Delta \rho_{11} / \rho_{0} - \Delta \rho_{1} / \rho_{0}$$

and
$$\cot^2\theta = \frac{\Delta \rho_{\perp} / \rho_0}{\Delta \rho_{\perp} / \rho_0}$$
 (2.34)

Using eqn. (2.24), we can write this equation as,

$$\cot^2 \theta = -\frac{\Delta \rho_{\perp} / \rho}{\Delta \rho_{\perp} / \rho} \tag{2.35}$$

2.2.4 Relation Between FAR and Saturation Magnetization

Bhonke et al⁷⁹ have shown that $\Delta \rho/\rho$ varies as $T^{3/2}$. The saturation magnetic moment $\mu(\mu_B/\text{Fe} \text{ atom})$ also varies as $T^{3/2}$. Considering these two observations Bhonke et al have suggested an empirical relationship between them as,

$$\frac{\Delta \rho}{\rho} = A \mu^{\rm m} \tag{2.36}$$

where μ is the saturation magnetic moment/Fe atom and A,m are constants.

2.3 HALL EFFECT

The Hall resistivity $\rho_{\rm H}$ in a polycrystalline ferromagnet can be written as 102 ,

$$\rho_{H} = \frac{E_{y}}{J_{y}} = R_{o}B_{z} + R_{S}M_{z}$$

where \vec{J} || $\hat{\vec{x}}$ is the electric current density, \vec{E} the clectric field and \vec{B} || $\hat{\vec{z}}$ is the magnetic induction. The first term has its origin in Lorentz force acting on the conduction electrons and is present in nonmagnetic materials too. R_o is the coefficient of this ordinary Hall effect. The second term



depends on the magnetization and is a characteristic property of fewromagnets. The coefficient $R_{\rm s}$ is called the extraordinary or spontaneous Hall constant. Here we will concentrate only on the spontaneous Hall effect.

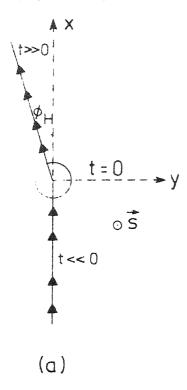
An excellent physical picture of the scattering mechanism for $R_{\rm s}$ is given by Berger $^{\rm LC5}$. The spontaneous Hall effect depends on the magnetization. When a magnetic moment moving in an electric field sees a magnetic field, its gradient gives rise to a force on the moment. Thus the interaction of the electronic spin (magnetic moment) with the electric field of the screened nucleus defines its spin-orbit interaction. The spin-orbit interaction gives rise to a left-right asymmetry in the scattering of the spin-polarized carriers. This asymmetry is observed as the spontaneous Hall effect. In ferromagnets at ordinary temperatures (T > 100K), $R_{\rm s}$ >> $R_{\rm o}$ and can be written as 102 ,

$$R_{s} = A \rho^{n}, \qquad (2.37)$$

where A is a constant depending on the metal, but not on temperature and $R_{\rm S}$ is the spontaneous Hall coefficient, related to the spin-orbit interaction.

Consider an electron wave-packet approaching a scattering potential (Fig. 2.4). Before scattering the centre of mass of the packet moves in a straight line through the periodicrystal.

ASYMMETRIC SCATTRING



SIDE -JUMP MECHANISM

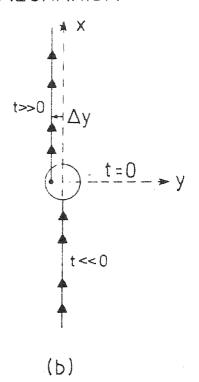


FIG. 2.4

After scattering, the wave-packet is broken into a set of outgoing spherical waves. A part of the wave is back-scattered, so the motion of the wave-packet after scattering is rather slow. Still, according to quantum mechanics this motion again follows a straight line, at a constant speed.

If the electron spin \vec{S} is normal to the plane of the picture, the spin-orbit interaction removes any symmetry between right and left. So, the trajectory after scattering differs from the trajectory before scattering. Let us say that the new trajectory is at an angle ϕ_H [see Fig. 2.4.a)to the old one before scattering. This implies that the electron acquires transverse momentum on scattering. This effect is called skew-scattering and can be derived from classical Boltzmann equation if the differential cross-section has a left-right asymmetry. This effect is characterized by the tangent of the Hall angle ϕ_H , i.e., β

$$\tan \mathcal{D}_{H} = \beta = \rho_{H}/\rho \qquad (2.38)$$

Clearly, for skew-scattering $\rho_H \alpha \rho$ and hence in eqn. (2.37) it gives n = 1. This scattering effect vanishes for weak scatterers. The only materials where this mechanism is observed are low-resistivity dilute alloys at 4K.

Instead of deflection of wave-packet at any angle after scattering, the scattering potential can displace the new trajectory by a distance Δy . This transverse displacement is

called the 'side-jump' by Berger¹⁰⁵. It is a quantum mechanical mechanism. The side-jump Δ y of the carrier wave-packet is approximately related to the Hall angle by the mean free path λ

$$tan \mathcal{D}_{H} = \beta = \Delta y / \lambda \alpha \cdot \rho \Delta y \qquad (2.39)$$

From eqn. (2.39) it is clear that the side-jump mechanism predicts n=2 in eqn. (2.37). Thus for a given band structure variation of R_s with ρ is given as,

$$R_s = a \rho + b \rho^2$$
 (2.40)

For a single band 106,

$$\Delta y = 4\pi M_s b(\hbar k_F/n e^2) = 4\pi (R_s M_s/\rho^2) (\hbar k_F/n e^2)$$
 (2.41)

Thus, one can say, that eqn. (2.37), if valid, clearly shows that the spontaneous Hall effect is connected with the electron scattering. In metallic glasses, the validity of this relation $(R_{\rm S}\alpha~\rho^2)$ is difficult to confirm experimentally because of the weak temperature dependence of $R_{\rm S}$ and ρ and also because small variations in metalloid content have comparatively little effect on the resistivity, which is dominated more by disorder. Nevertheless in Chapter V we would try to find out the validity of this relation by comparing the concentration (x) dependence of $R_{\rm S}$ and ρ . The Hall conductivity $\gamma_{\rm H_{\rm C}}$, given by,

$$\gamma_{H_s} = \rho_H / \rho^2 = R_s M_s / \rho^2$$
, (2.42)

becomes almost independent of temperature or concentration if eqn. (2.37) with n = 2 is valid for R_s .

2.4 CORRELATION BETWEEN MAGNETORESISTANCE AND HALL EFFECT

When a d.c. current is passed perpendicular to the domain walls, the current lines get sharply bent at the walls by twice the Hall angle of the material. As a result the current follows a zig-zag path and the ohmic resistance of the sample is expected to increase. In an uniaxial ferromagnet, where the resistivity tensor has an off-diagonal Hall component, Berger 107 has calculated from Maxwell's equations in the neighbourhood of 180° domain walls that there is an increase in ohmic resistivity. When a magnetic field parallel to the easy axis removes the domain walls, a negative magnetoresistance results, which is given (assuming wall spacing << sample width) by,

$$\Delta \rho / \rho' = -\beta^2 \tag{2.43}$$

Here ρ' is the resistivity in the absence of walls, β is the tangent of the Hall angle and is given by,

$$\beta = \tan \theta_{H} = \rho_{H}/\rho_{\perp}$$
 (2.44)

Chon the basis of this theory, a correlation between magnetoresisbasis and Hall effect can be predicted 108. Considering the above mechanism as well as the usual ferromagnetic anisotropy of resistivity, the resistivity in the demagnetized state r_0 can be written as,

$$\rho_0 = (\rho_1 \sin^2\theta + \rho_1 \cos^2\theta)(1 + \beta^2 \sin^2\theta)$$
 (2.45)

or

$$\rho_{o} - (\rho_{\perp} \sin^{2}\theta + \rho_{\parallel} \cos^{2}\theta) = \rho_{o} \beta^{2} \sin^{2}\theta$$

or

$$\beta^2 = \frac{\rho_0}{\rho_0 \sin^2 \theta} - \frac{(\rho_1 \sin^2 \theta + \rho_1) \cos^2 \theta}{\rho_0 \sin^2 \theta}$$

This can be simplified to give

$$\beta^2 = -\left[\frac{\Delta \rho_1}{\rho} + \frac{\Delta \rho_{11}}{\rho} \cot^2 \theta\right] \tag{2.46}$$

where $\Delta \rho_{\parallel \parallel}/\rho$ and $\Delta \rho_{\perp}/\rho$ are the longitudinal and transverse magnetoresistances respectively and Θ is the angle between the current and magnetization direction as defined in Sec. 2.2.3.

CHAPTER III

EXPERIMENTAL PROCEDURE

The measurements made in the present investigation are electrical resistivity at room temperature (300K), variation of electrical resistivity with temperature between 4.2 and 300K, magnetoresistance at 300K and liquid nitrogen temperature (77K) and Hall resistivity at 300' and 77K. The samples are in the form of thin ribbons, typically 1 mm wide and 30 μm thick and were manufactured by Allied Chemical Corporation, U.S.A.

3.1 CRYOSTAT DESIGN AND FABRICATION

The measurements of electrical and magnetic properties are relatively easy to make in comparison to thermal properties. Most of our measurements were between 77K and room temperature, so the problem of exchange of thermal energy with surroundings was less important.

A common cryostat was fabricated for the measurements of electrical resistivity, longitudinal and transverse magneto-resistances and Hall effect between 77K and room temperature. The sample holders for the electrical resistivity and transverse magnetoresistance, for longitudinal magnetoresistance and for Hall resistivity measurements were separately made and attached to the main tubing assembly [see Figs. 3.1 and 3.2] described later depending on the experiment.

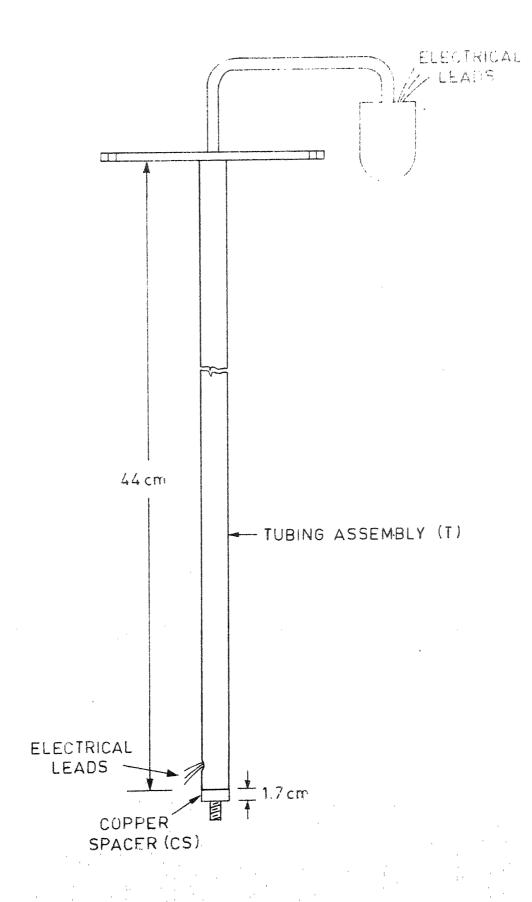
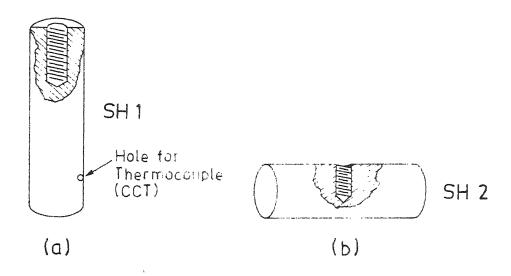


FIG. 3.1

For electrical resistivity and transverse magnetoresistance measurements, the sample holder (SH1) was made of a
(~ 5 cms) long cylindrical copper block. Around 0.5 cms
width of this copper block was machined to provide a plane
rectangular surface which provides a good thermal contact to
the specimen. A thin layer of araldite was coated on this
surface to insulate the specimen electrically from the copper
block. Arrangement was made to attach a copper-constantan
thermocouple (CCT) to this copper block for temperature
measurements between 77 and 300K. A hole along the axis of
the cylinder was machined for its attachment to the main
tubing system [see Fig. 3.2.a].

For longitudinal magnetoresistance measurements a similar cylindrical copper block (SH2) of ~ 3.5 cm length was used. All other arrangements were same except the fact that the hole for attaching sample holder to the main tubing system was made perpendicular to axis of the cylindrical block (Fig. 3.2.b).

A fibre glass reinforced plastic sample holder (SH3) was specially designed for the Hall effect measurements. As shown in Fig. 3.2.c the upper portion of this ~ 2 inch piece was filed to get a plain base for mounting the sample. Two copper strips were attached to this sample holder to provide pressure contacts for the current probes. Two other similar plastic



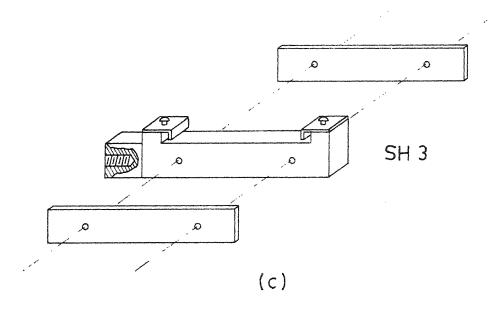


FIG. 3.2

pieces were used to hold the voltage probes against the sample by pressure. Arrangements were made to screw this sample holder to the main tubing system.

Depending on the experiment, the particular type of sample holder was attached to a thin walled non-magnetic stainless steel tube T (Fig. 3.1) of 3/8" diameter through a copper spacer (CS). The tail of this copper spacer has screw threads on it. This tube extends slightly beyond the top plate of the cryostat. The three current leads (2 for connecting to the specimen and 1 extra) with the thermocouple wires (CCT) and the four voltage leads (2 for connecting to the specimen and 2 extra) were put in two different plastic sleeves. These sleeves were taken out for the connection of the leads to the specimen through a hole made on one end of this tube T. The other end of this tube was vacuum sealed with black wax (manufactured by CENCO, USA). This assembly (the tubing system and the sample holder SH attached to it) is surrounded by a copper cryostat C of 4 cms diameter connecting the sample chamber to the vacuum line.

The electrical leads used in the sample holder assembly are of copper. The sample current leads are of 26 gauge which can carry a current upto 1 ampere. The voltage leads are multistrand 40 gauge copper wires. The electrical leads to the sample were soldered to the sample (wherever needed) with a low melting point Cerroseal-35 solder.

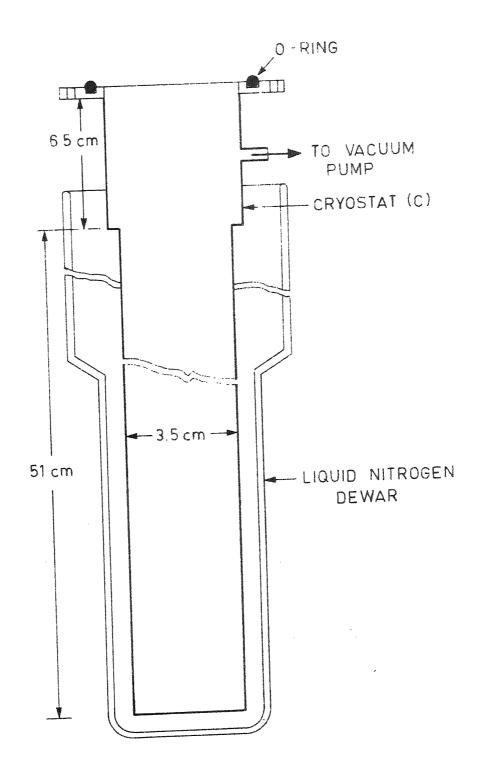
The top of the cryostat C is made of brass. A schematic diagram of the cryostat assembly, which fits into a liquid nitrogen dewar, is shown in Fig. 3.3.

3.2 MEASURING CIRCUIT

The detailed block diagram of the measuring circuit is shown in Fig. 3.4. This circuit can measure as small a voltage difference as 0.01 μV and voltage changes of 5 ppm could be detected in these samples. Care was taken to minimise electrical noise and thermal fluctuations in the system. In order to minimise the thermoelectric voltages, thin, long single wires, without any soldered joint, were used as voltage leads. These voltage leads were again directly connected to the voltage circuit, avoiding any soldering. The measuring circuit could be divided into two parts.

(a) Constant Current Circuit:

A constant current of 50 to 100 mA was drawn from a 500 mA/50 volts Model 6177C Hewlett Packard precision constant current source. The current stability was found to be better than 0.001%. In this circuit a Leeds and Northrup (L and N) standard resistance R (1 ϱ) and a L and N commutator was used, as shown in the circuit diagram. A digital multimeter was connected to read the voltage drop across the 1 ϱ 0 resistance and hence the current flowing through the sample. The current could also be measured by finding out the voltage



THE CRYOSTAT AND THE LIQUID NITROGEN DEWAR ASSEMBLY.

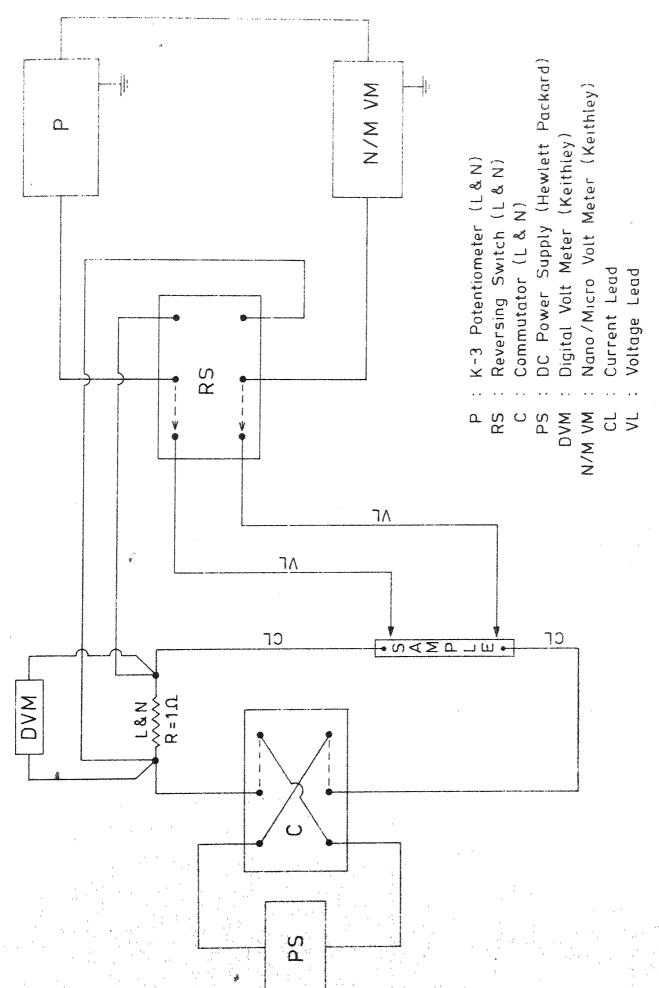
drop across R with the help of anL and N K-3 potentiometer and a model 148 Keithley nanovoltmeter (details given in the next paragraph). Using the reversing switch, we could reverse the current direction with the help of the commutator as shown in Fig. 3.4.

(b) Voltage Circuit:

The zero field voltage across the sample was measured by using a voltage compensation technique in the following manner. An L and N K-3 potentiometer which has a sensitivity of 0.5 microvolt was used as a standard voltage source. The voltage, V, due to the sample current, I, was compensated by adjusting the K-3 potentiometer, connected in series opposition. This resulting voltage was read on a model 148 Keithley Nanovoltmeter, which was used as a null detector. In this situation, the voltage read on the K-3 potentiometer was precisely the voltage drop, V, across the sample. To find out the current flowing through the sample the voltage drop across R = 1 Ohm was similarly found out. To minimise the fluctuations due to various pick-up voltages, proper care was taken to shield the wires in this circuit.

3.3 MEASUREMENT OF TEMPERATURE

The cryostat was evacuated with the help of a rotary pump. We could get a vacuum of ~ 100 micron, which was sufficient for our measurements between $77K \le T \le 300K$. The



BLOCK DIAGRAM OF THE MEASURING CIRCUIT

FIG. 3.4

copper-constantan thermocouple was used for the measurement of temperature in this range. The thermocouple voltage was read on an L and N millivolt potentiometer.

3.4 MEASUREMENT OF ABSOLUTE VALUES OF RESISTIVITY P AT 300K

The absolute value of resistivity, ρ , at room temperature (300K) was measured with the help of a Type 1608 A Impedance Bridge (General Radio, U.S.A.). The accuracy of this bridge is 0.1% when a resistance of 10 to 1 M0 was measured. Around 2 to 4 cm inlength of sample pieces were taken. These pieces were then weighed on a Model 2006MP6E Saratorius electronic balance which could weigh accurately upto 0.1 mg. Now the resistance of these very sample pieces were directly read on the impedance bridge. The density of these samples were taken from the data of Hasegawa and Ray 109. Thus, with the help of the knowledge of resistance of a sample of known length, weight and density, the resistivity could be calculated.

3.5 MEASUREMENT OF TEMPERATURE DEPENDENCE OF RESISTIVITY $\rho(T)$ (77K $\langle T \langle 300K \rangle$

The samples were cut to ~15 mm length for the measurement of temperature dependence of resistivity $\rho(T)$ between 77 and 3COK. As described in Section 3.1, the sample was mounted on the sample holder (SH1). The sample was free to expand on the sample holder. The current and voltage leads were soldered neatly on the sample with the special low-melting point soft solder (Cerroseal-35) to prevent excessive heating of the

sample. The flux used was zinc chloride. The large copper chunk which was used as the sample holder, also served the purpose of a heat-sink for the sample. The copper-constantan could measure the thermocouple adhered to this heat_sink temperature of the sample quite accurately. The thermocouple wires were directly connected to a Leeds and Northrup (L and N) millivolt potentiometer, which could read the temperature correct upto O.25K. The current and voltage lead connections were now made as shown in Fig. 3.4. The cryostat was evacuated (\sim 100 micron) and then the system was ready for measurement. A sample current of ~ 100 mA was passed through the sample. At room temperature (300K) the sample voltage (\sim 100 mV) was compensated by adjusting a L and N K-3 potentiometer (see Sec. 3.2), put in series opposition and using a digital voltmeter (Keithley Model 174, sensitivity O.1 μV) as a null detector. Now the liquid nitrogen was transferred to the dewar, surrounding the cryostat. As the sample was cooled the change in resistivity was directly read on the digital voltmeter and the corresponding thermocouple voltage was simultaneously recorded from the millivolt potentiometer. The heating data were also taken in a similar manner. In the present set up a resistance change of a few parts in 10^6 could be detected. The dimension measurements were unnecessary because finally the ratio of resistivity ρ_{T} at a particular temperature T and the resistivity at room temperature ρ_{RT} , i.e., ρ_{T} / ρ_{RT} was plotted against temperature.

3.6 MAGNETORESISTANCE MEASUREMENT

The ferromagnetic anisotropy of resistivity (FAR) at 300 and 77K were measured by the usual four probe d.c. method. For transverse magnetoresistance measurements the sample was mounted on the sample solder SH1 and for the longitudinal measurement The 2 current and 2 voltage probes were it was mounted on SH2. soft soldered to the sample. The usual current and voltage lead connections were made as given in Sec. 3.2. The whole system was now kept in a magnetic field. The magnet used in the present study was a Varian 15" electromagnet, fed by a VFR-2703 highly stable power supply. This gives a magnetic field 18 ~ 20 kG. For both the transverse and longitudinal measurements the orientation was such that the field applied (H_{ext}) was parallel to the ribbon plane. The reason for keeping such an orientation is to minimise the effect of the demagnetizing field (see Appendix 2). Another point which was taken care of was the alignment of the sample with respect to the magnetic field. This plays an important role at low fields. If the sample is misaligned, the transverse magnetoresistance at low fields showed a positive value, as observed by many other workers 75,77,110 (see discussion in Chap. V). Keeping all these points in mind, the sample was mounted in such a way that it was lying exactly parallel to the cylindrical axis of the sample holder (SH1). In this way, when the system was mounted inside the magnet pole-pieces in the proper orientation

 $(H_{\rm ext}$ parallel to ribbon plane) and a current was passed along its length, the right alignment condition (current I perpendicular to $H_{\rm ext}$ and $H_{\rm ext}$ lying in the ribbon plane)was automatically satisfied.

A current of ~ 50 mA was then passed through the sample (except for ${\rm Fe_{87}B_{13}}$, which was very thin, lower current ~ 10 mA was used to avoid the fluctuations due to excessive heating of the sample). The zero field voltage was compensated by the K-3 potentiometer and then the small change in voltage due to magnetic field was directly read on a nanovoltmeter, as stated earlier.

For measurements at 77K, as described in Sec. 3.2 and Sec. 3.3, the system was evacuated and kept in a dewar containing liquid nitrogen. When the system reached this liquid nitrogen temperature (77 K), similar measurements, as stated above, were repeated.

In this measurement, the system could detect changes of resistivity of about a few parts per million.

3.7 HALL EFFECT MEASUREMENTS

The sample was mounted on the sample holder (SH3). The current leads were soldered to the copper strips used as the pressure contact probes for this sample holder. Because of the irregularity of the width of these samples, it was very

cifficult to use pressure contact for both the Hall voltage probes. Also, the samples being very thin were forming a ridge if the pressure was applied from both sides, across the width of the sample. So, one of the voltage probes was soft-soldered and a pressure contact was used for the other to minimise the misalignment voltage. Now, this sample holder, enclosed in a cryostat was placed in the electromagnet, in such a way that the applied field, $H_{\rm ext}$, was perpendicular to the sample plane. This orientation of the sample was necessary to get the Hall voltage along the width of the sample. Also, in this orientation, the magnetic induction inside the sample, $H_{\rm ext}$, $H_{\rm ext$

$$B_{in} = H_{in} + M_s$$
,

where M is the saturation magnetization and H is the internal field. Or.

$$B_{in} = (H_{ext} - \alpha M_s) + M_s$$

where α is the demagnetizing factor. Or,

$$B_{in} = H_{ext} + M_{s}(1-\alpha) .$$

In this particular orientation used for this measurement $\alpha \simeq 1$. Hence,

Now, for Hall measurements, we did not use the K-3 potentiometer shown in Fig. 3.4. Instead, the Nanovoltmeter was directly connected to the reversing switch. potentiometer was not needed because the Hall voltages for these samples were quite large, as compared to the changes due to magnetoresistance at higher fields. In zero field if the Hall contacts are not aligned perfectly so as to coincide with the opposite ends of the same equipotential line, an ohmic voltage drop proportional to the sample current will be measured. So, the misalignment voltage was first minimised by sliding one of the voltage probes slightly along the length, by trial and error. Then, the effect of the remaining spurious ohmic drop was eliminated by making the Hall voltage measurements under the reversal of magnetic field. Also, the sample current was reversed to eliminate spurious thermal voltages. The actual Hall voltage obtained then is,

$$V_{H} = 1/4[V(H_{+},I_{+})+V(H_{-},I_{-})-V(H_{+},I_{-})-V(H_{-},I_{+})]$$

It is evident that the ohmic drop will be eliminated by this procedure, since the Hall voltage changes sign if either current or field is reversed, while the ohmic drop changes sign only when current is reversed.

The Hall measurements were repeated on the same sample several times and the sample to sample variation was also checked. Within experimental error, these data were found to be

quite reproducible. Finally, for Hall resistivity ρ_H (= $\frac{V_H t}{I}$, where t is the thickness of the samples and I is the current flowing through the sample), the thickness of the samples were measured with the help of a micrometer (least-count = 0.0001 inch).

For the measurements at low temperatures (77 K) the cryostat was evacuated and surrounded by a liquid nitrogen dewar. Similar measurements were repeated when the desired temperature was attained and the system was stable.

3. 8 MGASUREMENT OF RESISTIVITY BETWEEN 4.2 K and 77 K

We measured the variation of resistivity with temperature between 4.2 and 77 K at the Tata Institute of Fundamental Research, Bombay, using their experimental facility. The experimental procedure could be summarised as follows:

(a) The cryostat used in the present measurement was inserted to a liquid helium dewar and this in turn to a liquid nitrogen dewar. The latter provides a thermal shielding to the liquid helium. On the top of the cryostat provision was made for (i) transferring liquid helium (ii) inserting the sample chamber and (iii) recovery of the gas and pumping of the vapour to go below 4.2 K.

- (b) The sample chamber was a double-walled system. Arrangements were made to flow exchange gas in the space between
 the outer tube and the outer wall of the inner tube and
 also to pump this gas out. The sample chamber could be
 evacuated down to 1 micron with the help of a suitable
 mechanical pump.
- (c) The sample holder was made of a rectangular copper strip
 (~5 cms in length). A manganin heater wire was wound
 at the lower part of this sample holder. A precalibrated
 silicon diode sensor (Lake Shore Cryotronics, USA) was
 encapsulated in the sample holder. The merit of this
 sensor is that it can scan a very wide range of temperature,
 from 1.5 to 300K.
- (d) The samples, in the form of thin long ribbons, were mounted on the sample holder. The current and voltage leads were soldered first by using Cd-Sn (Cd-70%, Sn30%) solder. This solder has a melting point ~150°C and is nonsuperconducting down to 3.5K (flux used was ZnCl₂). A scattering of data points near the liquid helium temperature was observed when the sample was soldered with the help of this solder. To avoid this problem around 4.2K (probably due to the superconductivity of the solder material) another soldering material Bi-Cd (60% Bi,40% Cd) was used (flux used for this was also ZnCl₂) in the next set of measurements. This solder has a lower melting point ~140°C and is nonsuperconducting down to 0.8K.

The measuring circuit was principally similar to the one described in Sec. 3.3.2. A Hewlett-Packard 250 mA power supply was used as a constant current source and the voltages at particular temperatures were read directly on a Keithley digital Nanovoltmeter. To control the temperature of the sample, a Lake Shore Cryotronics temperature controller was used and the voltage corresponding to the temperature was read directly on a 5.5 digit voltmeter of Datron Instruments, U.K.

CHAPTER IV

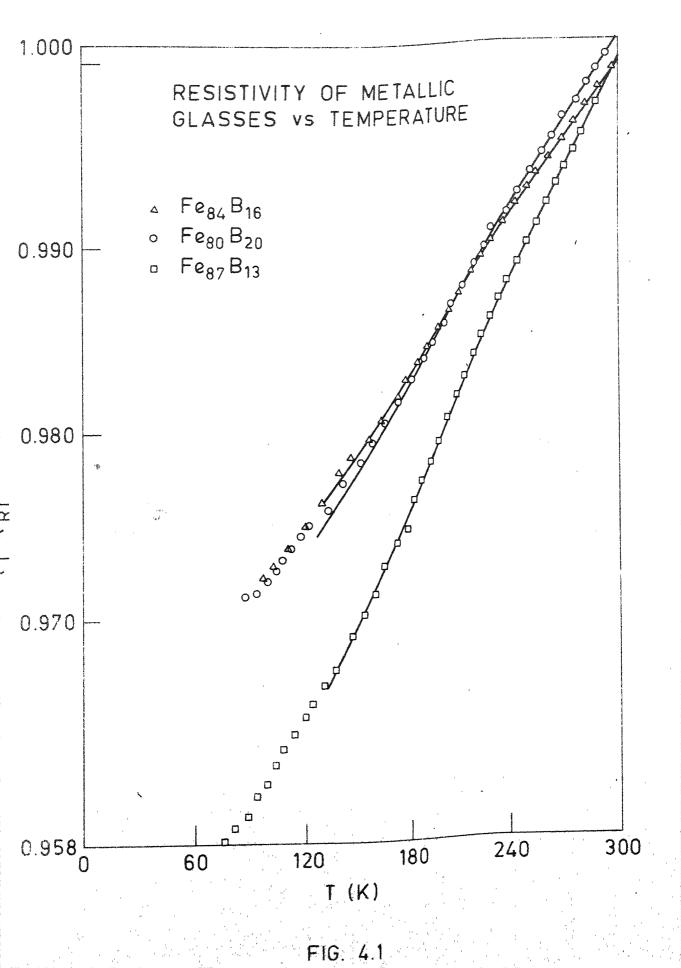
EXPERIMENTAL RESULTS

The present study comprises of the measurements of :

- i) Variation of electrical resistivity ρ with temperature T in two metallic glass series (a) $\mathrm{Fe_{100-x}}^B{_x}$ (13 \leq x \leq 26), and (b) $\mathrm{Fe_{80}}^B{_{20-x}}^S{_i}{_x}$ (o \leq x \leq 12),
- ii) Variation of electrical resistivity ρ with concentration x in Fe_{100-x}B_x series,
- iii) Variation of ferromagnetic anisotropy of resistivity (FAR) with concentration x in $Fe_{100-x}B_x$ series, and,
- iv) Concentration (x) dependence of spontaneous Hall constant R_s in $Fe_{100-x}E_x$ series.
- All these measurements, except the resistivity variation with T in Fe-B-Si series, were made in the temperature range of 77 to 300K. The ternary series was studied in the temperature range of 4.2 to 300K.

4.1 VARIATION OF RESISTIVITY WITH TEMPERATURE

The general behaviour of electrical resistivity as a function of temperature is the same in all the samples. In Fig. 4.1 we have plotted the ratio of resistivity at any temperature T and that at room temperature, $\rho_{\rm T}/\rho_{\rm RT}$, against T in the temperature range 80K \leq T \leq 300K for the samples in



Fe $_{100-x}$ B $_x$ series. The plots of ρ_T/ρ_{RT} against T in the temperature range 4.2K \leq T \leq 300K for some of the Fe $_{80}{}^{\rm B}$ 20- $_{\rm x}{}^{\rm Si}$ $_{\rm x}$ samples are shown in Fig. 4.2. It is clear from these figures that the resistivity varies linearly in the temperature range 150K < T < 300K, below about 150K there is a departure from linearity. In both the heating and the cooling cycles measurements were repeated at least 2-3 times for each sample. Different pieces of the same composition were also measured in a few cases to check for the inaccuracy arising from sample to sample variation. The temperature coefficient of resistivity α (the high temperature slope of the $\rho_{\rm T}/\rho_{\rm RT}$ vs T graph) is positive over the entire range of x and is reproducible within the error limits. The percentage change of resistivity $\Delta \rho / \rho$ can be found out directly from the $\rho_{\rm T}/\rho_{\rm RT}$ versus T plots. Fig. 4.3 shows the quadratic behaviour of resistivity at low temperatures (80K \leq T \leq 150K) for all the Fe $_{100-x}$ B $_x$ samples. Similarly, Fig. 4.4 shows the $ho_{
m T}/
ho_{
m RT}$ versus T 2 plot for all the seven samples in $Fe_{80}B_{20-x}Si_x$ samples in the temperature range $COK \leq T \leq 105K$.

In Table 4.1, we have listed the composition, crystallization temperature $T_{\rm cr}$, the percentage change of resistivity $\Delta\rho/\rho$ in the temperature range 80K \leq T \leq 300K, α and Debye temperature $\Theta_{\rm D}$ for all the ${\rm Fe}_{100-x}{\rm B}_x$ (13 \leq x \leq 26) alloys. The large error in $\Theta_{\rm D}$ is introduced because of the uncertainty in the determination of the slope S of $\rho_{\rm T}/\rho_{\rm RT}$ vs T² plots in this

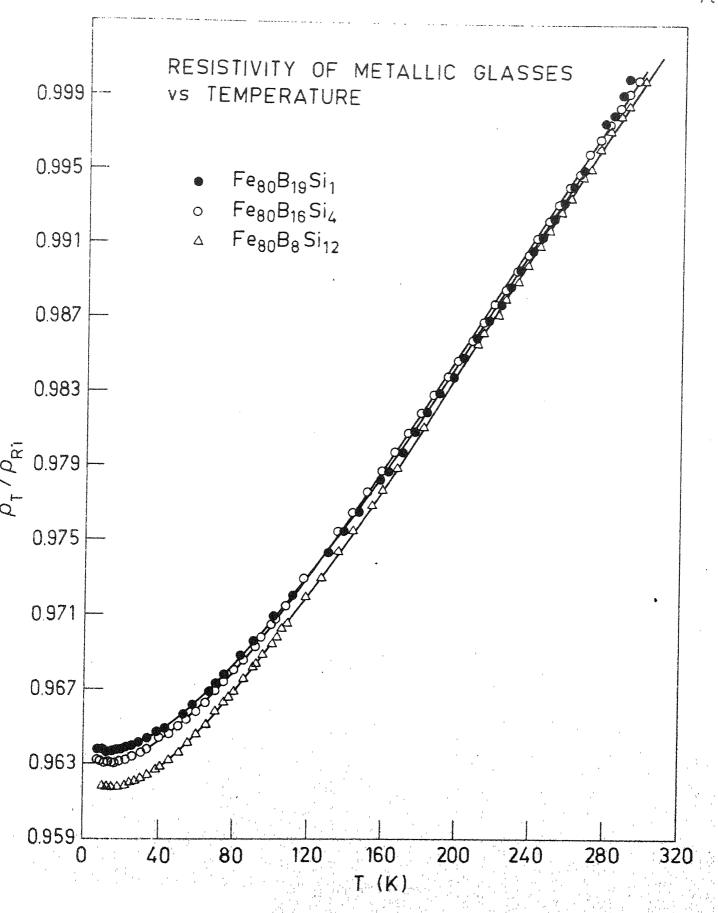


FIG. 4.2

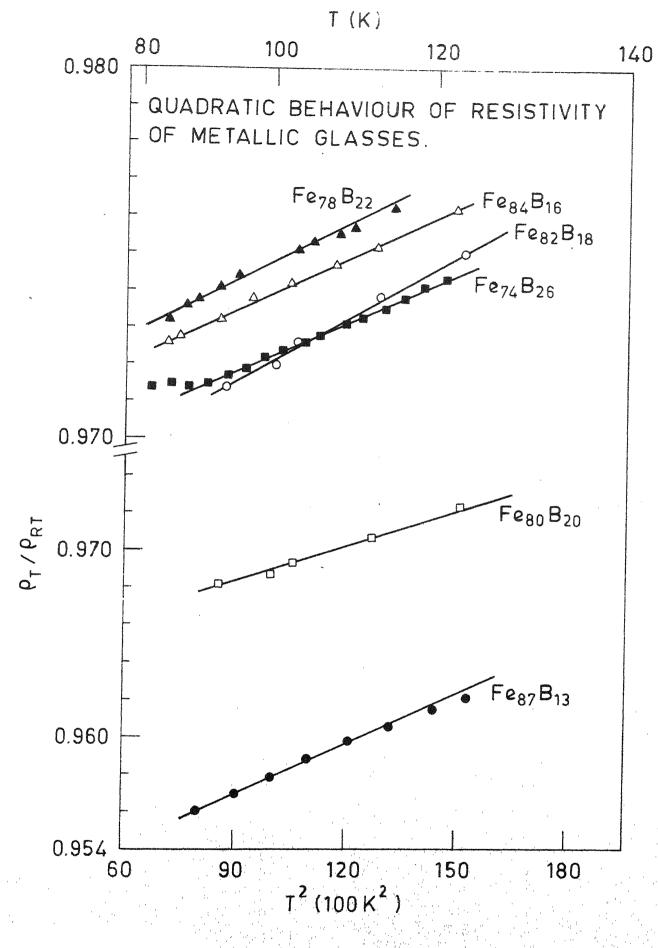
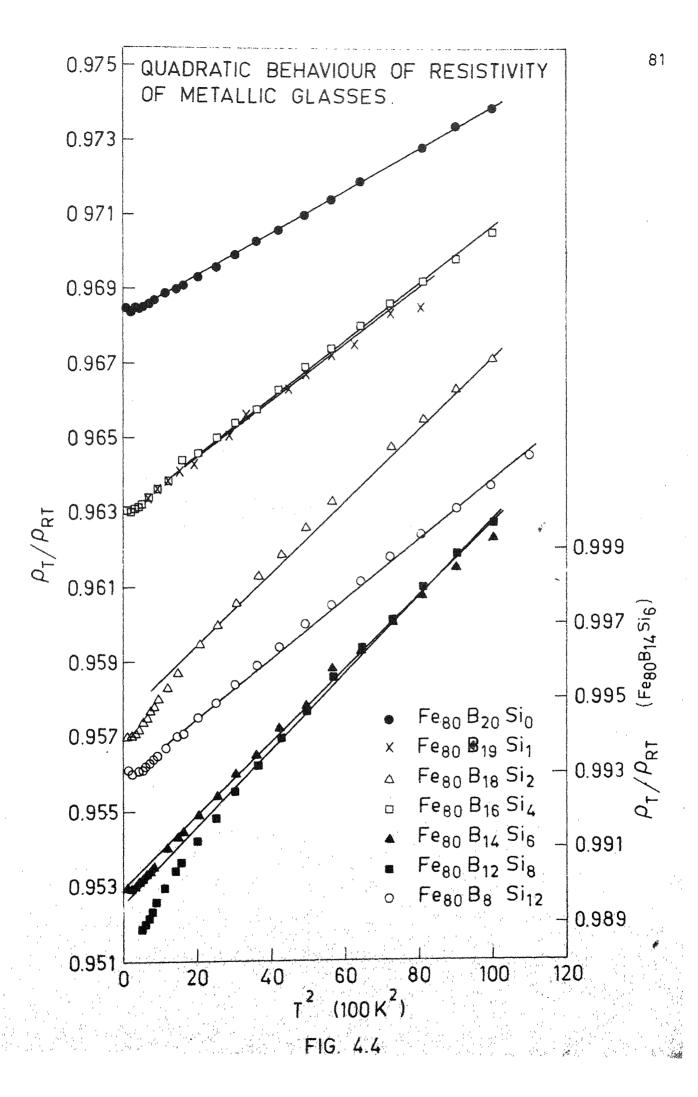


FIG. 4.3



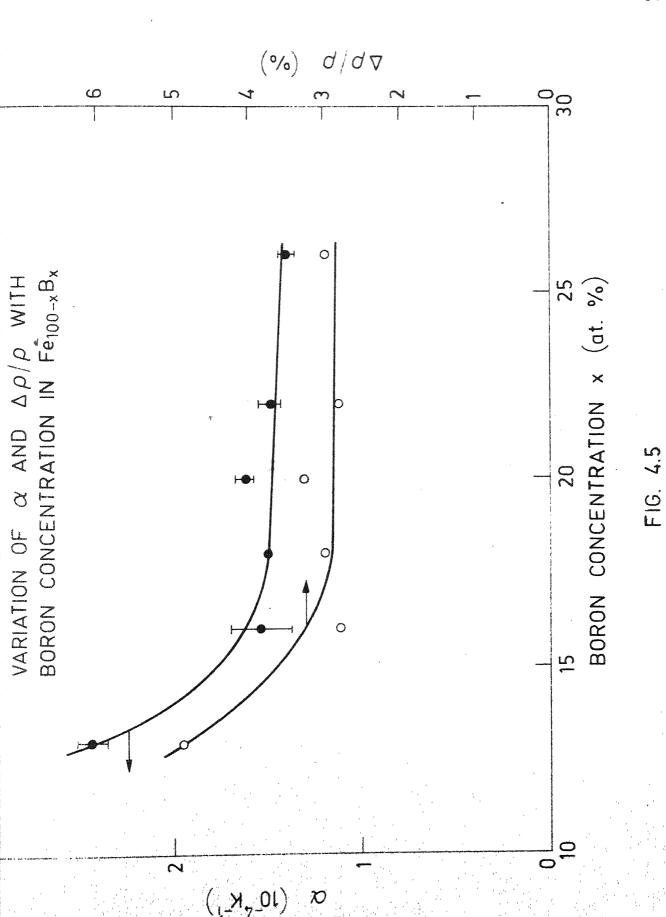
temperature range, as discussed in the next chapter. Table 4.2 gives the composition, $\Delta\rho/\rho$ in the temperature range $4.2\mathrm{K} \leq T \leq 300\mathrm{K}$, α and θ_D for all the $\mathrm{Fe_{80}B_{20-x}Si_x}$ (o \leq x \leq 12) samples. As can be noticed from these tables, the error in the θ_D values in $\mathrm{Fe_{80}B_{20-x}Si_x}$ series is much less than that in the $\mathrm{Fe_{100-x}B_x}$ series.

In Fig. 4.5, we have shown the boron concentration (x) dependence of α , $\Delta 9/\rho$ in the Fe-B series. Fig. 4.6 similarly shows the dependence of α and $\Delta 9/\rho$ on the silicon concentration x in Fe₈₀B_{20-x}Si_x series. In Fe_{100-x}B_x both α and $\Delta \rho/\rho$ versus x plots show an abrupt fall in going from x = 13 to x = 16 and then they are more or less independent of x for $16 \le x \le 26$. About Fe₈₀B_{20-x}Si_x series one can say that the α value does not change appreciably by replacing one metalloid by another and $\Delta \rho/\rho$ increases first from x = 0 to x = 1 and then remains constant in the range (1 $\le x \le 12$).

Figs. 4.7 and 4.8 show the variation of $\Theta_{\rm D}$ with concentration x in ${\rm Fe_{100-x}B_x}$ (13 \leq x \leq 26) and ${\rm Fe_{80}B_{20-x}\dot{S}i_x}$ (0 \leq x \leq 12) spries respectively.

4.2 VARIATION OF RESISTIVITY WITH CONCENTRATION x in Fe 100- x^Bx

In Fig. 4.9 we have plotted the absolute value of resistivity ρ at 300K against x, the boron concentration, for $\text{Fe}_{100-x} \text{B}_{x} \ (13 \leq x \leq 26) \text{ series.}$ It is clear from this figure



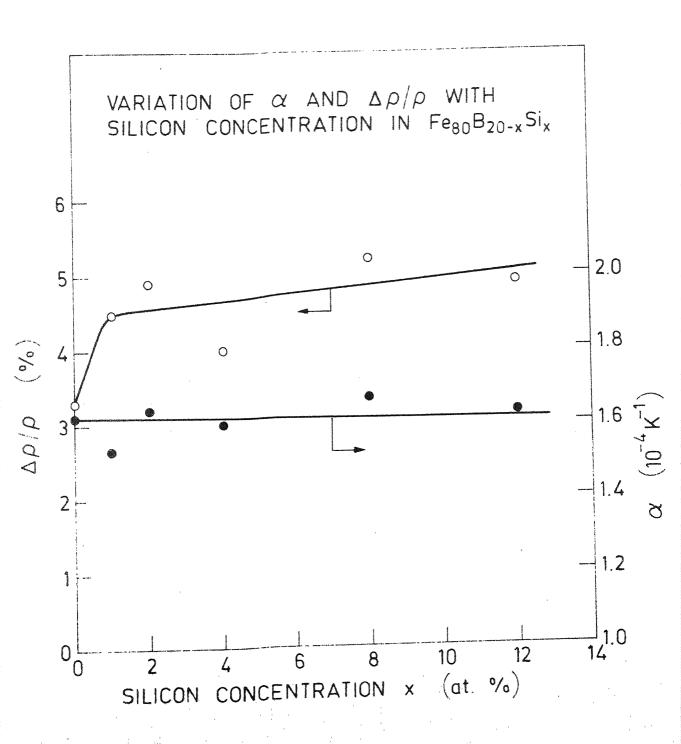
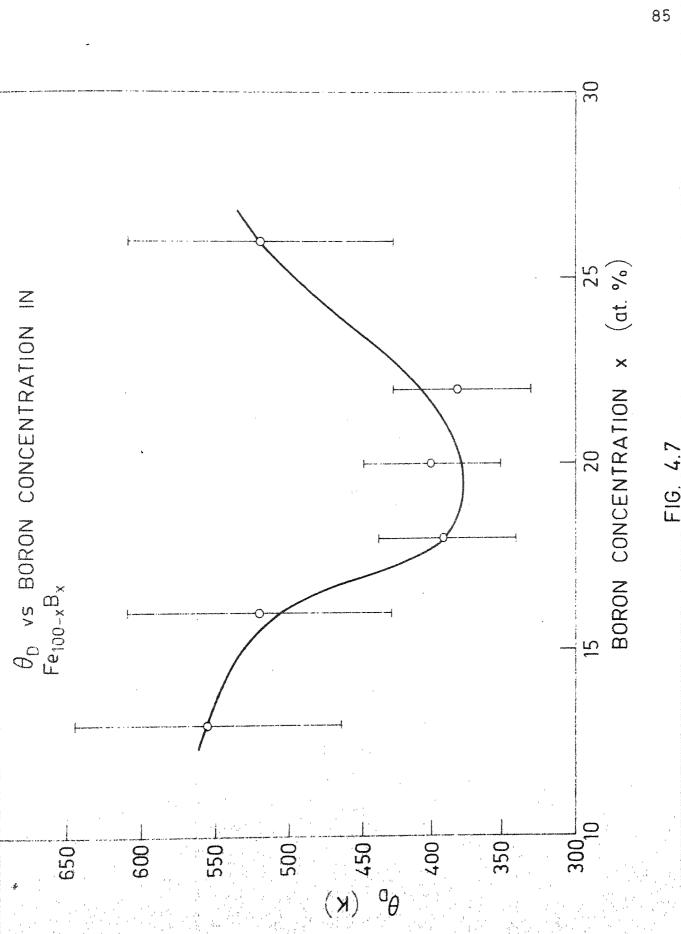


FIG. 4.6



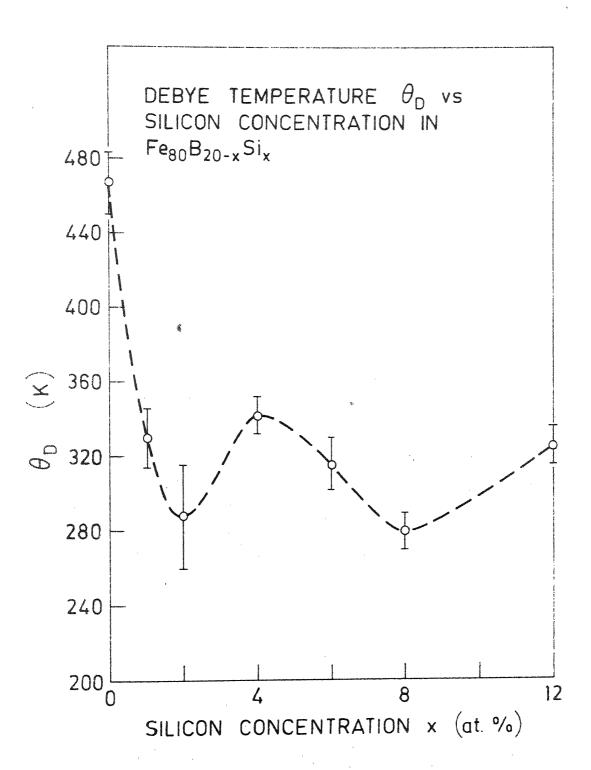


FIG. 4.8

Table 4.1 $\mbox{Values of $T_{\rm cr}$, $\Delta\rho/\rho$, α and $\theta_{\rm D}$ in ${\rm Fe}_{100-x}{\rm B}_x$ (13 $\le x \le 26$) } \\ \mbox{series in the temperature range } 80K $\le T \le 300K$

Composition	T _{cr} (K)	Δ ρ/ ρ (%)	$\alpha(10^{-4}K^{-1})$	⊖ _D (K)
Fe ₈₇ B ₁₃	586	4.9	2.43 ± 0.07	555 <u>+</u> 90
^{Fe} 84 ^B 16	643	2.8	1.53 ± 0.15	520 <u>+</u> 90
Fe ₈₂ B ₁₈	660	3.0	1.49 ± 0.01	390 ± 50
Fe ₈₀ B ₂₀	660	3.3	1.62 ± 0.04	400 ± 50
Fe ₇₈ B ₂₂	666	2.8	1.49 + 0.06	380 <u>+</u> 50
Fe ₇₄ B ₂₆	688	3.0	1.40 ± 0.04	520 ± 90

Table 4.2 $Values~of~\Delta\rho/\rho~,~\alpha~and~~\partial_D~in~Fe_{80}{}^B{}_{20-x}Si_x~(o\le x\le 12)$ series in the temperature range 4.2K $\le T\le 300K$

Composition	Δρ/ρ (%)	α(10 ⁻⁴ K ⁻¹)	θ _D (K)
Fe ₈₀ B ₂₀	3 . 3	1.62 ± 0.04	467 <u>+</u> 17
Fe ₈₀ B ₁₉ Si ₁	4.5	1.53 ± 0.02	330.8 ± 16
Fe _{8C} B ₁₈ Si ₂	4.9	1.64 + 0.04	284 <u>+</u> 28
Fe ₈₀ B ₁₆ Si ₄	4.0	1.60 ± 0.02	341.5 <u>+</u> 10
Fe ₃₀ B ₁₄ Si ₆		1.84 ± 0.02	315 <u>+</u> 14
Fe _{8C} E ₁₂ Si ₈	5.2	1.665 ± 0.02	280 <u>+</u> 10
Fe ₈₀ B ₈ Si ₁₂	4.9	1.625 + 0.02	326 <u>+</u> 10

that the experimental data show an increase of ρ with increasing boron content. As mentioned in Sec. 3.4, the accuracy with which the absolute value of resistance was measured is quite high. In fact, repeated measurements on the same piece and also on different pieces of the same sample, showed similar values within the experimental error limits. The main error of $3\% \sim 15\%$ in the determination of absolute value of resistivity was introduced from the inaccuracy involved in the measurements of the length and weight of the samples. The details of these measurements (including the percentage error introduced by each measurement) with the error limits are tabulated in Table 4.3. We have also estimated the values of resistivity of each sample theoretically with the help of eqn. (2.15) and this will be discussed later in Chapter V.

Fig. 4.9 shows the plot of the theoretical values of ρ and a function of boron concentration x. The monotonic increase in the absolute value of the resistivity with increasing metalloid concentration is clearly reflected in the theoretical curve.

4.3 MAGNITORESISTANCE MEASUREMENTS IN Fe 100-x Bx

In Fig. 4.10 we have shown some typical results of our magnetoresistance measurements. In ferromagnetic pure metals and dilute alloys around 4K the ferromagnetic anisotropy of resistivity is generally masked by the so-called normal positive

Sample	Resistance, R(Ω)	Weight, M(10 ⁻³ g)	Density, D(g/cm ³)	Length, p L(cms)	(10 ⁻⁶ Ω m)
^{Fe} 87 ^B 13	4.278	4.15 <u>+</u> 0.04	7.44	4.285 <u>+</u> 0.1	1.3+0.04
Fe _{,84} B ₁₆	3.727	4.45+0.22	7.43	3.92 4 <u>+</u> 0.1	1.45+0.12
^{Fe} 82 ^B 18	1.663	15.68+0.31	7.42	4.468+0.09	1.74+0.07
Fe ₃₀ B ₂₀	2.032	7.57 <u>+</u> 0.05	7.40	3.790+0.10	1.45 <u>+</u> 0.04
Fe ₇₈ B ₂₂	3.700	4.7 +0.20	7.30	3.43 <u>+</u> 0.10	2.03+0.14
Fe ₇₄ B ₂₆	3.089	2 . 95 <u>+</u> 0.30	7.16	2.42 <u>+</u> 0.10	2.07+0.31
			•		•

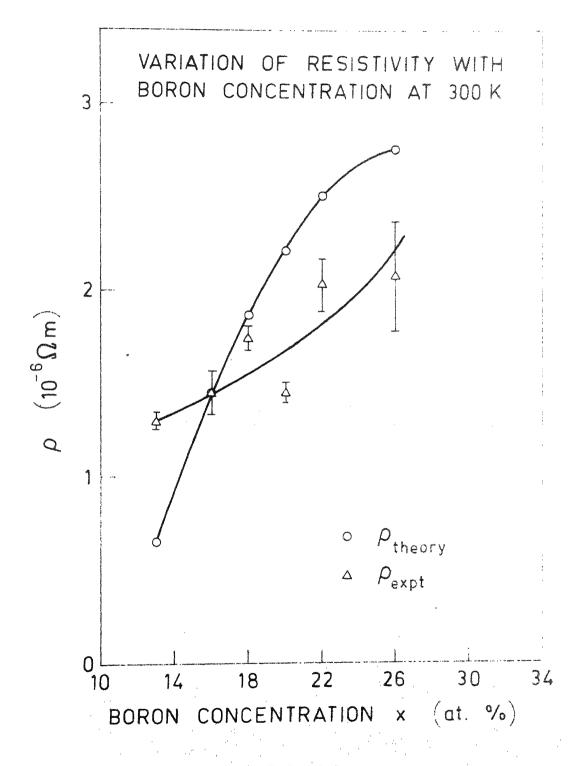


FIG. 4.9

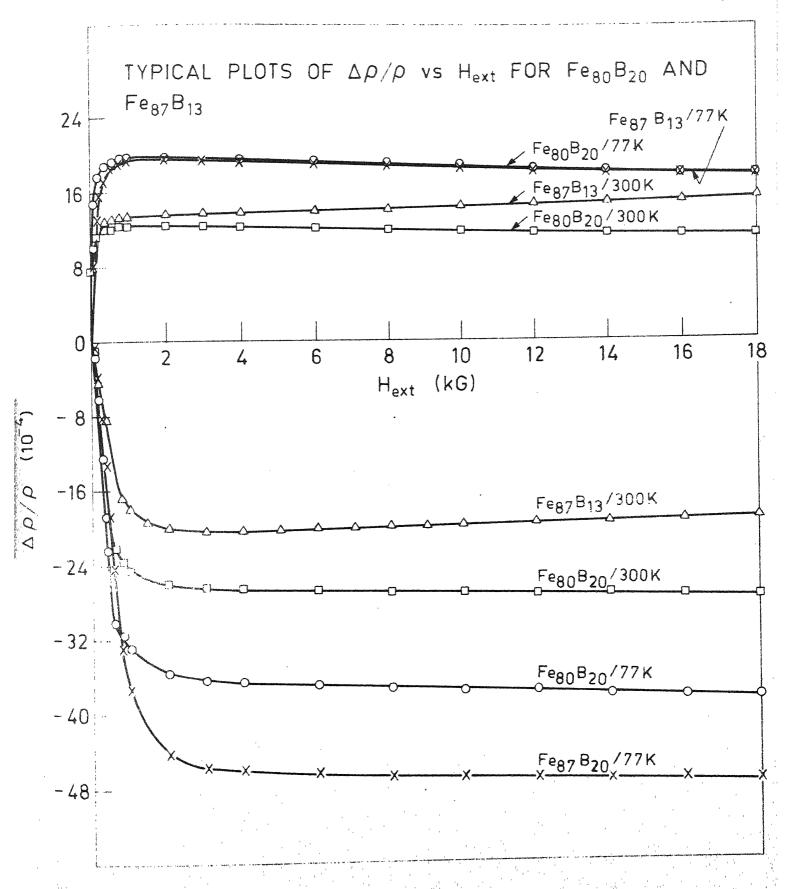


FIG. 4.10

magnetoresistance (due to the Lorentz force acting on the conduction electrons) 102 . Thus, for concentrated alloys the most convenient temperature range for studying ferromagnetic anisotropy is above 77K where it can be assumed that the normal magnetoresistance will not play a dominant role. Here, in this study we have measured the longitudinal and transverse magnetoresistance of $\mathrm{Fe_{100-X}}_{\mathrm{X}}$ series (13 \leq x \leq 26) at room temperature (300K) and at liquid nitrogen temperature (77K). At low fields, the longitudinal magnetoresistances, $\Delta\rho_{11}/\rho$, are all positive and rise rather fast with increasing field, whereas the transverse ones, $\Delta\rho_{1}/\rho$ (in magnitude always larger than $\Delta\rho_{11}/\rho$) are all negative and drop much more slowly with increasing field. This behaviour of $\Delta\rho/\rho$ versus H_{ext} plots at low fields is very similar to that of crystalline ferromagnets with usual domain structures.

The errors in the measurements of the magnetoresistance are generally introduced through instability of the current, thermal noise, unregulated magnetic field, geometrical non-uniformity of the samples, etc. Fortunately, the factor which finally matters is a ratio, $\Delta\rho/\rho$ (= $\Delta V/V$) (defined in Chapter II) and hence any error due to the non-uniformity of the samples is cancelled. Since in the final values of $\Delta V/V$, the total voltage V was much higher (~100 mV) than the fluctuations in the measurement of ΔV (~0.1 μV), the uncertainty in the results varied between 1 ppm and 6 ppm for the whole series.

4.3.1 Ferromagnetic Anisotropy of Resistivity

Though qualitatively the variations of magnetoresistance with external field for amorphous and crystalline ferromagnets are quite similar, the ferromagnetic anisotropy of resistivity, i.e., FAR values of amorphous ferromagnets are much smaller than those of their crystalline counterparts. The values of longitudinal and transverse magnetoresistances $\Delta \rho_{11}/\rho$, $\Delta \rho_{1}/\rho$, $(\rho_{11}-\rho_{1})$ and FAR for all the samples at 300 and 77K are given in Table 4.4. FAR vs x plots at room temperature and 77K are shown in Fig. 4.11. At room temperature this plot shows a broad maximum at x = 16. This maximum, still at x = 16, becomes more prominent at 77K. The FAR values for all the samples in this Fe-B series are positive and range between 0.2% and 0.4% at 300K and 0.3% and 0.7% at 77K. Fig. 4.11 also shows the variation of the anisotropic magnetoresistance $(\rho_{11}-\rho_{1})$ with boron concentration x.

4.3.2 Variation of $\frac{1}{6} \frac{\partial P}{\partial H}$ with Boron Concentration x

The high field slopes of the magnetoresistance vs H plots are calculated from Fig. 4.10. These values for longitudinal and transverse magnetoresistances at 300 and 77K are all tabulated in Table 4.5. The values of $(\frac{1}{\rho}, \frac{\partial \rho}{\partial H})_{11}$ and $(\frac{1}{\rho}, \frac{\partial \rho}{\partial H})_{11}$ are quite close to each other and hence the average values of $(\frac{1}{\rho}, \frac{\partial \rho}{\partial H})_{11}$ at 300K and 77K against the boron concentration x are plotted in Fig. 4.12. The above mentioned table and the figure clearly show that $(\frac{1}{\rho}, \frac{\partial \rho}{\partial H})_{11}$ values at 77K are all negative and

Values of $\Delta \rho_{11}/\rho$, $\Delta \rho_{11}/\rho$, $(\rho_{11}-\rho_{11})$ and FAR at 300K and 77K for Fe $_{100-x^Bx}$ series (13 $\le x \le 26$)

1 dole 4.4

Samples	$\Delta \rho_{11}/\rho(10^{-4})$	$\Delta \rho_{11}/\rho(10^{-4}) \Delta \rho_{1}/\rho(10^{-4})$	1	$\rho_{11} - \rho_{1}(10^{-10})$	$FAR(\chi) \rho_{11} - \rho_{1}(10^{-10} \Omega m) \Delta \rho_{11}/\rho(10^{-4}) \Delta \rho_{1}/\rho(10^{-4})$) $\Delta \rho_{\gamma}/\rho(10^{-4})$	FAR
	skriniski vydykosky metrokoski vydy od poslednik sejem, skrinisky sejem od poslednik sejemelik seje	a i delicità del della compania della compania della compania della compania della compania della compania del	AND STREET STREET, STATE OF STREET, STATE STATE STREET, STATE STATE STREET, STATE STAT		明明的,这是不明明,他也是这个人,也不是是一种,这是一种,这是不是一种的时间	ender Service of the service of the	
$Fe_{87}B_{13}$	13.2	-20.8	0.34	40.2	. 19•6	-46.2	. 0.6
Fe84 ^B 16	18.2	-24.6	0.43	62.1	31.0	-43.0	0.7
Fe ₈₂ B ₁₈	13.9	-28.4	0.42	73.5	22.6	-44.7	0.6
$^{\mathrm{Fe}_{80}^{\mathrm{B}_{20}}}$	12,3	-26.3	0.39	56.0	19.9	-36.1	0.56
$Fe_{78}B_{22}$	11,2	-23.5	0,35	70,4	15.2	-31.2	0.46
Fe74 ^B 26	5,5	-18.6	0.24	49.8	7.5	-20.6	0.28
) •

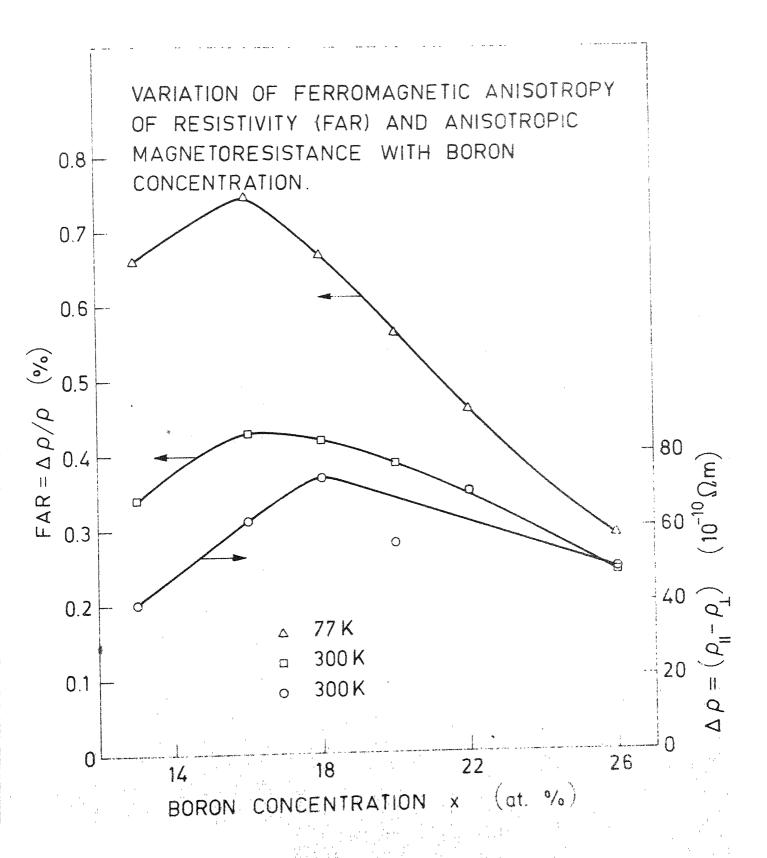


FIG. 4.11

Table 4.5

High-field slopes of magnetoresistance plots at 300K and 77K in Fe $_{\rm 10C-x}{\rm B_x}$ (13 \le x \le 26) series

	300 K			XXX	¥	
×	$\frac{1}{p} \frac{\partial^{2} I I}{\partial H} (10^{-4} I^{-1}) \frac{1}{2} \frac{\partial^{2} L}{\partial H} $	-	$\frac{3p}{3H}(10^{-4}T^{-1}) \frac{1}{p} \frac{3}{2}$	$(0^{-4}r^{-1})^{\frac{1}{\rho}} \frac{\partial \rho}{\partial H} (10^{-4}r^{-1})^{\frac{1}{\rho}} \frac{\partial^{\beta}}{\partial H} (10^{-4}r^{-1})^{\frac{1}{\rho}} \frac{\partial \rho}{\partial H} (10^{-4}r^{-1})^{\frac{1}{\rho}} \frac{\partial \rho}{\partial H} (10^{-4}r^{-1})^{\frac{1}{\rho}} \frac{\partial \rho}{\partial H} (10^{-4}r^{-1})^{\frac{1}{\rho}}$	⁰ 1.(10 ⁻⁴ 1 ⁻¹)	$\begin{pmatrix} 1 & 0 & \rho \\ \rho & \delta H \\ 10^{-4} T^{-1} \end{pmatrix}$
13	1,25	0.91	1,08	-1.1	-0.88	56 [•] 0-
16	-0.5	-0.83	-0.67	1.9	-2.00	-1.95
18	-0.63	-0.95	-0.75	-1,3	-1.55	-1.43
20	09.0-	-0.70	-0.65	-1.25	-1,30	-1.28
22	ī.	9.0-	09.0-	1	09.0-	09.0-
26	-0.50	-0.25	.0.38	-0.50	-0.13	-0.32
	•					
bereignistele supering states	Andrea (1904) - 1904 - 1904 - 1904 - 1904 - 1904 - 1904 - 1904 - 1904 - 1904 - 1904 - 1904 - 1904 - 1904 - 190	《《《《《································	- 7、1、10.12年,以後77.2年。 157.7 号: 159.7 号:158.7 号	· · · · · · · · · · · · · · · · · · ·		the sign of state of the sign of the state of the

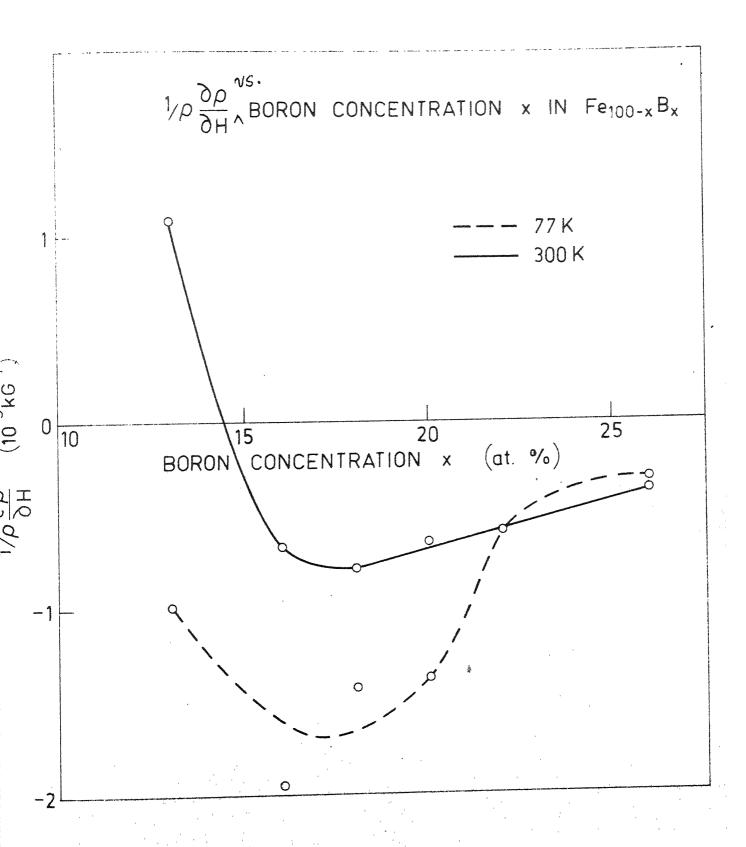


FIG. 4 12

Table 4.6

The values of 0, the angle between current and magnetization (from magnetoresistance measurements) and β , the tangent of the Hall angle (from Hall effect and resistivity measurements) of Fe_{100-x}^Bx (13 \leq x \leq 26) samples

Samples	$\beta = \tan$	$\mathcal{D}_{H} = \rho_{H}/\rho (10^{-2})$	
Fe87 ^B 13		3.86	38.9 ⁰
Fe ₈₄ B ₁₆		3.65	40.70
Fe ₈₂ 3 ₁₈		4.11	34.9°
Fe ₈₀ B ₂₀		3.81	34.4°
Fe ₇₈ B ₂₂		1.42	34.6°
Fe ₇₄ B ₂₆		1.70	28.6°

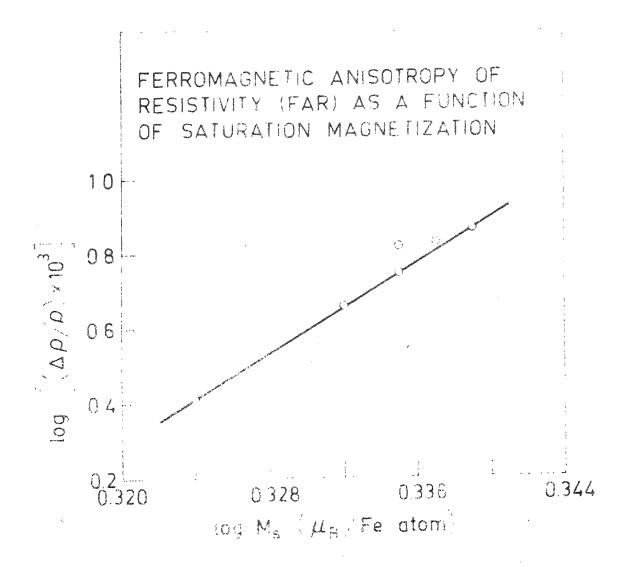


FIG 4.13

4.4 HALL EFFECT

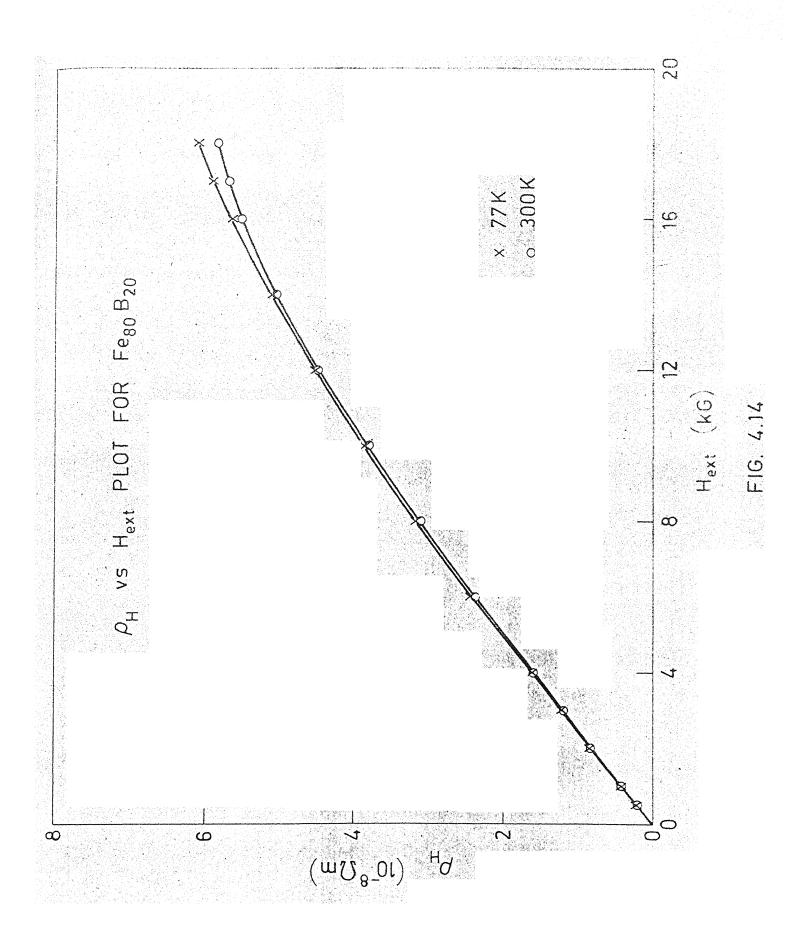
A typical plot of the Hall effect measurements, i.e., the Hall resistivity $\rho_{\rm H}$ versus field H_{ext} at room temperatures and 77K of Fe₈₀D₂₀ sample is shown in Fig. 4.14. The samples of this series have high values of saturation magnetization and hence the Hall resistivity $\rho_{\rm H}$ saturates at much higher fields. The values of the spontaneous Hall coefficient $R_{\rm S}$ of this series, are therefore, calculated from the low field slopes of $\rho_{\rm H}$ vs H data and are given in Table 4.7. In Fig. 4.15, we have plotted the spontaneous Hall coefficient $R_{\rm S}$ and the Hall conductivity $\gamma_{\rm H}$ at room temperature as functions of boron content x. It is clear, that $R_{\rm S}$ like many other properties of Fe-B glassy alloys shows a peak around x = 18, whereas $\gamma_{\rm H}$ falls monotonically with x between 13 \leq x \leq 26. It is also seen from Table 4.7 that qualitatively the variation of $R_{\rm S}$ with x is similar at room temperature and 77K.

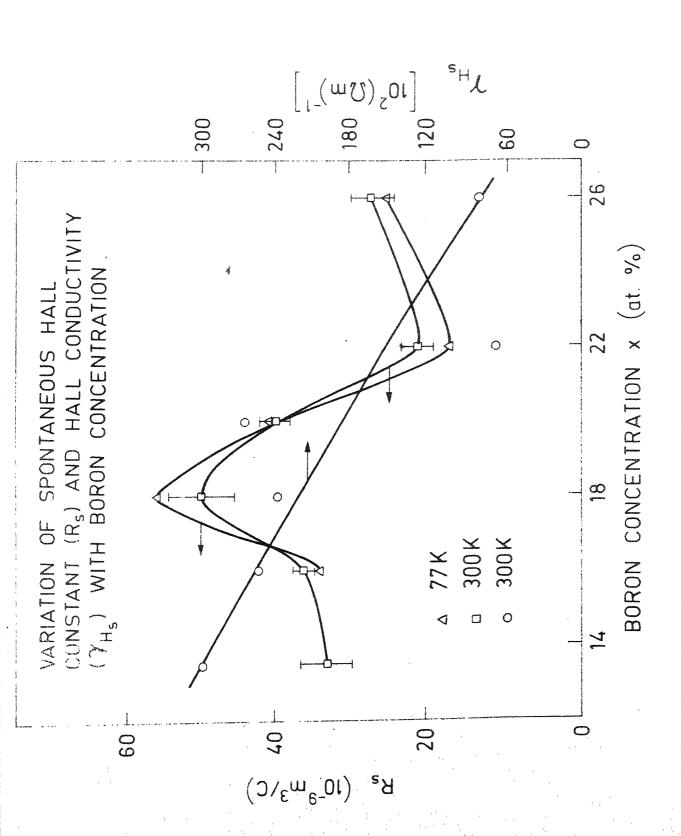
The error in the values of ρ_H and hence in R_s , ranging between 4% ~ 11%, is mainly introduced by the irregularity of the shape of the samples. The thickness t of the samples, which is needed to calculate $(\rho_H = \frac{V_H t}{I})$, was measured directly at different places of the sample pieces used for the measurement. The thickness was also indirectly calculated from the formula density = $\frac{m}{wlt}$ by measuring the width w at different places, length 1 and mass m of the same pieces. For the density of the

Table 4.7

Values of $\rm R_S$, $\rm M_S$ and $\rm \gamma_{HS}$ at 300% and $\rm R_g$ at 77% for Fe $_{\rm 100-x}{\rm B_X}$ samples (13 \leq x \leq 26)

2 7K	R (10 ⁻⁹ m ³ /C)		34 + 1	56 + 5	41 + 2	17 ± 2	25 + 3
は、1980年には、「1990年には、「1980年には1980年には、「1980年には1980年には1980年には1980年には1980年には1980年には1980年には1980年には1980年には1980年には1980年には1980年には1980年には1980年には1980年には1980年に1	$^{\gamma_{\mathrm{HS}}}_{\mathrm{10}^{2}(\mathrm{gm})^{-1})}$	297	252	236	263	70	82
	$M_{\mathbf{S}}^{\mathbf{M}_{\mathbf{S}}}$	1.52	1.47	1.43	1.38	1.37	1,30
300K	Rs (10-9 m ³ /C)	33 + 1	36 + 1	50 + 5	40 + 2	21 + 2	27 ± 3
	Samples	Fe ₈₇ B ₁₃	Fe84 ^B 16	Fe ₈₂ B ₁₈	Fe80B20	Fe ₇₈ B ₂₂	Fe74 ^B 26





samples the data of Hasegawa and Ray were used. The current stability in the circuit used was better than a few ppm and the accuracy of V_H was \sim 0.1%. Due to the irregularity of the shapes of the samples, the error in the thickness measurement was \sim 4% - 10%. Thus the error in final values of ρ_H was introduced mainly through the error in the measurement of thickness.

A brief discussion on the validity of the relation between R_s and ρ [eqn.(2.37)]is due in the next chapter. The tangent of the Hall angle, β , is directly found out from the experimental ρ and ρ_H data with the help of eqn. (2.38). These β values are tabulated in Table 4.6. Using the β value of $Fe_{80}B_{20}$ from this table we calculated θ from eqn. (2.46). The θ value of $Fe_{80}B_{20}$ thus calculated was $\sim 46^{\circ}$, which was obviously higher than the expected 79 , lll value. This lack of correlation between Hall effect and magnetoresistance is discussed in Chapter V.

DISCUSSION

In this chapter we have discussed the results given in Chapter IV. The theories used to interpret these results are already given in Chapter II.

5.1 ELECTRICAL RESISTIVITY: VARIATION WITH TEMPERATURE

In this section we have studied the temperature variation of electrical resistivity of two series of metallic glasses, namely, Fe-B and Fe-B-Si.

5.1.1 Variation of ρ_T/ρ_{RT} with T (77K \leq T \leq 300K) for $Fe_{100-x}B_x$ (13 \leq x \leq 26)

The range of possible error in α , $\Delta\alpha$, calculated for this series are given in Table 4.1. These include errors coming from (a) repeated measurements on a given piece of alloy (b) measurement on the different samples of the same composition. The average value of $\Delta\alpha$ over the entire composition range is $\simeq 0.05 \times 10^{-4} \text{K}^{-1}$, except for x = 16. Thus $\Delta\alpha$ due to sample to sample variation is not more than $0.05 \times 10^{-4} \text{K}^{-1}$. As a matter of fact, in case of $\text{Fe}_{82}\text{B}_{18}$ we could exactly reproduce the result in two different pieces. This fact clearly shows that these samples are quite homogeneous.

We will discuss our results in the light of the extended Ziman theory given in Chapter II. In the Fe-B series the sign

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of α is found to be positive in the whole range of amorphosity. As shown in Chapter II [eqn. 2.6)], α is expected to be negative only for materials with the structure factor $S_T(2k_F) > 1$. We calculated the value of k_F in the free-electron model, from the number of conduction electrons per unit volume, n, as

$$k_F = (3\pi^2 n)^{1/3}$$
 (5.1)

For Fe we have taken⁸³ $n_{Fe} \simeq 2 \times 10^{28} \text{m}^{-3}$, atomic weight = 56, and density = 7.8 g/cm^3 , with these data Z_{Fe} is calculated to be \simeq 0.24, where Z is the effective number of conduction electrons per atom. Further, using atomic weight of boron = 10, density of the particular metallic glass, say Fe₈₀B₂₀ = 7.4 g/cm³ and $Z_B = 1.6^{83}$, we have calculated n for $Fe_{80}B_{20}$ as $4.75 \times 10^{28} \text{m}^{-3}$. Hence, from eqn. (5.1), k_F is found to be $\simeq 1.1 \times 10^{10} \text{m}^{-1}$. The corresponding S(k) value (for k = 2k_F = 2.2×10^{10} m⁻¹) is found to be $\simeq 0.15$ from the S(k) vs k graph 112. The k_F values for the entire series were calculated and $2k_F$ value was found to lie between 2.01x1010 and 2.4x10¹⁰m⁻¹ increasing with increasing x. The corresponding $S(2k_F)$ were also found to increase monotonically within this range of 2k_F. Although precise estimation of S(k) is rather difficult from this graph, they are definitely much less than 1 and hence theoretically the values of α for the entire series is expected to be positive; this matches well with our

experimental data. An order-of-magnitude calculation of α for $^{\rm Fe}80^{\rm B}20$ was made by using eqn. (2.6) and eqn. (2.8) taking M \simeq 50 and $\Theta_{\rm D}$ = 400K. From theory, α comes out to be \simeq 1.4×10⁻⁴K⁻¹, which is in good agreement with our experimental α (\simeq 1.6×10⁻⁴K⁻¹).

The variation of α with x is shown in Fig. 4.6. temperature coefficient of resistivity falls abruptly from x = 13 to x = 16, and in the range $16 \le x \le 26$, α is almost independent of concentration. The latter is in agreement with the results of Mogro-Campero and Walter 113 . This fall in α from x = 13 to x = 16 points to a structural difference between $\mathrm{Fe}_{87}\mathrm{B}_{13}$ and other glasses of the series. Similarly, in the region 16 \leq x \leq 26, a nonvarying α indicates that there is no serious change in the structure. In fact, the concentration dependence of α comes from two factors, namely, the structure factor term and the Debye-Waller factor [see, for example, eqn. (2.6)]. As x increases the $2k_F$ value, and hence $S_T(2k_F)$ increases monotonically. Thus the positive value of α should decrease with x, if $S_T(2k_F)$ was the only factor governing it. But α depends on the Debye-Waller factor as well. As can be seen from eqn. (2.8), the x dependence of $\partial W(T)/\partial T$ mainly comes from the dependence of W(o) and the latter increases with x. Thus, qualitatively it can be argued that the decreasing effect of α from $S_T(2k_F)$ overrides the increasing effect of α from $\partial W(T)/\partial T$ for x = 13 sample and in

the region $16 \le x \le 26$ these two effects are competitive and hence α becomes approximately independent of concentration x. Such type of variation of α with x can be correlated with the variation of the crystallization temperature T_{cr} of these alloys with x, as studied by Hasegawa and Ray 109 . They found that T_{cr} abruptly increases from x=13 to x=16 and then there is a constant region in the range between $18 \le x \le 22$ and after that it slowly increases with x. Such a correlation gives rise to a stability criterion in terms of α . One should note that the effect of magnetic scattering, which might give an additional positive contribution to α , is ignored here.

In the temperature range 80K \leq T \leq 300K, $\Delta \rho/\rho$ is calculated from eqn. (2.10) by evaluating C and using the values of θ_D , M and k_F for Fe₈₀B₂₀. It is found that $\Delta \rho/\rho$ should approximately be \simeq 4.2%. As shown in Fig. 4.5 the values of $\Delta \rho/\rho$ in the temperature range 80K \leq T \leq 300K is independent of the concentration in the range 16 \leq x \leq 26, with values lying between 2.8 and 3.3%. However, for x = 13 this percentage change is higher (viz., 4.9%).

The Debye temperature of all the six samples were calculated from eqn. (2.11). The Θ_D values for $18 \le x \le 22$ are (390 ± 50) K (similar to those found by Mogro-Campero) 114, but for x = 13 and 16 it shows higher values of 540 \pm 90K, and for

x = 26 again it is around 520K. The exact values can be seen in Table 4.1 and all these Θ_{D} values have large error bars due to uncertainty in the slope S of the quadratic portion of the $ho_{
m T}/
ho_{
m RT}$ vs T graph. This was due to the experimental limitations of restricting the measurements in the top portion of the intermediate temperature range, i.e., 20K < T < 300K. In fact the range of temperature which we have chosen for finding out S, i.e., 80K \leq T \leq 150K, is the portion of $\rho_{\rm T}/\rho_{\rm RT}$ vs T plot where ρ_{T}/ρ_{RT} already starts deviating from the quadratic behaviour and moves towards linearity. Hence, uncertainty in the values of S could be expected. Nevertheless, as shown in Fig. 4.7, Θ_{D} has a minimum around x = 20 in qualitative agreement with the plots given by other workers 54,115 who have found out θ_n accurately from independent specific heat measurements. Onn et al 116 had found from heat-capacity measurements in $Fe_xNi_{80-x}P_{14}B_6$ metallic glasses that Θ_D is invariably lower in the amorphous alloys as compared to their nearest available crystalline counterparts. But, as it is clear from our measurements, for $Fe_{100-x}B_x$ alloys with x = 13, 16 and 26, Θ_{D} values are higher than that of pure Fe (\simeq 420K). This result is supported by the data of Japanese workers 54,115.

Since high Debye temperature means low thermal expansion coefficient, which in turn indicates Invar characteristics, we explain these high values of θ_D in Fe₈₇B₁₃ and Fe₈₄B₁₆ by Invar anomaly. For Fe_{100-x}B_x series it is well established 25,26,117

that around 13 \leq x \leq 17 atomic percent boron, alloys show Invar characteristics. This is the same range in which $\Theta_{
m D}$ values are higher than that of pure Fe. Hence, these two facts can be correlated. Matsuura et al⁵⁴ have also explained the high Debye temperature values of this series in terms of Invar anomaly. However, the reason for getting high θ_{D} values (for x = 18, 20, 22 comparable to θ_{D} of pure Fe and for x = 26 higher than that of pure Fe) in the range $18 \le x \le 26$, in contrast to the results of Onn et al, is not understood. Matsui and Adachi 118 and Caudron et al 119 have shown that in Fe-Ni alloys there is a drastic reduction in Θ_{D} values towards the Invar region. This reduction has been interpreted as 'softening' of phonon modes and the resulting instability of the Invar phase. From our data of Θ_{D} , it could perhaps be said that the phonon softening does not take place in the amorphous Fe-B alloys.

Lastly, a comment is due on the applicability of Ziman's theory in these metallic glasses. From eqns. (2.5), (2.7) and (2.8), one can easily find that 93

$$\rho(T) = \begin{cases} a\pi^2 T^2 / 6 \ \Theta_D^3 & \text{for } T << \Theta_D \\ aT / \Theta_D^2 & \text{for } T \ge \Theta_D \end{cases}$$
 (5.2)

Eqn. (5.3) clearly shows that the variation of $\rho(T)$ with T should deviate from linearity for temperatures below θ_D . In contrast to this we find that ρ_T/ρ_{RT} versus T graphs

(Fig. 4.1) are linear down to temperatures much less than the corresponding Debye temperatures, $\Theta_D.$ As pointed out in Chapter I, many workers $^{56-58}$ have discussed the limitations of applying Ziman's theory to such strong scattering liquid or glassy metals and recently this has been a subject of interest for theoreticians. Thus, the values of α and $\Delta P/P$, calculated here on the basis of the above theory should be taken as only order-of-magnitude estimates.

5.1.2 Electronic Stability Criterion

Next, we come to the question of the electronic stability criterion. A system is most stable when the Fermi energy E_{F} lies at a minimum of the density-of-states curve, D(E). To solve for the density of states of the glassy system, an expression using the free electron perturbation theories, is given by 20

$$E = E_{k}^{0}, + V(0) + \frac{Q}{8\pi^{3}} \int \frac{|V(k)|^{2} S(k)}{E_{k}^{0} - E_{k}^{1} + k} d^{3}k ; \qquad (5.2)$$

where V(k), S(k) and Q have been defined in Chapter II and $E_k^0 = \hbar^2 k^2/2m$. This expression fails when $|\vec{k}| + \vec{k}_p| = |\vec{k}|$ just as it does in the crystal where a gap opens up in the energy band at the zone boundary. In the case of glasses we do not expect a gap but we expect a similar decrease in the density of states at the energy $E = \frac{\hbar^2}{2m} (1/2 k_p^2)$. In the glassy state when S(k) remains spherically symmetric, we expect that all the states at $|k| = 1/2 k_p$ are affected. Hence, at the concentrations where $k_F = 1/2 k_p$ or $2k_F = k_p$ the Fermi energy E_F will

lie at a minimum of the density of states curve. As stated in Sec. 2.1.3, the effective number of conduction electrons per atom Z_{eff} corresponding to $2k_F = k_P$ is around $Z_{eff} = 1.7$. For the present $Fe_{100-x}B_x$ series, in eqn. (2.14) using $Z_{Fe} = 1$ and $Z_{\rm B}$ = 3 (valency of Boron) we get a stability around x = 35. This value is far away from the actual stable region of this series (which is around x = 20). We have calculated the Z_{eff} at k_p for this particular series. Using $k_p = 3x10^{10} m^{-1}$, it can be easily shown that $Z_{\mbox{\scriptsize eff}}$ corresponding to the peak of the S(k) vs k graph of the Fe-B series is 21.2 electrons per atom. The $Z_{\mbox{eff}}$ values for this series of stable alloys lie between 0.4 and 0.6 [calculated from eqn. (2.16)] using $Z_{Fe} = 0.24$ and $Z_{\rm R} = 1.6$ [Ref. 83)] and hence they are obviously far away from 1.2. Thus, we find that one could still have stable alloys with $2k_F$ << k_p . This conclusion is also corroborated by the interpretation we have given to justify the positive α for the Fe-B series. Since 0.4 \leq Z_{eff} \leq 0.6 is much less than the Z_{eff} corresponding to the peak of S(k) versus k graph, we get S(k) << 1, giving rise to a positive α . Also, taking these values of Z_{eff} in our theoretical calculations, we could reproduce all our experimental data, within reasonable error limits. Thus, one could say that the stability criterion of Nagel and Tauc is not applicable to the stable amorphous alloys with positive α , although it holds quite well for those having negative α values.

5.1.3 Variation of Resistivity with Concentration x

The resistivity values of all the six samples were theoretically estimated from eqn. $(2.15)^{120}$. The values of W(o) for the Fe_{100-x}B_x series are obtained from eqn. (2.9) using k_F, M and Θ_D as given in Sec. 5.1.1. Although it is not easy to get a precise estimate of $S(2k_F)$ from S(k) versus k graph¹¹² we still have to take into account its variation with x because it plays a significant role in eqn. (2.15). The ρ values are first calculated in terms of the constant C' of eqn. (2.15) and by comparing one of these values to the corresponding experimental value, we can have a rough estimate of the trend of the variation of ρ with boron concentration x. As stated in Chapter IV, ρ shows a tendency to increase with increasing x, both theoretically and experimentally. The experimental plot (Fig. 4.9) shows that the percentage change of resistivity between x = 13 and x = 26 samples is $\sim 30\%$.

Fukamichi et al⁸¹ have also studied the variation of absolute resistivity with concentration x in $Fe_{100-x}B_x$ (14 \leq x \leq 22) metallic glass series. They too have found an increase in resistivity with increasing x, but in their samples total variation (between x = 14 and x = 22) of ρ is only \sim 10%. As it is clear from Fig. 4.9, the theoretical curve shows a rather sharp change over the entire range of composition. This overestimation of ρ might be a result of overestimating

the structure factor $S(2k_F)$, which is very difficult to estimate precisely from the available plots. The error in calculating ρ was also introduced because we have taken the values of $S(2k_F)^{112}$ of a different set of samples, prepared under different conditions (Fukunaga et al¹¹² measured S(k) on splat-cooled Fe-B amorphous alloys, whereas our samples are melt-spun). Also, according to eqn. (2.15), we needed the values of $S_0(k)$, i.e. S(k) at 0 K, but the available data were taken at room temperature. Still, in absence of the exact values of $S_0(2k_F)$, we have used these structure factor plots to get an idea of the behaviour of ρ , theoretically. Hence, our theoretical plot of ρ versus x should be taken just as a guide to show whether ρ decreases or increases with x.

The main contribution to the electrical resistivity of pure transition metals arises from resonance scattering. The addition of metalloid atoms effectively increases the number of conduction electrons and thus in turn increases k_F . Because of this addition the structure factor S(k) plays a significant role in the resistivity of metallic glasses. With increasing x, $2k_F$ moves towards k_P (the most probable nearest neighbour distance in k-space) and thus increase the value of the resistivity.

5.1.4 Variation of Resistivity $\rho(T)$ with T in the Range 4.2K \leq T \leq 300K for Fe₈₀B_{20-x}Si_x (o \leq x \leq 12) Series As shown in Fig. 4.2, for this series too, the ρ_T/ρ_{RT} versus T plots are linear down to ~150K. In the temperature range 20K \leq T \leq 100K $\rho_{\rm T}/\rho_{\rm RT}$ data fit quite well in a T² plot (Fig. 4.4). The Debye temperature $\theta_{\rm D}$ were calculated from eqn. (2.11), with the help of slopes α and S, found out directly from Figs. 4.2 and 4.4. Fig. 4.8 shows a $\theta_{\rm D}$ versus x plot for Fe $_{\rm 80}$ B $_{\rm 20-x}$ Si $_{\rm x}$ (0 \leq x \leq 12) series. It is clear that the addition of silicon to the parent series (Fe-B), brings down the Debye temperature of these glasses. In fact, as stated earlier (Ref. 116), $\theta_{\rm D}$ values of these amorphous alloys are expected to be smaller than those of pure Fe (~420K). Unlike in Fe-B series, $\theta_{\rm D}$ of Fe-B-Si series are found to be \leq 420K, as expected. Probably, the addition of silicon removes the Invar characteristics of Fe-B alloys and hence the values of Debye temperature come down. About the varying nature of the

- i) it is a real effect and might indicate some structural changes in these alloys
- ii) it might be a result of the limitations of applying Ziman's theory to these alloys and the oscillatory curve might be replaced by a straight line.

Since the structural data of these alloys are not available, we do not have any means to verify these points.

Ziman's theory takes into account the electron-ion potential scattering and evolves into a T² dependence at low temperatures. Another possibility is the electron-magnon scattering

which results in a $T^3/2$ dependence. A detailed analysis of the resistivity data in the temperature range $20K \le T \le 100K$, was done to find out the possibility of the presence of magnon contribution to the resistivity. The least-squares fitting procedure was used for this purpose. Resistivity data were fitted to a power law of the form ,

$$\rho = a + bT^{3/2} + cT^2$$

As shown in Table 5.1, the x^2 of the least-squares fit were smaller when both $T^{3/2}$ and T^2 terms were simultaneously present than when only T^2 was considered. Inspite of this, the possibility of the simultaneous presence of both terms is ruled out because such a fitting gave negative b or c or unrealistically high Debye temperature.

Hence, in the temperature range 20K \leq T \leq 100K, we have considered the presence of T² terms only. To calculate θ_D , we have used the coefficients c (or the slope S of ρ_T/ρ_{RT} vs T² plots) from the least-squares fit when only T² term was considered.

5.2 MAGNETORESISTANCE

We first discuss an important point about the magnetoresistance measurements, in these thin ribbons. As stated in
Chapter III, during both the transverse and longitudinal
measurements the sample was oriented in such a way that the
applied field was always exactly parallel to the ribbon plane.

Table 5.1

χ^2 ,b,c of least-squares fit when	× 2 C (of least-squares fit when
$T^{3/2}$ and T^2 terms are simultaneously present	•	T ² term is present
For sample with $x = 0$	^	
x^2 1.24x10 ⁻⁹	x^2	3.21x10 ⁻⁹
b (-0.15+0.02)x10 ⁻⁵		
c $(7.24\pm0.23) \times 10^{-7}$	С	(5.81 <u>+</u> 0.04)x10 ⁻⁷
For sample with $x = 1$		
x ² 8.57x10 ⁻⁸	x^2	2.74×10^{-7}
b (1.38±0.24)x10 ⁻⁵		// 22 / 22 \ 22 \ 23 \ 23 \ 27
c $(-6.52 \pm 2.2) \times 10^{-7}$	С	$(6.31\pm0.38)\times10^{-7}$
For sample with $x = 2$		
x^2 7.4x10 ⁻¹⁰	x ²	7.75 x10 ⁻⁸
b $(1.08\pm0.025) \times 10^{-5}$		
c $(0.62\pm0.2) \times 10^{-7}$	С	$(10.9\pm0.21)\times10^{-7}$
·		•
For sample with $x = 4$		•
x^2 2.11x10 ⁻⁸	x ²	4.12x10 ⁻⁸
b $(0.52 \pm 0.12) \times 10^{-5}$		
c $(2.97\pm1.09)\times10^{-7}$	С	(7.85±0.13)x10 ⁻⁷
		contd

x^2 ,b,c of least-square fit when $T^{3/2}$ and T^2 terms are simultaneously present	· · · · · · · · · · · · · · · · · · ·	least-squares fit when term is present
For sample with $x = 6$		
x ² 6.11x10 ⁻⁹	x ²	3.21x10 ⁻⁸
b $(0.64+0.07) \times 10^{-5}$		•
c $(3.78 \pm 0.68) \times 10^{-7}$	С	(9.88±0.13)x10 ⁻⁷
For sample with $x = 8$		
x^2 2.69x10 ⁻⁸	x^2	1.54x10 ⁻⁷
b (1.43+0.15)x10 ⁻⁵		
c $(-1.3 \pm 1.46) \times 10^{-7}$	С	(12.5±0.31)x10 ⁻⁷
For sample with $x = 12$		
x^2 3.34x10 ⁻⁹	x^2	1.37x10 ⁻⁸
b (0.37±0.05)x10 ⁻⁵		
c $(5.06\pm0.44)\times10^{-7}$	С	(8.51+0.08)x10 ⁻⁷

We point out here why this precaution should be taken! In fact, while making transverse magnetoresistance measurements two types of orientation of the field with respect to the ribbon plane are possible. Fig. 5.1 shows these two prientations.

As it is clear from this figure, in both these orientations the condition of transverse magnetoresistance (HIJ) is met. But, we have always chosen the particular orientation H | | ribbon plane for our measurements. The reason for doing so is to minimise the effect of demagnetizing field. When the applied magnetic field H is directed perpendicular to the ribbon plane, at low fields, the influence of demagnetizing field is very prominent (see Appendix 2) 121, since these samples have large width/thickness ratio. Because of this the saturation magnetization and hence the saturation of $\Delta \epsilon_{i} / \rho$ of these samples are reached only at considerably higher fields thereby causing the fall in negative magnetoresistance with field to be much slower. At high fields this influence is not present. We would like to point out here that, in the case of transverse magnetoresistance measurements, not only the sample orientation but also the sample alignment with respect to the magnetic field plays an important role at low fields. If the sample is misaligned, the transverse magnetoresistance at low fields will show positive values, as observed by Fukamichi et al 75 and Kern and Gönser 77 . They have attributed this

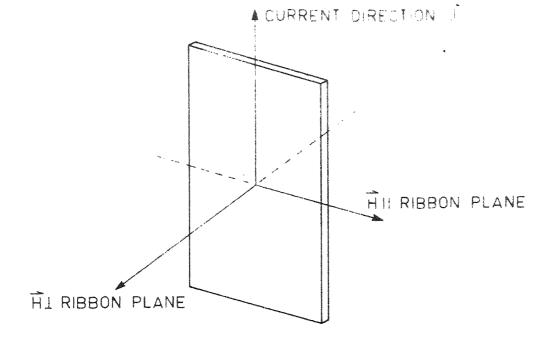
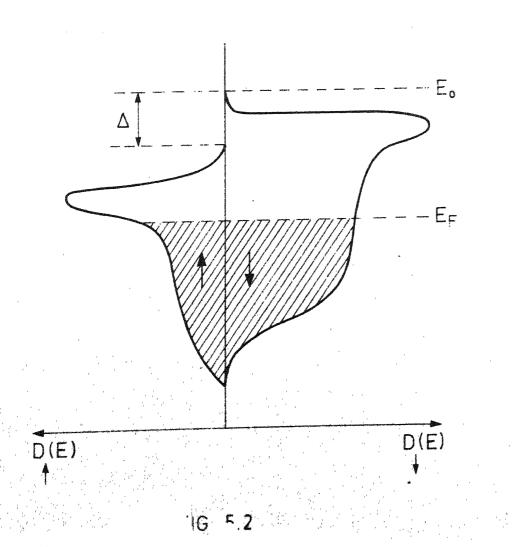


FIG. 5.1



positive value to the initial orientation of some of the domains in the direction perpendicular to the field and parallel to the current. However, according to our observations, this sort of positive values of $\Delta P_1/P$ will show up in the magnetoresistance measurements, in both the possible orientations of the field with respect to the ribbon plane, only if the alignment of the sample is wrong. Since longitudinal magnetoresistance, $\Delta P_1/P$, saturates much faster with field than transverse magnetoresistance, $\Delta P_1/P$, even a slight misalignment would introduce a positive value which overshadows the inherent negative value of $\Delta P_1/P$. The only merit of choosing the orientation \vec{H} in this orientation because of the small value of the demagnetizing factor. Hence, it is much easier to avoid the misalignment effect in this orientation.

5.2.1 Ferromagnetic Anisotropy of Resistivity (FAR)

As shown in Chapter II, the ferromagnetic anisotropy of resistivity is given by eqn. (2.29). The values calculated from magnetoreistance measurements are given in Chapter IV. The broad maximum of FAR vs x plot at 300K and a more prominent one at 77K are in agreement with the results obtained by Fukamichi et al⁷⁵. This type of variation of FAR with concentration is quite similar to the variation of many other physical properties like density 109,112, magnetostriction 47,122, co-ordination number 112, magnetic moment 25 etc. Kemény et al 124

have shown that even the crystallization process changes from a 2-step mechanism to a 1-step one as the boron content x changes from x \leq 15 to x \geq 15. From eqn. (2.36) it is clear that a peak in magnetic moment versus x plot implies a peak in FAR versus x graph. In these metallic glasses the peak in μ versus x plot gets smeared out with increasing temperature (in fact μ vs x plot at 4.2K itself is quite smeared out and when the room temperature μ values are calculated from eqn. (1.3), using the data of Hasegawa and Ray the μ becomes independent of x at 300K). So, again from eqn. (2.36), a similar behaviour is expected in FAR vs x graph too with a more prominent peak at 77K. It is clear from Fig. 4.11 that our FAR versus x plot at room temperature is broader as compared to that at 77K.

Another interesting feature which merits some discussions is the small values of FAR in these metallic glasses as compared to that of their crystalline counterparts. For crystals, as given by Jan^{102} , FAR values might be as high as 20%, whereas our data show that FAR for this series varies only between 0.2% and 0.6%. Nigam and Majumdar have tried to explain this in the light of Berger's split-band model. According to them glasses of Fe-B series lie far away from the λ_s = 0 line on the (Fe_XNi_{1-x})₈₀B₂₀ ternary diagram (λ_s = coefficient of linear magnetostriction) and hence the FAR values are small for these alloys. But, as pointed out by Fukamichi et al ⁷⁵, Berger's model is applicable to strong ferromagnets, whereas Fe-B

amorphous alloys are weak ferromagnets. This view is supported by the band model 125 [$\Delta < (E_o-E_F)$] too (see Fig. 5.2). In fact 125 Fe $_{30}$ B $_{20}$ is a typical example of a weak ferromagnet. Also, d-type band splitting in Fe-D alloys is definitely not possible because boron does not have any d-electron state $(2s^2, 2p^1)$. Hence, it is not justified to use Berger's model to explain the small FAR values of Fe-B alloys. The small FAR values of metallic glasses can be attributed to the fact that though the anisotropic magnetoresistance i.e. $\rho_{11}-\rho_{11}$ of amorphous and crystalline materials are comparable (it does not depend on the initial magnetic domain structure), the resistivity of crystalline materials is much smaller than that of amorphous alloys.

From Fig. 4.9 and Fig. 4.11, we have tried to predict at 300K, the FAR and the resistivity of amorphous Fe, by extrapolating these plots to x = 0. Our results show that the FAR of amorphous Fe is negative ~-0.4% (whereas for crystalline Fe it is +0.5%) and the resistivity of amorphous Fe, $\rho_{\rm am-Fe}$ is found to be $\simeq 1 \times 10^{-6}$ Ω m which is an order of magnitude larger as compared to $\rho_{\rm cryst.Fe} = 10^{-7} \, \Omega$ m .

5.2.2 Θ , the Angle between \vec{J} and \vec{M}

Metallic glasses have uniaxial anisotropy. Hence, the domains in these alloys are preferntially oriented at some angle Θ with the ribbon axis. Generally, metallic glasses

choice of current direction \vec{J} is along the ribbon axis Many workers 28,79,111 have tried to find out this angle between \vec{J} and \vec{M} through various methods. As given by eqn. (2.35), we have tried to formulate an expression for Θ in terms of our measured quantities from the fundamental concepts of magnetoresistance.

5.2.3 Variation of the Forced Magnetoresistivity $\frac{1}{\rho} \frac{\partial \rho}{\partial H}$ with x

As pointed out in Chapter IV, the magnetoresistance plots $(\Delta P/P)$ vs H) show negative slopes at high fields. These slopes, i.e., the forced magnetoresistivity $\frac{1}{P}\frac{\partial P}{\partial H}$ were directly found out from these graphs. A plot of $\frac{1}{P}\frac{\partial P}{\partial H}$ vs x (Fig. 4.12), at 300K shows that it decreases from a positive value at x = 13 to negative values beyond x = 14.5 giving a minimum at x = 18 and then it increases slowly with x. At 77K it is always negative and has a minimum around x = 17.

Actually, the negative slope in these plots are due to reduced electron-magnon scattering at higher fields. It is well known that in Fe-B amorphous alloys the magnetic moment decreases with decreasing boron content 25,75,117 . Hence, in the range of lower boron content, less electron-magnon scattering is expected and correspondingly the slope should be more negative. As it is clear from eqn. (2.30) in Chapter II $(\frac{1}{\rho},\frac{\partial\rho}{\partial H})$ should be more negative with increasing high-field

susceptibility. Also, the samples with low boron content have large high field susceptibility values (Invar property) and hence eqn. (2.30) implies that lower the boron content more negative should be the value of $\partial P/\partial H$. But as stated in the last paragraph, in the range 13 < x < 18 at 300K and 13 < x < 16, at 77K, in contradiction to our expectations the value of $\frac{1}{6} \frac{\partial \rho}{\partial H}$ becomes less negative with decreasing x. However, in the range $18 \le x \le 26$ (for 300K) and $16 \le x \le 26$ (for 77K) the trend of the plots is consistent with our expectations. The behaviour in the range $13 \le x \le 18$ can be explained by the Invar anomaly. A similar behaviour has been observed in Fe-Ni crystalline Invar alloys. Soumura 126 has explained this behaviour by taking into account the contribution due to large forced volume magnetostriction. In fact Fukamichi et al 117 have observed large values of volume magnetostriction (δω/δΗ) for these alloys in the Invar region (13 \leq x \leq 18); therefore, this large value of $\partial\omega/\partial H$ could be expected to contribute to the magnetoresistance of these alloys. Assuming that $\frac{1}{\rho} \frac{\partial \rho}{\partial H}$ is a function of volume V and magnetic field H, at constant prossure we can write,

$$\frac{1}{\rho} \left(\frac{\partial \rho}{\partial H} \right)_{\mathbf{p}} = \left(\frac{\partial \ln \rho}{\partial \ln V} \right)_{\mathbf{H}} \left(\frac{\partial \omega}{\partial H} \right)_{\mathbf{p}} + \frac{1}{\rho} \left(\frac{\partial \rho}{\partial H} \right)_{\mathbf{V}}$$
 (5.3)

where

$$\frac{\partial \omega}{\partial H} \propto \# M \times_{hf}$$
 (5.4)

where K is the compressibility, M the magnetization and Xhf is the high field susceptibility. In eqn. (5.3) generally the first term is negligibly small but for Invar alloys, as stated earlier $\partial \omega / \partial H$ is large and one cannot ignore this term. room temperature value of $\partial\omega/\partial H$ for Fe-B alloys is remarkably large 127 and as stated by Fukamuchi et al 75 the calculated value at 4.2K by using eqn. (5.4) is also large, hence $\partial\omega/\partial H$ at 77K is also expected to be considerably large lying between these two values. Since $\partial \omega/\partial H$ increases with decreasing boron content and this effect seems to override the effect of electronmagnon scattering on forced magnetoresistivity, we get a less negative $\frac{1}{0}\frac{\partial \Omega}{\partial H}$ with decreasing boron content in the Invar range of Fe-B alloys, namely, $13 \le x \le 18$. It is clear from Fig. 4.12 that the values of $\frac{1}{p} \frac{\partial p}{\partial H}$ decrease, i.e., become more negative with decreasing temperature. This is an unexpected result, because at low temperatures magnons are very few in number, hence saturation is reached and consequently $\partial M_s/\partial H$ Thus negative slope at high fields is expected tends to zero. to vanish in contrast to our results.

5.3 HALL EFFECT

In amorphous ferromagnetic alloys, just as in the case of polycrystalline materials, Hall resistivity is given as,

$$\rho_{H} = \frac{V_{H}^{t}}{I} = R_{o} B_{in} + R_{s}^{M} s$$
 (5.5)

where the magnetic induction B and magnetization M are both expressed in Tesla. The spontaneous Hall coefficient $R_{\rm s}$ is generally found out by extrapolation of the high field data of $\rho_{\rm H}$ versus $B_{\rm in}$ to $B_{\rm in}$ = 0. But as stated in Chapter IV, in case of metallic glasses $\rho_{\rm H}$ versus $B_{\rm in}$ ($B_{\rm in}$ = $H_{\rm ext}$) plot saturates so slowly that it is very difficult to find out $R_{\rm s}$ by this direct method. $R_{\rm s}$ in such alloys with high $M_{\rm s}$ values are calculated from the low field slope of $\rho_{\rm H}$ versus $B_{\rm in}$ plots. Justification of calculating $R_{\rm s}$ by this latter method is given below 128 .

We can express eqn. (5.5) in terms of R_1 and R_0 as,

$$\rho_{H} = R_{o} B_{in} + (R_{1} - R_{o}) M_{s}$$

$$= R_{o} (B_{in} - M_{s}) + R_{1} M_{s}$$

As shown in Sec. 3.7, we can write $B_{in} = H_{ext}$ and thus ρ_{H} can be written as,

$$\rho_{\rm H} = R_{\rm o}(H_{\rm ext} - M_{\rm s}) + R_{\rm l}M_{\rm s}$$
 (5.6)

Below the Curie temperature T_c and well below saturation $H_{\rm ext} = M_s$. Then, eqn. (5.6) becomes

$$\rho_{H} = R_{1}M_{s} \tag{5.7}$$

Since in amorphous ferromagnets $R_s \gg R_o$, $R_1 \simeq R_s$ and hence

 $\frac{\partial H}{\partial H}$ ext $H_{\text{ext}} = 0$ will give the spontaneous Hall coefficient R_s .

We will, therefore, discuss the spontaneous Hall coefficient $R_{_{\rm S}}$ thus calculated from the low field slope of ${m
ho}_{_{\mbox{\scriptsize H}}}$ versus $^{\rm H}{\rm ext}$ graph. O'Handley $^{\rm 83}$ has discussed R $_{\rm s}$ of amorphous Fe $_{\rm 80}{}^{\rm B}{\rm 20}{}^{\rm s}$ He has explained his results in terms of Berger's scattering mechanism as explained in Chapter II. It is argued that $R_{\boldsymbol{s}}$ of $Fe_{80}^{B}20$ is proportional to ho^{2} because it falls on an universal R_s vs ρ graph. It also seems to satisfy the relation $\Delta y \propto R_{\rm S}/\rho^2$ (where Δy is the magnitude of the side jump) by giving $\Delta y \simeq 1 \times 10^{-10}$ m [calculated from eqn. (2.41)], comparable to that of crystalline transition metal alloys (also ~ 10 $^{-10}$ m). This agreement between Δy values and the point for $Fe_{80}^{B}_{20}$ falling on the R_{s} versus ρ graph for crystalline materials seem to be a mere coincidence. As can be seen from Figs. 4.9 and 4.15, R_s does not vary as ρ^n . In fact, this relation given by eqn. (2.37) $(R_s = A \rho^n)$ makes the assumption that any band structure differences due to the additives are negligible, the alloys are dilute (~ 5 %) and R_s is governed mainly by scattering. As shown by Suzuki et al 112, the composition dependence of the coordination number, the density and the binding energy of Fe 3d-band clearly show that around the composition range from 14 to 16 atomic percent boron, there is a drastic modification in the topological arrangement of the Fe atoms in the Fe-B glassy alloys. These studies

suggest that the B atoms occupy interstitial position in the low boron content alloys and with increasing boron content, these atoms take the substitutional positions in the alloy. Thus the band structure is severely altered around the eutectic composition, and hence eqn. (2.37) should not hold for these alloys.

For the $\text{Fe}_{100-x}\text{B}_x$ series, boron is non-magnetic and hence with decreasing boron concentration we expect an increase in R_s value. It is clear from Fig. 4.15, that between x = 26 and x = 18, R_s increases with decreasing x as expected, but for 13 \leq x \leq 18, there is a fall in the R $_{\rm s}$ values. This sort of unexpected behaviour of R_s for alloys with x \leq 18 can be attributed to the Invar anomaly of Fe-B glassy alloys. Also, the specific heat study of these alloys by Matsuura et al 54 shows an unusually large value of γ (the electronic specific heat coefficient) far exceeding the band structure contribution. They attribute this unexpectedly large \gamma value for the low B alloys to the ferromagnetic instability or magnetic inhomogeneity closely related to the occurrence of Invar effect. Keeping in view our R_s versus x plot, we suggest that due to the occurrence of Invar characteristics in this series of alloys around $x \leq 18$, the R_s values start falling.

The unexpectedly large monotonic fall of the Hall conductivity γ_{H_s} (R $_s$ M $_s/\rho^2$) could be understood in the following way.

In the range of composition $18 \le x \le 26$, R_s decreases and f increases with increasing x and thus both contribute to decrease γ_H with increasing x. However, in the range below x=18, R_s and ρ both decrease with decreasing x and it becomes difficult to predict the behaviour of γ_H . As it is clear from Figs. 4.9 and 4.15, and also from Tables 4.3 and 4.7 the percentage variation of R_s and ρ in the range $13 \le x \le 18$ are more or less the same but since γ_H is inversely proportional to ρ^2 , the effect of ρ is more and hence γ_H increases with decreasing x in this range.

5.4 CORRELATION BETWEEN HALL EFFECT AND MAGNETORESISTANCE

The correlation indicated by eqn. (2.46) could not be established in these metallic glasses. However, the reason behind this failure is very clear now. In $Fe_{80}B_{20}$, scanning electron microscope studies show 28 , 111 that the principal domains (\sim 600 μ m in width) lie parallel to the ribbon axis with the magnetization oriented at $20^{\circ} \sim 30^{\circ}$ off the ribbon axis in the plane of the sample. Due to the typical shape of these samples (thin, long ribbons), measurements of magnetoresistance and Hall effect are carried out in the orientation where the current flows parallel to the ribbon axis. It is clear from Sec. 2.4, that when current flows parallel to the domain walls, Berger's mechanism 107 does not come into the picture. Hence, the normal ferromagnetic anisotropy of resistivity is the only dominant mechanism for the magnetoresistance, as measured in the present orientation.

CHAPTER VI

ROLE OF Si AND C IN METGLAS 2605 SC*

6.1 INTRODUCTION

Metglas 2605 SC ($Fe_{81}B_{13.5}Si_{3.5}C_2$) is the successor of Metglas 2605 $(Fe_{80}B_{20})^{130}$. It has a superior combination of magnetic properties and low cost. In this chapter we report a detailed study of thermomagnetic and transport properties of these two amorphous ferromagnets in order to understand the role, if any, of the partial replacement of boron (B) by silicon (Si) and carbon (C). The low-field magnetic moment was measured as a function of temperature from 300 to 1050K investigate the whole process of magnetic and structural phase transitions. Differential thermal analysis in the same temperature range provided the crystallization temperatures. Mossbauer and X-ray studies on annealed Metglas 2605 SC established the equilibrium crystalline phases. The electrical resistivity was measured from 300K down to 77K while the magnetoresistance was measured at 300 and 77K. The Hall resistivity was measured at 300K only. An attempt is made to interpret the data in terms of existing ideas about amorphous systems.

6.2 EXPERIMENTAL TECHNIQUE

The metallic glasses 2605 and 2605 SC were obtained from *A part of this chapter is published in J. Mag . Mag . Mat. 25, 83 (1981).

Allied Chemical Corporation, New Jersey, USA. The thermomagnetic studies in the temperature range of 300 to 1050K were made by using a PAR vibrating sample magnetometer (Model 155) and a high temperature oven assembly (Model 151), placed in the residual field (~ 30G) of an electromagnet. The magnetometer was calibrated with the help of a standard Ni sample. The temperature of the sample was determined by a Chromel-Alumel thermocouple and was correct to \pm 2K. The sample was kept in such a way that the magnetic field lay in the plane of the sample (to minimise the demagnetizing field). The typical heating rate used in the experiment was \sim 5K/min. The rate was lowered to \sim 1K/min near the transition temperatures.

For X-ray diffraction and Mössbauer studies we had annealed a piece of 2605 SC for ~ 2 at 1200K. The sample was completely crystallized by this heat treatment. Mössbauer spectrum of this sample was taken by using a ⁵⁷Co-Rh source. X-ray diffraction pattern of the same piece was taken in an ISODEBYEFLEX 2002 diffractometer using a Cr source. The differential thermal analysis was performed at a heating rate of 5K/min using a Mom (Budapest) derivatograph.

The electrical resistivity, the magnetoresistances and the Hall effect were measured using the procedures already described in Chapter III.

6.3 RESULTS AND DISCUSSION

6.3.1 Curie Temperature T

The results of our studies of the low-field (\simeq 34 G) magnetic moment μ (in arbitrary units) of Metglas 2605 SC as a function of temperature T are plotted in Fig. 6.1. The kink-point method gives a T_c of 646 K. The inset shows that the maximum of $-d\mu/dT$ vs. T plot is at 649 K. Thus the average T_c of the sample could be taken as (647 ± 2) K. Curie temperatures, T_c for all the Fe_{100-x} B_x sample (13 \leq x \leq 26), were also measured. As shown in Fig. 6.2, T_c increases with increasing x. The Curie temperature of $Fe_{81}B_{19}$ from this graph is found to be \simeq 645 K. This agrees well with the data of Kemény et al¹²⁴. Thus, one can say that T_c is not much affected by partial replacement of B by Si and C. This implies that the near neighbour environment of the Fe-atoms is not very different in these two metallic glasses.

6.3.2 Thermomagnetic Studies

Fig. 6.3 shows an X-Y recorder plot of the low-field moment μ as a function of temperature T. A thermal cycling (from 300 to \simeq 1050 K) of both Metglas 2605 SC and 2605 is shown in this figure. In the process of measurement Metglas 2605 has also been annealed at 915 K for 2 h.

The continuous curve of Fig. 6.3 represents the magnetization behaviour of 2605 SC. The first fall (645 K) corresponds to the transition from an amorphous ferromagnetic (a_f)

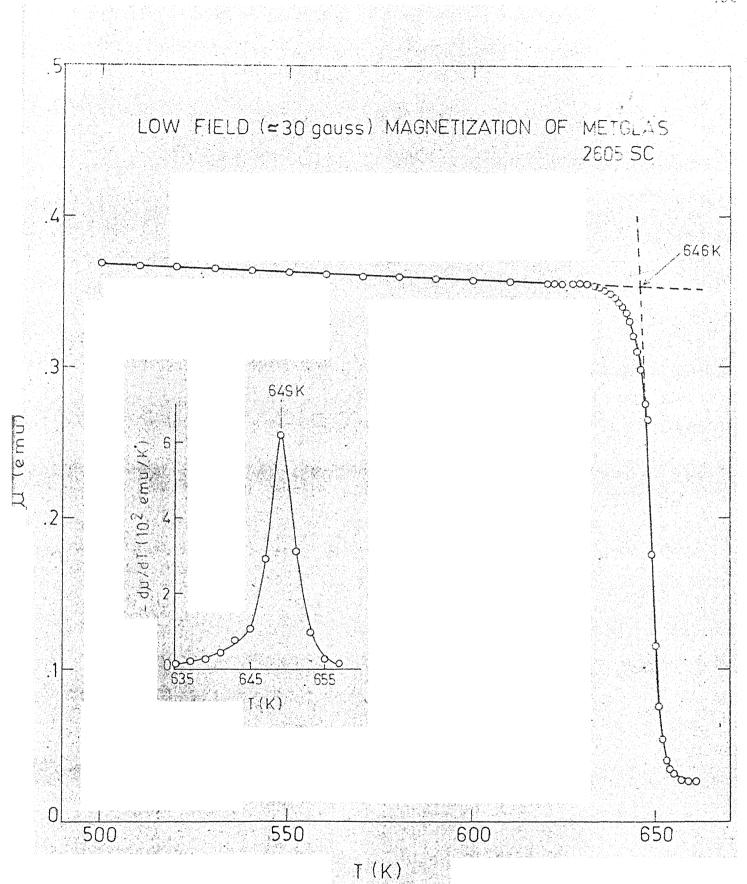


FIG. 6.1

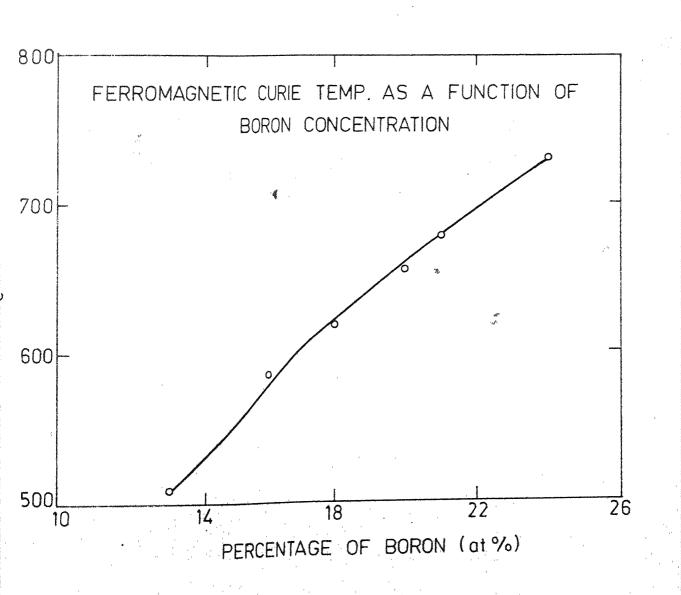
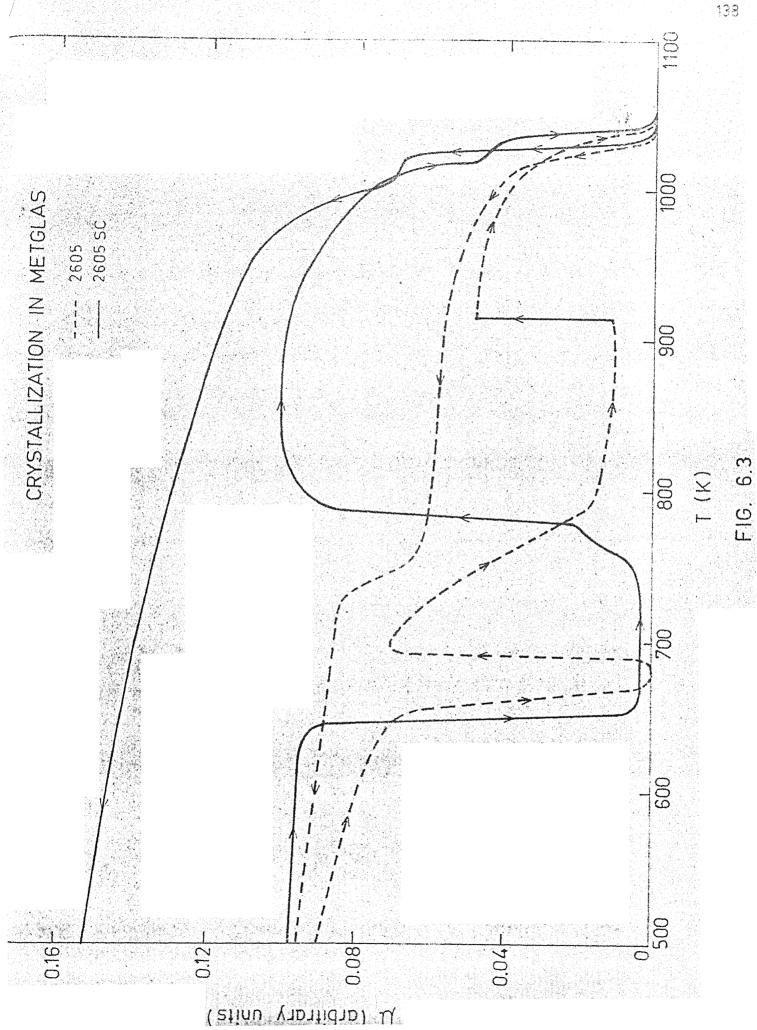


FIG. 6.2



to an amorphous paramagnetic (a $_{\rm p}$) state. At 750 K, $\alpha\text{-Fe}$ starts precipitating and then at 780 K Fe_3B is getting crystallized. The thermomagnetic data shows an unexpected sharp rise in moment at 780 K, which is reproducible in many runs. Such a rise in the moment could not be due to $\alpha ext{-Fe}$ precipitation only. The moment of Fe $_3$ B phase, on the other hand, cannot be so large near its Curie temperature which is around 800 $\mathrm{K}^{\,131}$. However, this is possible if there appears other crystalline phases having high enough T_c , e.g., Fe₃B decomposing into Fe₂B and α -Fe. Thus, most probably, this sharp rise indicates that at 780 K, Fe_3B has crystallized as well as has decomposed into Fe_B and $\alpha\text{--}\text{Fe}$ in their ferromagnetic states. Chien et al. had reported the decomposition temperature of Fe $_3$ B as \geq 825 K 131 , whereas we find it to be around 780 K. This difference in decomposition temperature could be due to very different heating rates in the two cases, namely, 20 and 5 K/min, respectively. At much higher temperatures there are two sharp falls, one at 1015 K and the next at 1045 K. This very clearly shows the presence of Fe₂B $(T_c = 1015 \text{ K})^{131}$ and α -Fe $(T_c = 1043 \text{ K})$. Since the magnetic moment becomes almost zero around 1045 K, it is clear that no other ferromagnetic phase is present having still higher T_c . While cooling we see a two-step rise in the moment near 1040 and 1010 K corresponding to the two equilibrium phases $\alpha ext{-Fe}$ and Fe_2B . The crystallization sequence of 2605 SC can be schematically represented as :

at 645 K
$$a_f(2605 \text{ SC}) \rightarrow a_p(2605 \text{ SC})$$
, at 750 K $a_p(2605 \text{ SC}) \rightarrow C_f(\alpha\text{-Fe}) + a_p(\text{rest})$, at 780 K $a_p(\text{rest}) \rightarrow C_f(\alpha\text{-Fe}) + C_f(\text{Fe}_3\text{B})$ and
$$C_f(\text{Fe}_3\text{B}) \rightarrow C_f(\text{Fe}_2\text{B}) + C_f(\alpha\text{-Fe})$$
, at 1015 K $C_f(\text{Fe}_2\text{B}) + C_f(\alpha\text{-Fe}) \rightarrow C_p(\text{Fe}_2\text{B}) + C_f(\alpha\text{-Fe})$, at 1045 K $C_f(\alpha\text{-Fe}) + C_p(\text{Fe}_2\text{B}) \rightarrow C_p(\alpha\text{-Fe}) + C_p(\text{Fe}_2\text{B})$.

The dotted curve of Fig. 6.3 represents the magnetization of 2605. The first fall (655 K) is again due to the transition from an amorphous ferromagnetic to an amorphous paramagnetic In contrast to 2605 SC, the sharp rise in moment at 690 K shows the simultaneous crystallization of $\alpha ext{-Fe}$ and Fe 3^B , both in their ferromagnetic states. Near 800 K, a smeared out fall occurs as one of the above two phases, namely, Fe3B becomes paramagnetic. Note that the magnetic moment still does not fall to zero which verifies the presence of $\alpha\text{-Fe}$, the second ferromagnetic phase. Around 915 K, the magnetic moment has a tendency to rise due to the crystallization of remaining Fe and here the sample was kept at a constant temperature for 2 h for complete crystallization. The next fall near 1040 K is clearly due to α -Fe. Here the magnetic moment becomes zero, showing the absence of any other ferromagnetic phase with higher T_c . While coming back in this thermomagnetic cycle

the rise in moment near 1040 and 800 K, proves the presence of α -Fe and Fe₃B as the two equilibrium phases. Schematically the crystallization sequence of 2605 is given by :

at
$$\stackrel{\sim}{\sim}$$
 655 K $a_f(2605) \rightarrow a_p(2605)$,
at $\stackrel{\sim}{\sim}$ 690 K $a_p(2605) \rightarrow C_f(\alpha - Fe) + C_f(Fe_3B)$,
at $\stackrel{\sim}{\sim}$ 800 K $C_f(\alpha - Fe) + C_f(Fe_3B) \rightarrow C_f(\alpha - Fe) + C_p(Fe_3B)$,
at $\stackrel{\sim}{\sim}$ 1040 K $C_f(\alpha - Fe) + C_p(Fe_3B) \rightarrow C_p(\alpha - Fe) + C_p(Fe_3B)$.

From the above discussion we find that in the case of 2605 $\alpha\text{--Fe}$ and Fe₃B crystallize in a single step whereas for 2605 SC there are two well-resolved steps of crystallization. The results of differential thermal analysis (DTA) support the above conclusion and are shown in Fig. 6.4. For Metglas 2605 SC the two major crystallization peaks are separated by about 30 K while Metglas 2605 has one major peak at ~ 710 K and two minor peaks around 920 K. A similar two-step crystallization for small B content samples and a single-step process for high B contents ones had been observed by Kemeny et al 124 . According to them, lpha-Fe precipitates until the composition of the remaining glass reaches $Fe_{75}B_{25}$ and then Fe3B starts crystallizing. In 2605 SC Fe and B are present in the ratio 6:1, hence α -Fe precipitates first until this ratio becomes 3:1 and only then crystallization of Fe3B starts. 2605 the ratio, being 4:1, is already very close to 3:1 and

DIFFERENTIAL THERMAL ANALYSIS

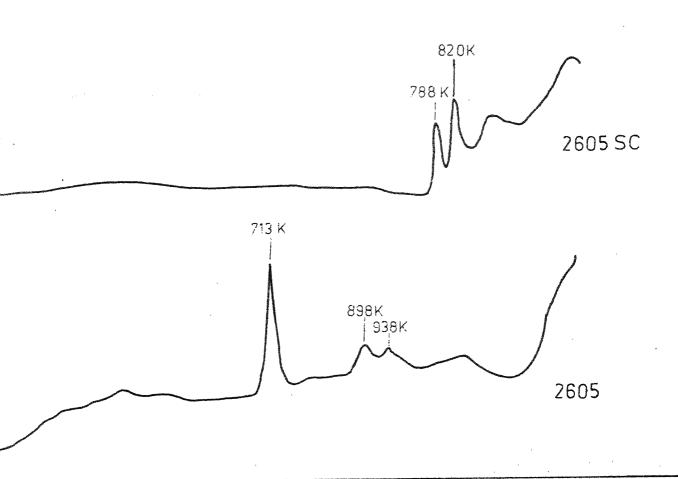


FIG. 6.4

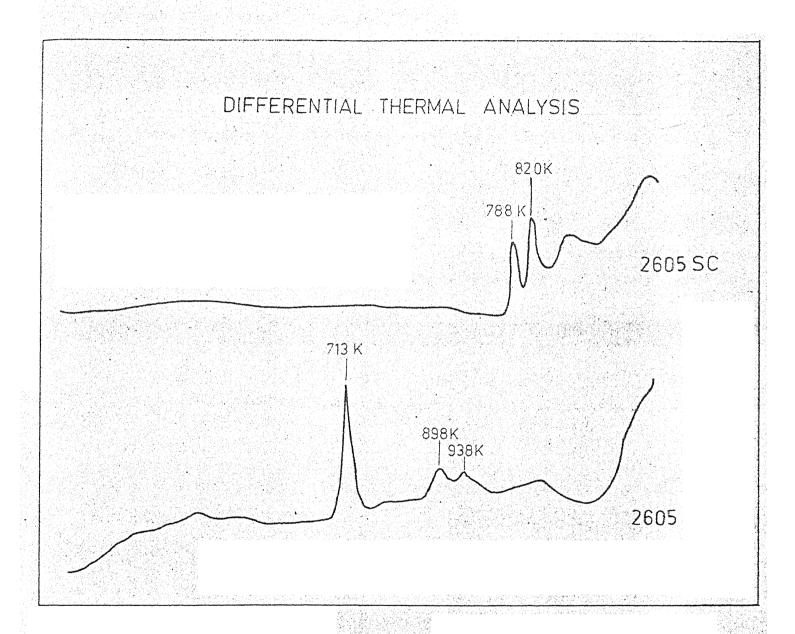
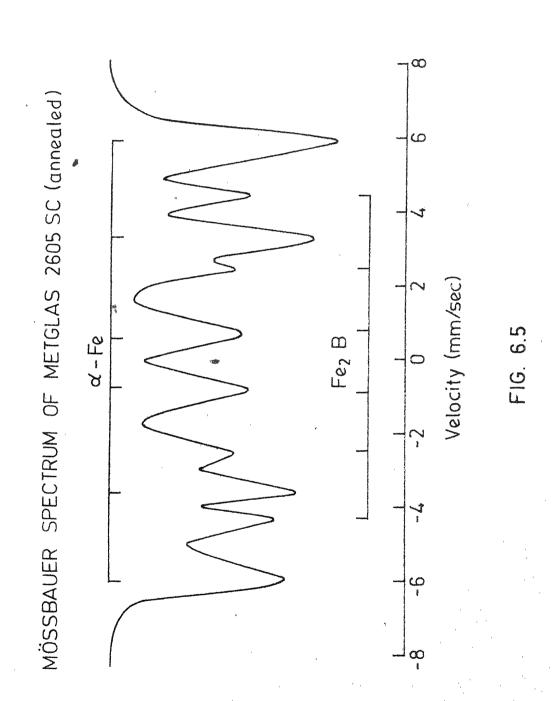


FIG. 6.4



isomer shift, within the error limit is found to be of α -Fe. Thus, Mossbauer study confirms the presence of α -Fe and Fe₂B as the equilibrium phases in 2605 SC.

6.3.4 X-ray Analysis

The X-ray analysis of the annealed 2605 SC sample shows a number of lines whose d-spacings are given in Table 6.1 as $d_{\rm obs}$. Also, the characteristic lines of α -Fe, Fe₂B and Fe₃B are tabulated as $d_{\rm std}$. A comparison immediately confirms the presence of α -Fe and Fe₂B phases. The X-ray diffraction pattern of 2605 SC had clearly shown the dominance of metalmetal pair contributions. This is due to the fact that the metal atoms have larger X-ray scattering factors than the metalloid (B) atoms and also, the alloy contains only about 13.5 at.% B.

The diffraction pattern had also shown some other lines which are yet to be identified. However, it is clear from the magnetization studies that they do not correspond to any magnetic phase.

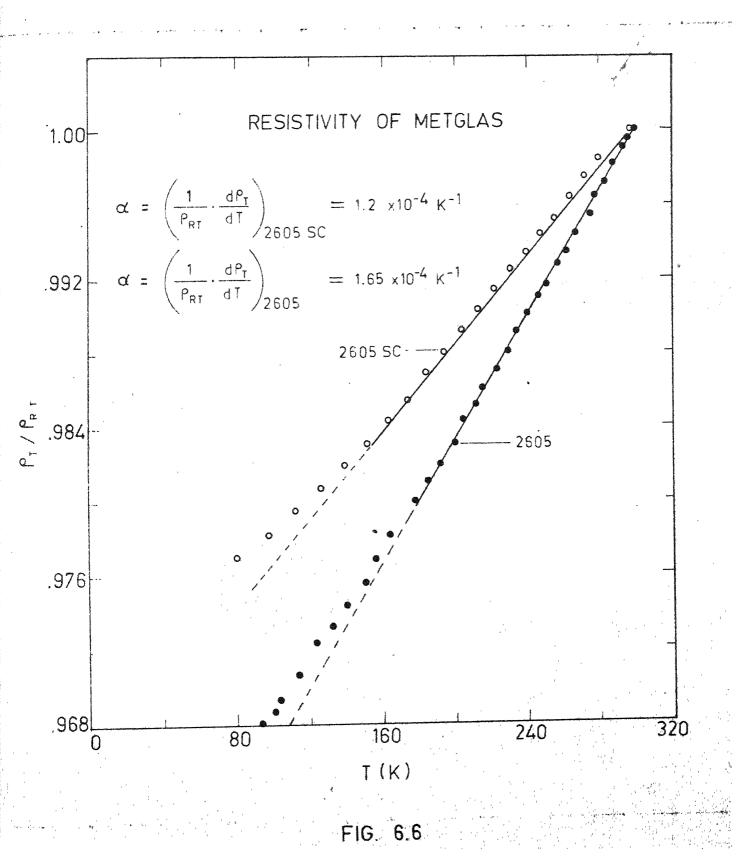
6.3.5 Transport Properties

In Fig. 6.6 we have plotted ρ_T/ρ_{RT} vs. T (heating rate of $\simeq 2$ K/min) for both Metglas 2605 SC and 2605. The resistivity varies linearly at higher temperatures and shows a quadratic behaviour at lower temperatures. The resistivity changes by about (2-3)% between 300 to 77 K. The temperature

Table 6.1
X-ray data of annealed Metglas 2605 SC

α - Fe		Fe ₂ B		Fe ₃ B	
dobs (A ^o)	135 ^d ştd (A ⁰)	dobs (A ^O)	135 ^d ,s td (A ^o)	d obs (A ^o)	d _{std} 135 (A°)
2.026	2.027	2.119	2.12	not present	2.090
1.430	1.433	2.011	2.01	not present	2.040
1.170	1.170	1.829	1.83	not present ,	2.034
		1.202	1.20		
		1.138	1.19		

coefficients of resistivity, $\alpha = (1/\rho_{RT}) \delta \rho_T / \delta T$ for 2605 SC and 2605 are $(1.20 \pm 0.05) \times 10^{-4} \, \text{K}^{-1}$ and $(1.65 \pm 0.05) \times 10^{-4} \, \text{K}^{-1}$, respectively. As stated earlier in Chapter II, the variation of ρ with temperature is governed by two factors :(1) The electron-phonon scattering which gives a positive α and(2) The decrease at higher temperatures in the height of the first peak of the structure factor S(k) vs. wave vector k graph which gives rise to a negative α . The latter is larger for



metalloids with valency 4 (for x = 20) (see e.g., ref. [98]). . When B (valency 3) is partially replaced by Si and C (valency 4 for both) the effective valency increases beyond 3 and so the negative contribution is more which makes the overall temperature coefficient of resistivity less positive in 2605 SC. The temperature coefficient of resistivity is large if the total resistivity is dominated by electron-phonon scattering. In metallic glasses scattering from structural disorder is the dominant mechanism and hence α is found to be much less than that of the crystalline alloys. Thus, the lower value of α for 2605 SC as compared to that of 2605 suggests more structural disorder in the former. Hence, partial replacement of B by Si and C makes 2605 SC comparatively more stable than 2605 as an amorphous alloy. The higher value of resistivity ρ (by ~ 6%) in 2605 SC also supports the above conclusion about their stability. The Debye temperature $\boldsymbol{\Theta}_{\!\!D}$, calculated from eqn. (2.11) for 2605 SC and 2605 are 470 and 390K, respectively. However, we observe that the linearity (down to 160 and 180K for 2605 SC and 2605, respectively, see Fig. 6.1) of $\rho_{\rm T}/\rho_{\rm RT}$ vs. T continues much below the Debye temperature in contradiction to eqn. (2.8).

Fig. 6.7 shows plots of magnetoresistance $\Delta \mathcal{F}/\mathcal{F}$ of Metglas 2605 SC against the external magnetic field H_{ext} for both longitudinal (\vec{J} || \vec{M}) and transverse (\vec{J} | \vec{M}) orientations at 300 and 77K. The behaviour at low fields is very similar

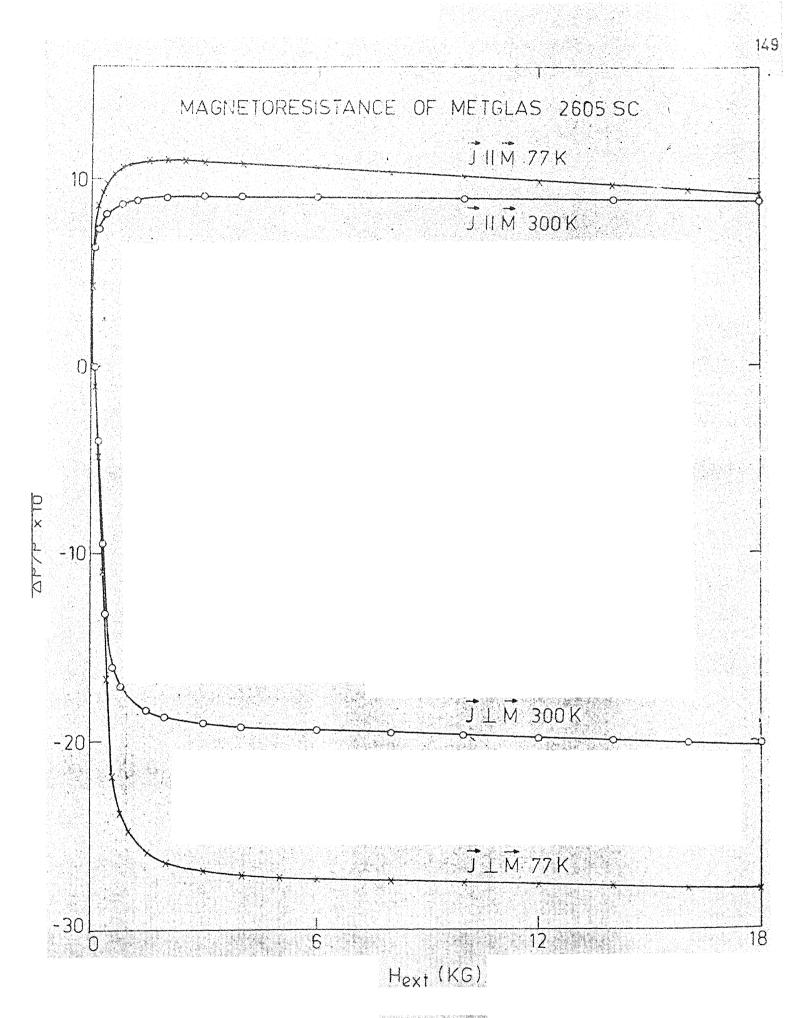


FIG. 6.7

to that of crystalline ferromagnets with domain structures. The FAR is 0.28 and 0.38% at 300 and 77 K, respectively, while for 2605 they are 0.38 and 0.54% at 300 and 77 K, respectively. These values are much smaller than those of their crystalline counterparts. The high field slopes are negative and are due to less electron-magnon scattering at higher fields. The Hall effect data of 2605 SC is shown in Fig. 6.8. $R_{\rm S}$ is here calculated in the usual manner. From the Hall resistivity ($\rho_{\rm H}$) data of Metglas 2605 SC we have calculated the extraordinary Hall constant $R_{\rm S}$ and the Hall conductivity $\gamma_{\rm H_S} = R_{\rm S} M_{\rm S}/\rho^2$ where $M_{\rm S}$ is the saturation magnetization (see Table 6.2).

In Table 6.2 we have compared the values of ρ , α , $\Delta \rho_{11S}/\rho$, $\Delta \rho_{1S}/\rho$, FAR, high-field slopes $[(1/\rho) \ \partial \rho/\partial H]_{11}$ and $[(1/\rho)\partial \rho/\partial H]_{11}$, M_s , R_s and γ_{H_s} for 2605 SC and 2605. One finds from this table that the magnetoresistance and the Hall effect do not show any qualitative difference in these two metallic glasses.

6.4 CONCLUSIONS

The present work could be summarized as follows:

i) The Curie temperature is little affected by the partial replacement of B by Si and C. However, the final equilibrium phases peresent in 2605 SC are Fe₂B and α -Fe while in 2605 they are Fe₃B and α -Fe.

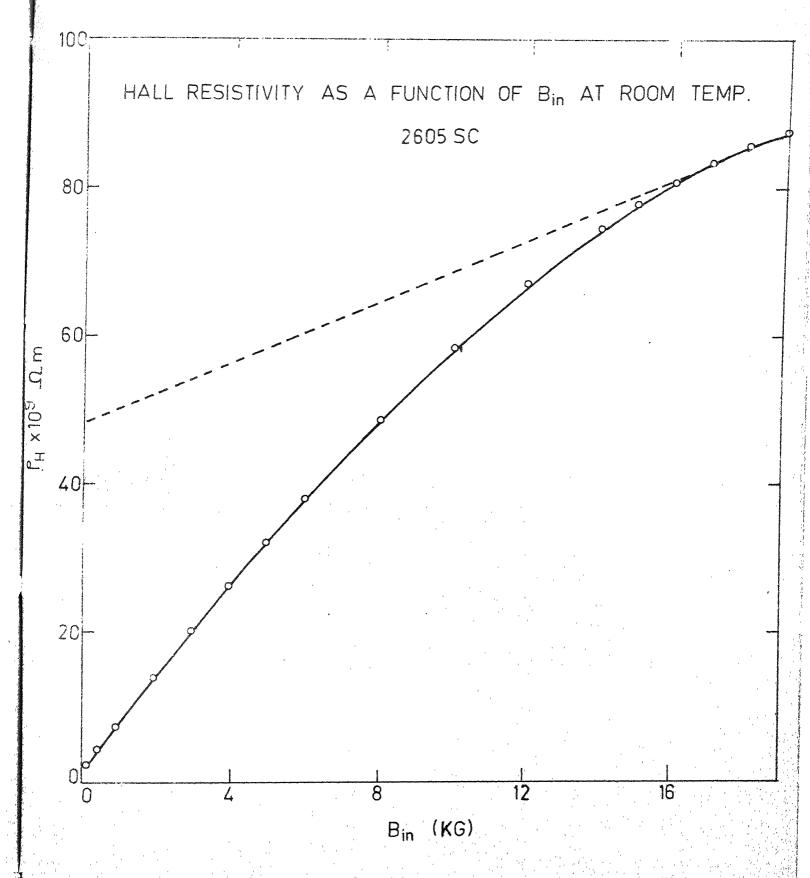


FIG. 6.8

Table 6.2

Comparison of transport properties of Metglas 2605 SC and 2605

Property	at T(K)	Metglas 2605 SC	Metglas 2605
ρ(μΩm)	300	1.25	1.18
$\alpha(10^{-4}K^{-1})$	-	1.20 <u>+</u> 0.05	1.65 <u>+</u> 0.05
⊖ _D (K)	-	470	390
$\frac{\Delta \rho_{11S}}{\rho}$ (10 ⁻⁴)	300 77	9 11	13 17
$\frac{\Delta \rho_{\perp S}}{\rho} (10^{-4})$	300 77	- 19 - 27	- 25 - 37
FAR(%)	300 77	0.28 0.38	0.38 0.54
$(\frac{1}{p}, \frac{\partial p}{\partial H})_{11}(10^{-8} \text{G}^{-1})$	300 77	-0.13 -1.00	-0.30 -1.00
$(\frac{1}{F} \frac{\partial P}{\partial H})_{\perp} (10^{-8} \text{G}^{-1})$	300 77	-0.75 -0.50	-0.50 -1.10
$R_s(10^{-8} \text{ m}^3/\text{c})$	300	2.90 <u>+</u> 0.3	5.5 ± 0.3
M _s (T)	3 0 0	1.61	1.56
$\gamma_{\rm H_S} (10^2 \Omega^{-1} \rm m^{-1})$	300	300	616

- ii) In 2605 SC, α -Fe and Fe₃B crystallize in two different steps while in 2605 it is a single step process. Differential thermal analysis also supports this fact by showing two peaks for 2605 SC and only one major peak in case of 2605.
- iii) The heat effect of the transformation of Fe₃B into α -Fe and Fe₂B is too small to be observed in DTA, but this transformation can be recognised through magnetization studies.
- iv) The partial replacement of B by Si and C enhances the crystallization temperature of 2605 SC and thereby increases its stability.
- v) A lower value of the temperature coefficient of resistivity and a higher value of the resistivity also confirm the fact that 2605 SC is more stable.
- vi) Magnetoresistance and Hall effect are not much affected by the partial replacement of B by Si and C.

Hence, it is concluded that the thermomagnetic properties are seriously affected by the replacement of B by Si and C while the transport properties have changed only quantitatively.

APPENDIX 1

ERROR CALCULATION IN $\Theta_{\rm D}$ OF ${\rm Fe_{80}B_{19}Si_1}$

$$\Theta_{\rm D} = \frac{\pi^2}{6} \frac{\alpha}{5}$$
 [eqn. (2.11)]

Hence, error in $\Theta_{\rm D}$ = error in α + error in S, where α is the slope of linear part of $\rho_{\rm T}/\rho_{\rm RT}$ vs T plot S is the slope of $\rho_{\rm T}/\rho_{\rm RT}$ vs T² plot.

It is clear that error in α will be the same whether the measurements are done between $77K \le T \le 300K$ or between $4.2K \le T \le 300K$. Only the accuracy in calculating S can be increased by making measurements down to 4.2K.

Error in S:

error in y axis of ρ_{T}/ρ_{RT} vs T^{2} plot =

$$\sqrt{\frac{[(0.5)^2+1^2+(1.5)^2+2^2+1^2]}{\sqrt{16}}} \text{ div} = 0.73 \text{ div}.$$

0.73 div in y axis = 0.000073.

Hence, uncertainty in y axis = $\frac{0.000073}{0.003600}$ = 2.03x10⁻² \approx 2% error in x axis of $\rho_{\rm T}/\rho_{\rm RT}$ vs T² plot =

$$\sqrt{\left[\frac{(0.5)^2 + (0.5)^2 + 1^2 + 2^2 + (2.5)^2 + (1.5)^2}{\sqrt{16}}\right]} = 0.9354 \text{ div}$$

 $0.9354 \text{ div on x axis} = 93.54 \text{K}^2$.

Hence, uncertainty in x axis = $\frac{93.54}{4742.91}$ = 1.97x10⁻² ~ 2 %

Therefore, error in S ~ 4% .

Error in α :

Error in y axis of ρ_T/ρ_{RT} vs T plot =

$$\sqrt{\left[\frac{1^2 + (0.5)^2 + 1^2 + (0.5)^2 + (0.5)^2 + 1^2}{\sqrt{20}}\right]} = 0.43 \text{ div} = 0.000043$$

Therefore, error in y axis = $\frac{.000043}{.016700}$ = 2.575x10⁻³ = 0.26%

Error in x axis =
$$\sqrt{(1)^2 + (0.5)^2 + (0.5)^2 + (0.5)^2 + (0.5)^2 + (1)^2}$$
 =

$$= 0.39 \text{ div} = 0.78K$$

Hence, error in x axis = $\frac{0.78}{109.5}$ = 7.12x10⁻³ \approx 0.7%

Therefore, error in $\alpha = 1$ %

Hence, error in $\theta_D = (4+1)\% = 5\%$

Hence, $\Theta_D = (330+16)K$ for $Fe_{80}B_{19}Si_1$.

APPENDIX - 2

CALCULATION FOR DEMAGNETIZING FIELD Hdemag

In a sample in the form of a rectangular plate with length = 2c, width = 2b and the thickness = 2a, the demagnetizing factor α is given by 121 :

When magnetic field H | | c,

$$\alpha = \frac{2}{\pi} \cot^{-1} \left[\frac{(a^2 + b^2 + c^2)^{1/2} c}{ab} \right]$$
.

When magnetic field H | b,

$$\alpha = \frac{2}{\pi} \cot^{-1} \left[\frac{(a^2 + b^2 + c^2)^{1/2}}{ac} \frac{b}{a} \right]$$
.

When magnetic field H | a,

$$\alpha = \frac{2}{\pi} \cot^{-1} \left[\frac{(a^2 + b^2 + c^2)^{1/2}}{bc} \right]$$
.

For a typical sample used for our transverse and longitudinal magnetoresistance measurements,

$$2c = 1.4 \text{ cm}$$

$$2b = 0.1 \text{ cm}$$

$$2a = 0.0025 \text{ cm}$$

For transverse magnetoresistance, H | b and therefore

$$\alpha = \frac{2}{\pi} \cot^{-1} \left[\frac{\{(0.7)^2(0.05)^2 + (0.00125)^2\}^{1/2} \times 0.05}{0.7 \times 0.00125} \right]$$

$$= \frac{2}{\pi} \cot^{-1} \left[40.102 \right]$$

$$= 1.588 \times 10^{-2}$$

Therefore,
$$H_{demag} = \alpha M_s = 1.588 \times 10^{-2} \times 16.1 [M_s = 16.1 kG]$$

= 0.256 kG
= 256 gauss

For longitudinal magnetoresistance H | | c and so,

$$\alpha = \frac{2}{\pi} \cot^{-1} \left[\frac{\{(0.7)^2 + (0.05)^2 + (0.00125)^2\}^{1/2} \times 0.7}{0.00125 \times 0.05} \right]$$

$$= 8.104 \times 10^{-5}$$

Therefore,
$$H_{demag} = \alpha M_s = 8.104 \times 10^{-5} \times 16.1 \text{ kG}$$

= $1.3 \times 10^{-3} \text{ kG}$
= 1.3 gauss

Hence, in longitudinal measurements, H_{demag} ~ 0.

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